

Study of Recent Technologies in computer Network

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Abstract

A network is any collection of independent computers that communicate with one another over a shared network medium. A computer network is a collection of two or more connected computers. When these computers are joined in a network, people can share files and peripherals such as modems, printers, tape backup drives, or CD-ROM drives. When networks at multiple locations are connected using services available from phone companies, people can send e-mail, share links to the global Internet, or conduct video conferences in real time with other remote users. When a network becomes open sourced it can be managed properly with online collaboration software. As companies rely on applications like electronic mail and database management for core business operations, computer networking becomes increasingly more important. However, in this day and age simply having internet is not enough, you need to be able to get high speeds that all companies from Verizon to Megapath should be able to provide. On the most fundamental level, a computer network is an interconnected collection of devices that enables you to store, retrieve, and share information. Commonly connected devices include personal computers (PCs), minicomputers, mainframe computers, terminals, workstations, thin clients, printers, fax machines, pagers, and various data-storage devices. Recently, other types of devices have become network connectable, including interactive televisions, videophones, handheld devices, and navigational and environmental control systems. Eventually, networked devices everywhere will provide two-way access to a vast array of resources on a global computer network through the largest network of all, the Internet. In today's business world a computer network is more than a collection of interconnected devices. For many businesses the computer network is the resource that enables them to gather, analyze, organize, and disseminate information that is essential to their profitability.

The rise of intranets and extranets—business networks based on Internet technology—is an indication of the critical importance of computer networking to businesses. Intranets, extranets, and the Internet will be treated in more detail in a later section. For now, it is enough to understand that most businesses have installed intranets to collect, manage, and disseminate information more quickly and easily than ever before. They established intranets simply to remain competitive; now, the momentum continues, and extending the company network to the Internet is the next technological transformation of the traditional business.

Introduction

This paper introduces the ISO-OSI layered architecture of Networks. According to the ISO standards, networks have been divided into 7 layers depending on the complexity of the functionality each of these layers provide. The detailed description of each of these layers is given in the notes below. We will first list the layers as defined by the standard in the increasing order of function complexity:

1. Physical Layer
2. Data Link Layer
3. Network Layer
4. Transport Layer
5. Session Layer
6. Presentation Layer
7. Application Layer

Physical Layer

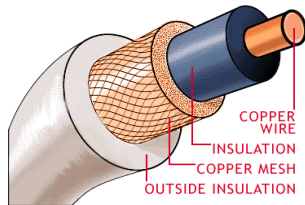
This layer is the lowest layer in the OSI model. It helps in the transmission of data between two machines that are communicating through a

physical medium, which can be optical fibres, copper wire or wireless etc. The following

are the main functions of the physical layer:

1. **Hardware Specification:** The details of the physical cables, network interface cards, wireless radios, etc are a part of this layer.

Coaxial Cable



Hybrid Cable



Wireless Card

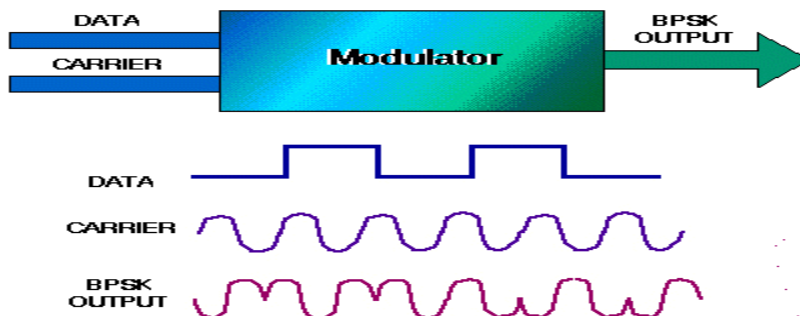


Network Card



2. **Encoding and Signalling:** How are the bits encoded in the medium is also decided by this layer. For example, on the copper wire medium, we can use different voltage levels for a certain time interval to represent '0' and '1'. We may use +5mV for 1sec to represent '1'

and -5mV for 1sec to represent '0'. All the issues of modulation is dealt with in this layer. eg, we may use Binary phase shift keying for the representation of '1' and '0' rather than using different voltage levels if we have to transfer in RF waves.



Binary Phase Shift Keying

3. **Data Transmission and Reception:** The transfer of each bit of data is the responsibility of this layer. This layer assures the transmission of each bit with a *high probability*. The transmission of the bits is not completely reliable as there is no error correction in this layer.
4. **Topology and Network Design:** The network design is the integral part of the physical layer. Which part of the network is the router going to be placed, where the switches will be used, where we will put the hubs, how many machines is each switch going to handle, what server is going to be placed where, and many such concerns are

to be taken care of by the physical layer. The various kinds of network topologies that we decide to use may be ring, bus, star or a hybrid of

these topologies depending on our requirements.

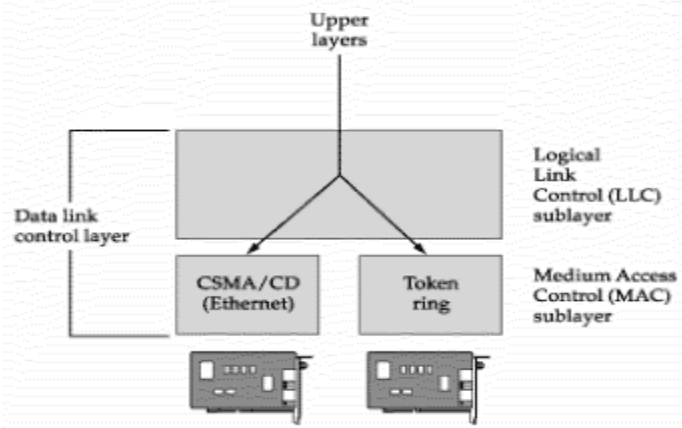


Figure 1-7 Commonly used network topologies

Data Link Layer

This layer provides reliable transmission of a packet by using the services of the physical layer which transmits bits over the medium in an unreliable fashion. This layer is concerned with :

1. Framing : Breaking input data into frames (typically a few hundred bytes) and caring about the frame boundaries and the size of each frame.
2. Acknowledgment : Sent by the receiving end to inform the source that the frame was received without any error.
3. Sequence Numbering : To acknowledge which frame was received.
4. Error Detection : The frames may be damaged, lost or duplicated leading to errors. The error control is on **link to link** basis.
5. Retransmission : The packet is retransmitted if the source fails to receive acknowledgment.
6. Flow Control : Necessary for a fast transmitter to keep pace with a slow receiver.



Data Link Layer

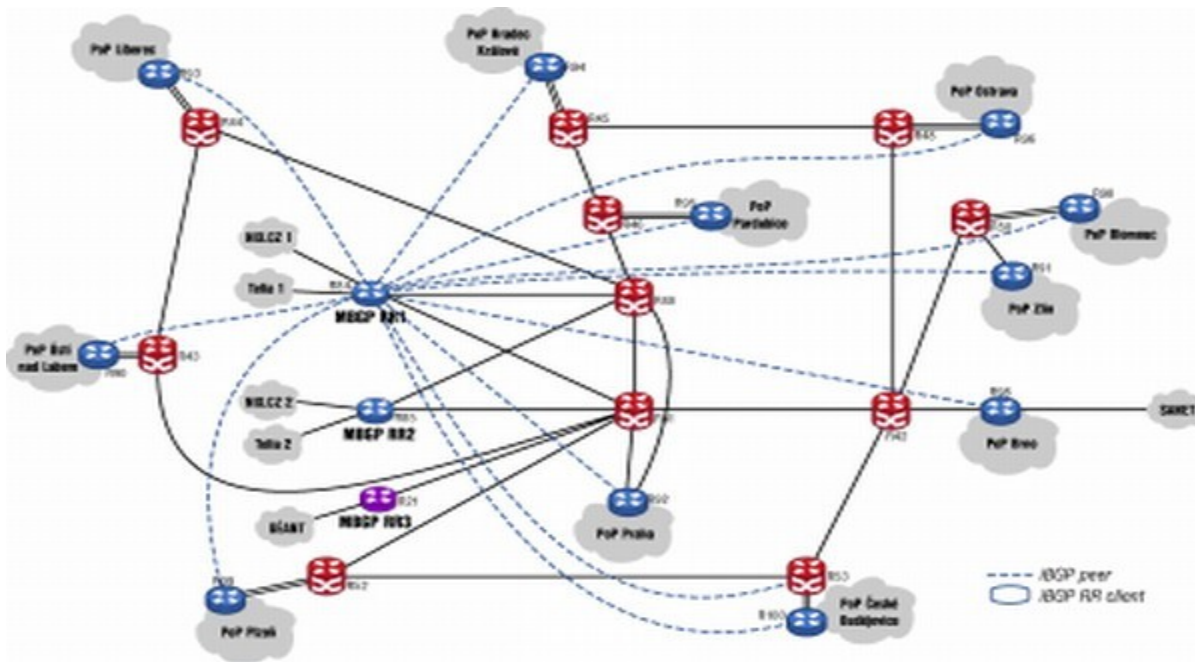
Network Layer

Its basic functions are routing and congestion control.

Routing: This deals with determining how packets will be routed (transferred) from source to destination. It can be of three types :

- Static : Routes are based on static tables that are "wired into" the network and are rarely changed.

- Dynamic : All packets of one application can follow different routes depending upon the topology of the network, the shortest path and the current network load.
- Semi-Dynamic : A route is chosen at the start of each conversation and then all the packets of the application follow the same route.



Routing

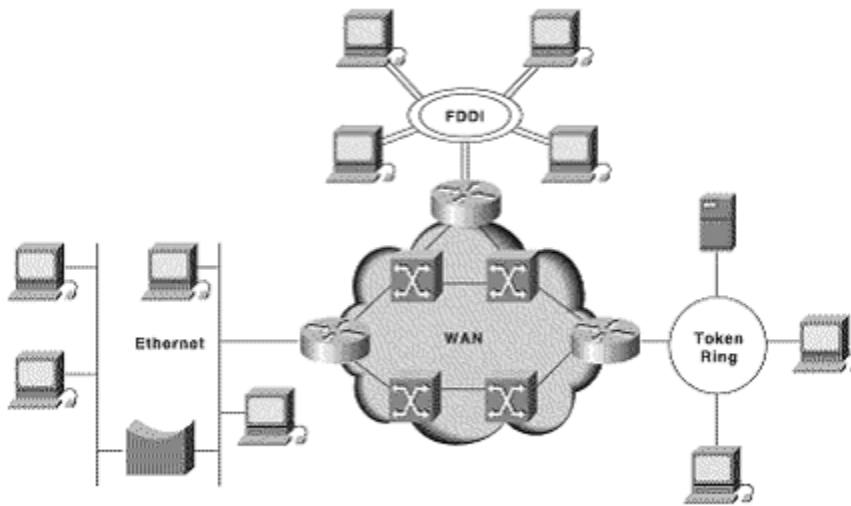
The services provided by the network can be of two types :

- **Connection less service:** Each packet of an application is treated as an independent entity. On each packet of the application the destination address is provided and the packet is routed.
- **Connection oriented service:** Here, first a connection is established and then all packets of the application follow the same route. To understand the above concept, we can also draw an analogy from the real life. Connection oriented service is modeled after the telephone system. All voice packets go on the same path after the connection is established till the connection is hung up. It acts like a tube ; the sender pushes the objects in at one end and the receiver takes them out in the same order at the other end. Connection less service is modeled after the postal system. Each letter carries the destination address and is routed independent of all the others. Here, it is possible that the letter sent first is delayed so that the second letter reaches the destination before the first letter.

Congestion Control: A router can be connected to 4-5 networks. If all the networks send packet

at the same time with maximum rate possible then the router may not be able to handle all the packets and may drop some/all packets. In this context the dropping of the packets should be minimized and the source whose packet was dropped should be informed. The control of such congestion is also a function of the network layer. Other issues related with this layer are transmitting time, delays, jittering.

Internetworking: Internetworks are multiple networks that are connected in such a way that they act as one large network, connecting multiple office or department networks. Internetworks are connected by networking hardware such as routers, switches, and bridges. Internetworking is a solution born of three networking problems: isolated LANs, duplication of resources, and the lack of a centralized network management system. With connected LANs, companies no longer have to duplicate programs or resources on each network. This in turn gives way to managing the network from one central location instead of trying to manage each separate LAN. We should be able to transmit any packet from one network to any other network even if they follow different protocols or use different addressing modes.



Inter-Networking

Network Layer **does not** guarantee that the packet will reach its intended destination. There are no reliability guarantees.

Transport Layer

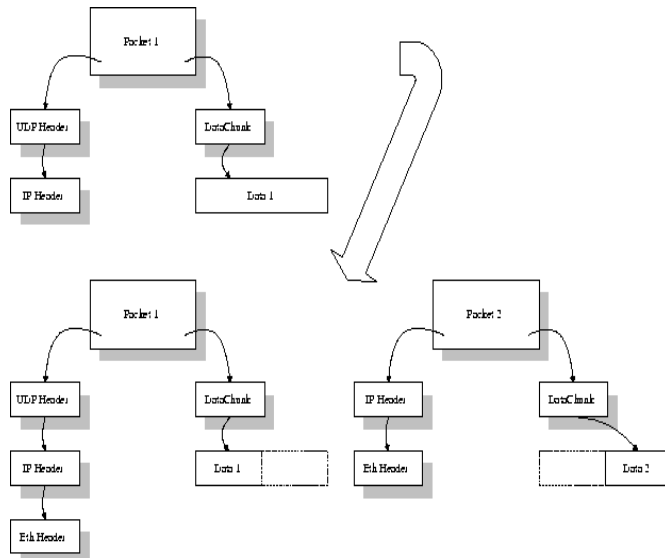
Its functions are :

- **Multiplexing / Demultiplexing** : Normally the transport layer will create distinct network connection for each transport connection required by the session layer. The transport layer may either create multiple network connections (to improve throughput) or it may multiplex several transport connections onto the same network

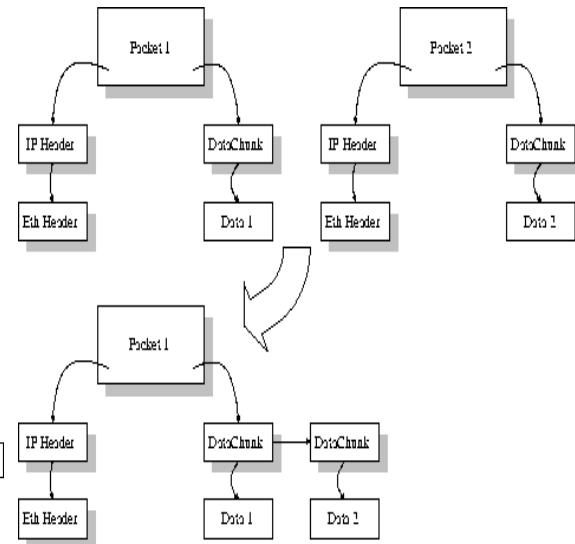
connection (because creating and maintaining networks may be expensive). In the latter case, demultiplexing will be required at the receiving end. A point to note here is that communication is always carried out between two processes and not between two machines. This is also known as process-to-process communication.

- **Fragmentation and Re-assembly** : The data accepted by the transport layer from the session layer is split up into smaller units (fragmentation) if needed and then passed to the network layer. Correspondingly, the data provided by the network layer to the transport layer on the receiving side is re-assembled.

Fragmentation



Reassembly



- **Types of service :** The transport layer also decides the type of service that should be provided to the session layer. The service may be perfectly reliable, or may be reliable within certain tolerances or may not be reliable at all. The message may or may not be received in the order in which it was sent. The decision regarding the type of service to be provided is taken at the time when the connection is established.
- **Error Control :** If reliable service is provided then error detection and error recovery operations are also performed. It provides error control mechanism on **end to end** basis.
- **Flow Control :** A fast host cannot keep pace with a slow one. Hence, this is a mechanism to regulate the flow of information.
- **Connection Establishment / Release :** The transport layer also establishes and releases the connection across the network. This requires some sort of naming mechanism so that a process on one machine can indicate with whom it wants to communicate.
- **Session Layer**

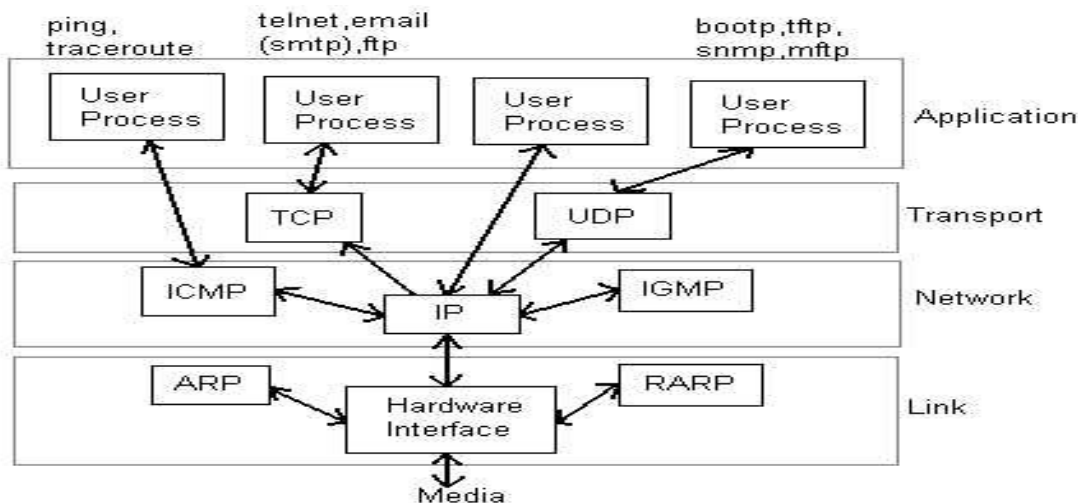
- It deals with the concept of **Sessions** i.e. when a user logs in to a remote server he should be **authenticated** before getting access to the files and application programs. Another job of session layer is to establish and maintain sessions. If during the transfer of data between two machines the session breaks down, it is the session layer which re-establishes the connection. It also ensures that the data transfer starts from where it breaks keeping it transparent to the end user. e.g. In case of a session with a database server, this layer introduces **check points** at various places so that in case the connection is broken and reestablished, the transaction running on the database is not lost even if the user has not committed. This activity is called **Synchronization**. Another function of this layer is **Dialogue Control** which determines whose turn is it to speak in a session. It is useful in video conferencing.
- **Presentation Layer**
- This layer is concerned with the syntax and semantics of the information transmitted. In order to make it possible for computers with

different data representations to communicate data structures to be exchanged can be defined in abstract way alongwith standard encoding. It also manages these abstract data structres and allows higher level of data structres to be defined an exchange. It encodes the data in standard agreed way(network format). Suppose there are two machines A and B one follows 'Big Endian' and other 'Little Endian' for data representation. This layer ensures that the data transmitted by one gets converted in the form compatibale to othe machine. This layer is concerned with the syntax and semantics of the information transmitted.In order to make it possible for computers with different data representations to communicate data structures to be exchanged canbe defined in abstract way alongwith standard encoding. It also manages these abstract data structres and allows higher level of data structres to be defined an exchange. Other functions include compression, encryption etc.

- **Application Layer**
- The seventh layer contains the application protocols with which the user gains access to the

network. The choice of which specific protocols and their associated functions are to be used at the application level is up to the individual user. Thus the boundary between the presentation layer and the application layer represents a separation of the protocols imposed by the network designers from those being selected and implemented by the network users.For example commonly used protocols are HTTP(for web browsing), FTP(for file transfer) etc.

- **Network Layers as in Practice**
- In most of the networks today, we do not follow the OSI model of seven layers. What is actually implemented is as follows. The functionality of Application layer and Presentation layer is merged into one and is called as the Application Layer. Functionalities of Session Layer is not implemented in most networks today. Also, the Data Link layer is split theoretically into **MAC (Medium Access Control) Layer** and **LLC (Link Layer Control)**. But again in practice, the LLC layer is not implemented by most networks. So as of today, the network architecture is of 5 layers only.



Network Layers in Internet Today

- **Some Related Links on OSI Model and TCP Model**

Physical layer is concerned with transmitting raw bits over a communication channel. The

design issues have to do with making sure that when one side sends a 1 bit, it is received by the other side as 1 bit and not as 0 bit. In physical layer we deal with the communication medium used for transmission.

Types of Medium

Medium can be classified into 2 categories.

1. **Guided Media** : Guided media means that signals are guided by the presence of physical media i.e. signals are under control and remain in the physical wire. For eg. copper wire.
2. **Unguided Media** : Unguided Media means that there is no physical path for the signal to propagate. Unguided media are essentially electro-magnetic waves. There is no control on flow of signal. For eg. radio waves.

Communication Links

In a network nodes are connected through links. The communication through links can be classified as

1. **Simplex** : Communication can take place only in one direction. eg. T.V broadcasting.
2. **Half-duplex** : Communication can take place in one direction at a time. Suppose node A and B are connected then half-duplex communication means that at a time data can flow from A to B or from B to A but not simultaneously. eg. two persons talking to each other such that when one speaks the other listens and vice versa.
3. **Full-duplex** : Communication can take place simultaneously in both directions. eg. A discussion in a group without discipline.

Links can be further classified as

1. **Point to Point** : In this communication only two nodes are connected to each other. When a node sends a packet then it can be received only by the node on the other side and none else.
2. **Multipoint** : It is a kind of sharing communication, in which signal can be received by all nodes. This is also called broadcast.

Generally two kinds of problems are associated in transmission of signals.

1. **Attenuation** : When a signal transmits in a network then the quality of signal degrades as the signal travels longer distances in the wire. This is called attenuation. To improve quality of signal amplifiers are used at regular distances.
2. **Noise** : In a communication channel many signals transmit simultaneously, certain random signals are also present in the medium. Due to interference of these signals our signal gets disrupted a bit.

Bandwidth

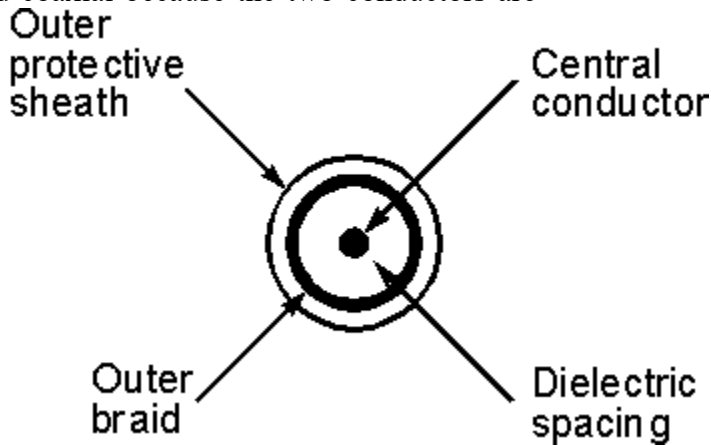
Bandwidth simply means how many bits can be transmitted per second in the communication channel. In technical terms it indicates the width of frequency spectrum.

Transmission Media

Guided Transmission Media
In Guided transmission media generally two kinds of materials are used.

1. Copper
 - o Coaxial Cable
 - o Twisted Pair
2. Optical Fiber

1. **Coaxial Cable:** Coaxial cable consists of an inner conductor and an outer conductor which are separated by an insulator. The inner conductor is usually copper. The outer conductor is covered by a plastic jacket. It is named coaxial because the two conductors are



2. **Twisted Pair:** A Twisted pair consists of two insulated copper wires, typically 1mm thick. The wires are twisted together in a helical form the purpose of twisting is to reduce cross

talk interference between several pairs. Twisted Pair is much cheaper than coaxial cable but it is susceptible to noise and electromagnetic interference and attenuation is large.

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Twisted Pair can be further classified in two categories:

Unshielded twisted pair: In this no insulation is provided, hence they are susceptible to interference.

Shielded twisted pair: In this a protective thick insulation is provided but shielded twisted pair is expensive and not commonly used.

The most common application of twisted pair is the telephone system. Nearly all telephones are connected to the telephone company office by a twisted pair. Twisted pair can run several kilometers without amplification, but for longer distances repeaters are needed. Twisted pairs can be used for both analog and digital transmission. The bandwidth depends on the

thickness of wire and the distance travelled. Twisted pairs are generally limited in distance, bandwidth and data rate.

3. **Optical Fiber:** In optical fiber light is used to send data. In general terms presence of light is taken as bit 1 and its absence as bit 0. Optical fiber consists of inner core of either glass or plastic. Core is surrounded by cladding of the same material but of different refractive index. This cladding is surrounded by a plastic jacket which prevents optical fiber from electromagnetic interference and harsh environments. It uses the principle of total internal reflection to transfer data over optical fibers. Optical fiber is much better in bandwidth as compared to copper wire, since there is hardly any attenuation or electromagnetic interference in optical wires. Hence there is less requirement to improve quality of signal, in long distance transmission. Disadvantage of optical fiber is that end points are fairly expensive. (eg. switches)

Differences between different kinds of optical fibers:

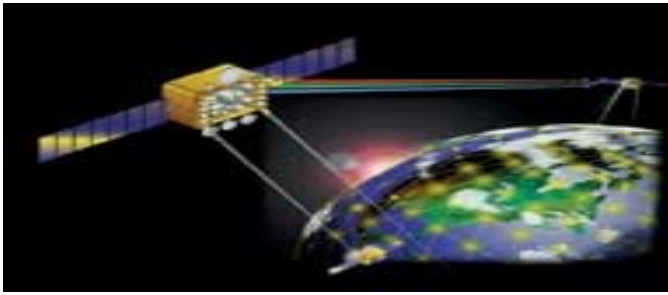
1. Depending on material
 - Made of glass
 - Made of plastic.
2. Depending on radius
 - Thin optical fiber
 - Thick optical fiber
3. Depending on light source
 - LED (for low bandwidth)
 - Injection laser diode (for high bandwidth)

Wireless Transmission

1. **Radio:** Radio is a general term that is used for any kind of frequency. But higher frequencies are usually termed as microwave and the lower frequency band comes under radio frequency. There are many applications of radio. For eg.

cordless keyboard, wireless LAN, wireless ethernet. but it is limited in range to only a few hundred meters. Depending on frequency radio offers different bandwidths.

2. **Terrestrial microwave:** In terrestrial microwave two antennas are used for communication. A focused beam emerges from an antenna and is received by the other antenna, provided that antennas should be facing each other with no obstacle in between. For this reason antennas are situated on high towers. Due to curvature of earth terrestrial microwave can be used for long distance communication with high bandwidth. Telecom department is also using this for long distance communication. An advantage of wireless communication is that it is not required to lay down wires in the city hence no permissions are required.
3. **Satellite communication:** Satellite acts as a switch in sky. On earth VSAT (Very Small Aperture Terminal) are used to transmit and receive data from satellite. Generally one station on earth transmits signal to satellite and it is received by many stations on earth. Satellite communication is generally used in those places where it is very difficult to obtain line of sight i.e. in highly irregular terrestrial regions. In terms of noise wireless media is not as good as the wired media. There are frequency bands in wireless communication and two stations should not be allowed to transmit simultaneously in a frequency band. The most promising advantage of satellite is broadcasting. If satellites are used for point to point communication then they are expensive as compared to wired media.

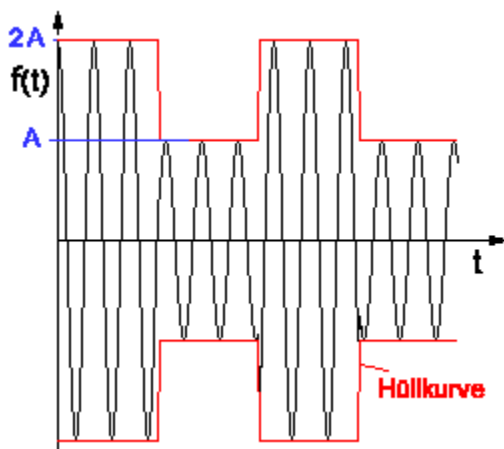


Data Encoding

Digital data to analog signals

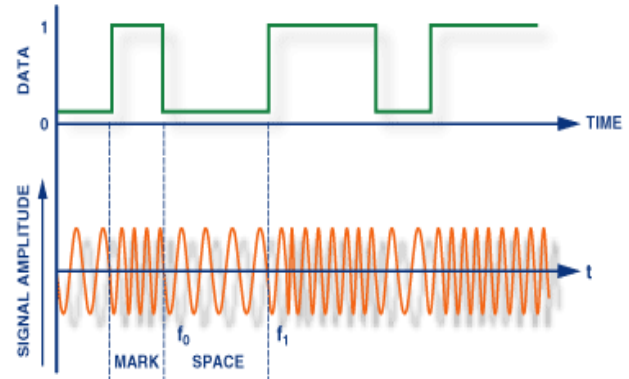
A modem (modulator-demodulator) converts digital data to analog signal. There are 3 ways to modulate a digital signal on an analog carrier signal.

1. **Amplitude shift keying (ASK):** is a form of modulation which represents digital data as variations in the amplitude of a carrier wave. Two different amplitudes of carrier frequency represent '0', '1'.

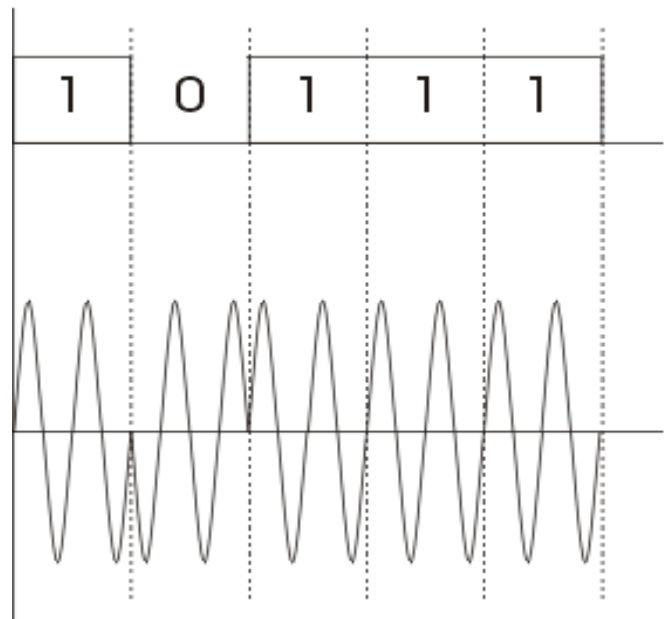


2. **Frequency shift keying (FSK):** In Frequency Shift Keying, the change in frequency define

different digits. Two different frequencies near carrier frequency represent '0', '1'.



3. **Phase shift keying (PSK):** The phase of the carrier is discretely varied in relation either to a reference phase or to the phase of the immediately preceding signal element, in accordance with data being transmitted. Phase of carrier signal is shifted to represent '0', '1'.

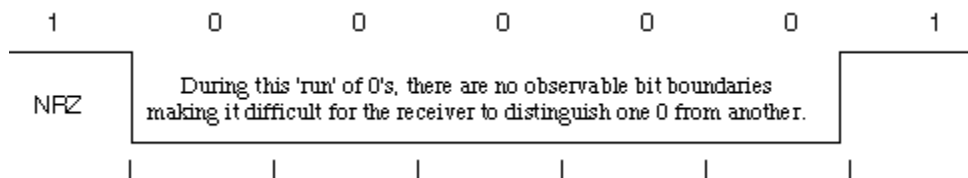


Digital data to digital signals

A digital signal is sequence of discrete , discontinuous voltage pulses. Each pulses a signal element. Encoding scheme is an important factor in how successfully the receiver interprets the incoming signal.

Encoding Techniques

Following are several ways to map data bits to signal elements.



The two variations are as follows:

1. **NRZ-Level:** In NRZ-L encoding, the polarity of the signal changes only when the incoming signal changes from a 1 to a 0 or from a 0 to a 1. NRZ-L method looks just like the NRZ method, except for the first input one data bit. This is because NRZ does not consider the first data bit to be a polarity change, where NRZ-L does.
2. **NRZ-Inverted:** Transition at the beginning of bit interval = bit 1 and No Transition at beginning of bit interval = bit 0 or viceversa. This technique is known as differential encoding.

NRZ-I has an advantage over NRZ-L. Consider the situation when two data wires are wrongly connected in each other's place. In NRZ-L all bit sequences will get reversed (B'coz voltage levels get swapped). Whereas in NRZ-I since bits are recognized by transition the bits will be correctly interpreted. A disadvantage in NRZ codes is that a string of 0's or 1's will prevent synchronization of transmitter clock with

- **Non return to zero(NRZ)** NRZ codes share the property that voltage level is constant during a bit interval. High level voltage = bit 1 and Low level voltage = bit 0. A problem arises when there is a long sequence of 0s or 1s and the volatage level is maintained at the same value for a long time. This creates a problem on the recieving end because now, the clock synchronization is lost due to lack of any transitions and hence, it is difficult to determine the exact number of 0s or 1s in this sequence.

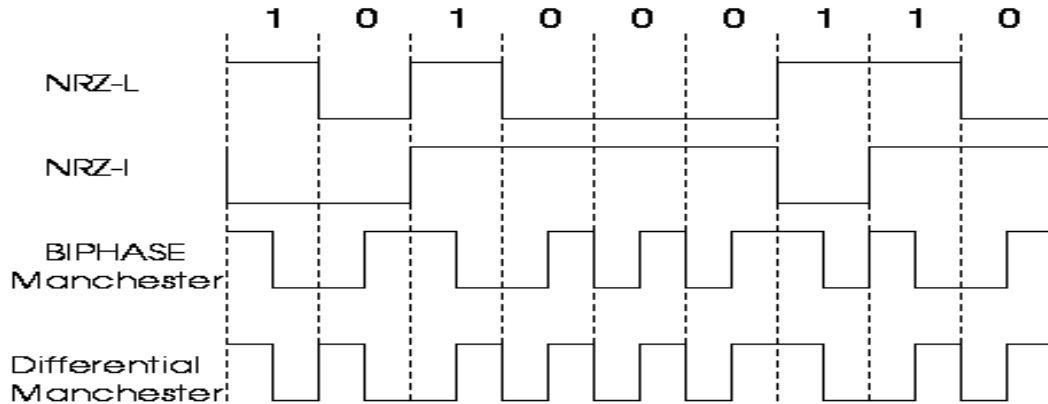
receiver clock and a separate clock line need to be provided.

- **Biphase encoding:** It has following characteristics:
 1. Modulation rate twice that of NRZ and bandwidth correspondingly greater. (Modulation is the rate at which signal level is changed).
 2. Because there is predictable transition during each bit time, the receiver can synchronize on that transition i.e. clock is extracted from the signal itself.
 3. Since there can be transition at the beginning as well as in the middle of the bit interval the clock operates at twice the data transfer rate.

Types of Encoding -->

- **Biphase-manchester:** Transition from high to low in middle of interval = 1 and Transition from low to high in middle of interval = 0

- **Differential-manchester:** Always a transition in middle of interval. No transition at beginning of interval=1 and Transition at beginning of interval = 0



○ **4B/5B Encoding:** In Manchester encoding scheme, there is a transition after every bit. It means that we must have clocks with double the speed to send same amount of data as in NRZ encodings. In other words, we may say that only 50% of the data is sent. This performance factor can be significantly improved if we use a better encoding scheme. This scheme may have a transition after fixed number of bits instead of every other bit. Like if we have a transition after every four bits, then we will be sending 80% data of actual capacity. This is a significant improvement in the performance.

This scheme is known as **4B/5B**. So here we convert 4-bits to 5-bits, ensuring at least one transition in them. The basic idea here is that 5-bit code selected must have :

- one leading 0
- no more than two trailing 0s

Thus it is ensured that we can never have more than three consecutive 0s. Now these 5-bit codes are transmitted using NRZI coding thus problem of consecutive 1s is solved.

The exact transformation is as follows :

4-bit Data	5-bit code	4-bit Data	5-bit code
0000	11110	1000	10010
0001	01001	1001	10011
0010	10100	1010	10110
0011	10101	1011	10111
0100	01010	1100	11010
0101	01011	1101	11011
0110	01110	1110	11100
0111	01111	1111	11101

Of the remaining 16 codes, 7 are invalid and others are used to send some control information like line idle(11111), line dead(00000), Halt(00100) etc.

There are other variants for this scheme viz. 5B/6B, 8B/10B etc. These have self suggesting names.

- **8B/6T Encoding:** In the above schemes, we have used two/three voltage levels for a signal. But we may altogether use more than three voltage levels so that more than one-bit could be send over a single signal. Like if we use six voltage levels and we use 8-bits then the scheme is called **8B/6T**. Clearly here we have 729(3^6) combinations for signal and 256(2^8) combinations for bits.

Bipolar AIM: Here we have 3 voltage levels: middle,upper,lower

- Representation 1: Middle level =0 Upper,Lower level =1 such that successive 1's will be represented alternately on upper and lower levels.
- Representation 2 (pseudoternary): Middle level =1 Upper,Lower level=0

Analog data to digital signal:

The process is called digitization. Sampling frequency must be at least twice that of highest frequency present in the the signal so that it may be fairly regenerated. Quantization - Max. and Min values of amplitude in the sample are noted. Depending on number of bits (say n) we use we divide the interval (min,max) into 2^n number of levels. The amplitude is then approximated to the nearest level by a 'n' bit integer. The digital signal thus consists of blocks of n bits.On reception the process is reversed to produce analog signal. But a lot of

data can be lost if fewer bits are used or sampling frequency not so high.

- **Pulse code modulation(PCM):** Here intervals are equally spaced. 8 bit PCB uses 256 different levels of amplitude. In non-linear encoding levels may be unequally spaced.
- **Delta Modulation(DM):** Since successive samples do not differ very much we send the differences between previous and present sample. It requires fewer bits than in PCM.

Digital Data Communication Techniques:

For two devices linked by a transmission medium to exchange data ,a high degree of co-operation is required. Typically data is transmitted one bit at a time. The timing (rate, duration,spacing) of these bits must be same for transmitter and receiver. There are two options for transmission of bits.

1. **Parallel** All bits of a byte are transferred simultaneously on separate parallel wires. Synchronization between multiple bits is required which becomes difficult over large distance. Gives large band width but expensive. Practical only for devices close to each other.
2. **Serial** Bits transferred serially one after other.Gives less bandwidth but cheaper. Suitable for transmission over long distances.

Transmission Techniques:

1. **Asynchronous:** Small blocks of bits(generally bytes) are sent at a time without any time relation between consecutive bytes .when no transmission occurs a default state is maintained corresponding to bit 1. Due to arbitrary delay between consecutive bytes,the time occurrences of the clock pulses at the receiving end need to

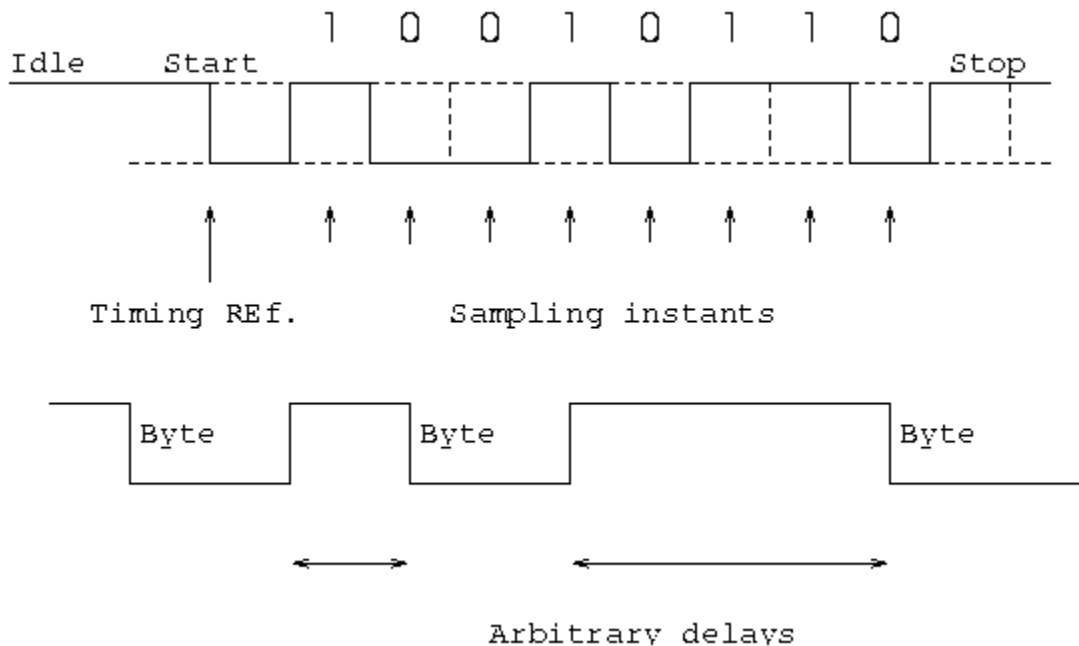
be synchronized for each byte. This is achieved by providing 2 extra bits start and stop.

Start bit: It is prefixed to each byte and equals 0. Thus it ensures a transition from 1 to 0 at onset of transmission of byte. The leading edge of start bit is used as a reference for generating clock pulses at required sampling instants. Thus each onset of a byte results in resynchronization of receiver clock.

Stop bit: To ensure that transition from 1 to 0 is always present at beginning of a byte it is necessary that default state be 1. But there may be two bytes one immediately following the other and if last bit of first byte is 0, transition

from 1 to 0 will not occur. Therefore a stop bit is suffixed to each byte equaling 1. Its duration is usually 1, 1.5, 2 bits.

Asynchronous transmission is simple and cheap but requires an overhead of 3 bits i.e. for 7 bit code 2 (start, stop bits)+1 parity bit implying 30% overhead. However % can be reduced by sending larger blocks of data but then timing errors between receiver and sender can not be tolerated beyond $[50/\text{no. of bits in block}] \%$ (assuming sampling is done at middle of bit interval). It will not only result in incorrect sampling but also misaligned bit count i.e. a data bit can be mistaken for stop bit if receiver's clock is faster.



2. **Synchronous** - Larger blocks of bits are successfully transmitted. Blocks of data are either treated as sequence of bits or bytes. To prevent timing drift clocks at two ends need to be synchronized. This can be done in two ways:

1. Provide a separate clock line between receiver and transmitter. OR

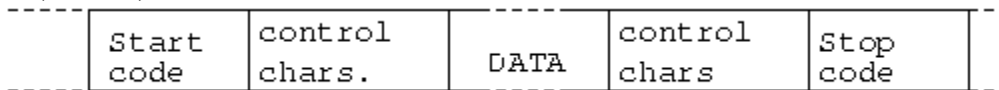
2. Clocking information is embedded in data signal i.e. biphase coding for digital signals.

Still another level of synchronization is required so that receiver determines beginning or end of block of data. Hence each block begins with a start code and ends with a stop code. These are

in general same known as flag that is unique sequence of fixed no. of bits. In addition some control characters encompass data within these flags. **Data+control information** is called a frame. Since any arbitrary bit pattern can be transmitted there is no assurance that bit pattern for flag will not appear inside the frame thus destroying frame level synchronization. So to avoid this we use bit stuffing

always insert an extra 0 bit after each occurrence of five 1's (except for flags). After detecting a starting flag the receiver monitors the bit stream. If pattern of five 1's appear, the sixth is examined and if it is 0 it is deleted else if it is 1 and next is 0 the combination is accepted as a flag. Similarly byte stuffing is used for byte oriented transmission. Here we use an escape sequence to prefix a byte similar to flag and 2 escape sequences if byte is itself a escape sequence.

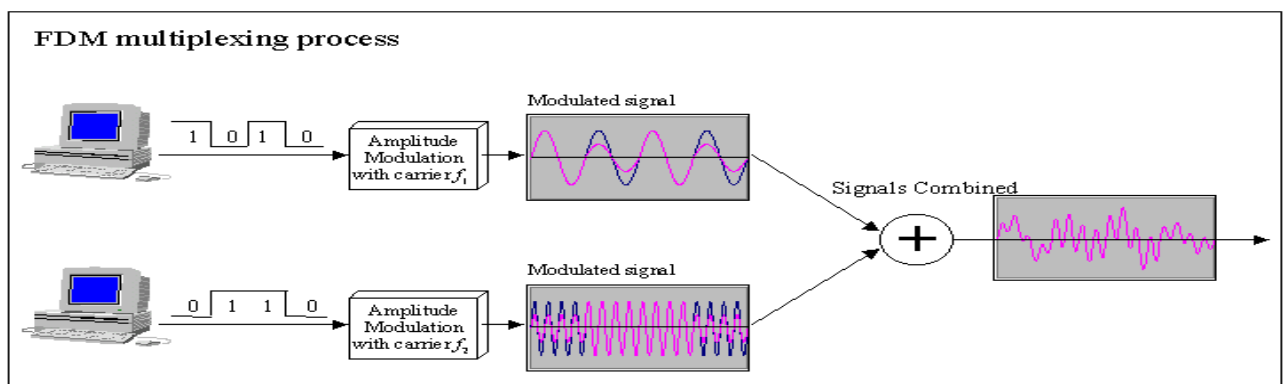
Bit Stuffing: Suppose our flag bits are 01111110 (six 1's). So the transmitter will



Multiplexing

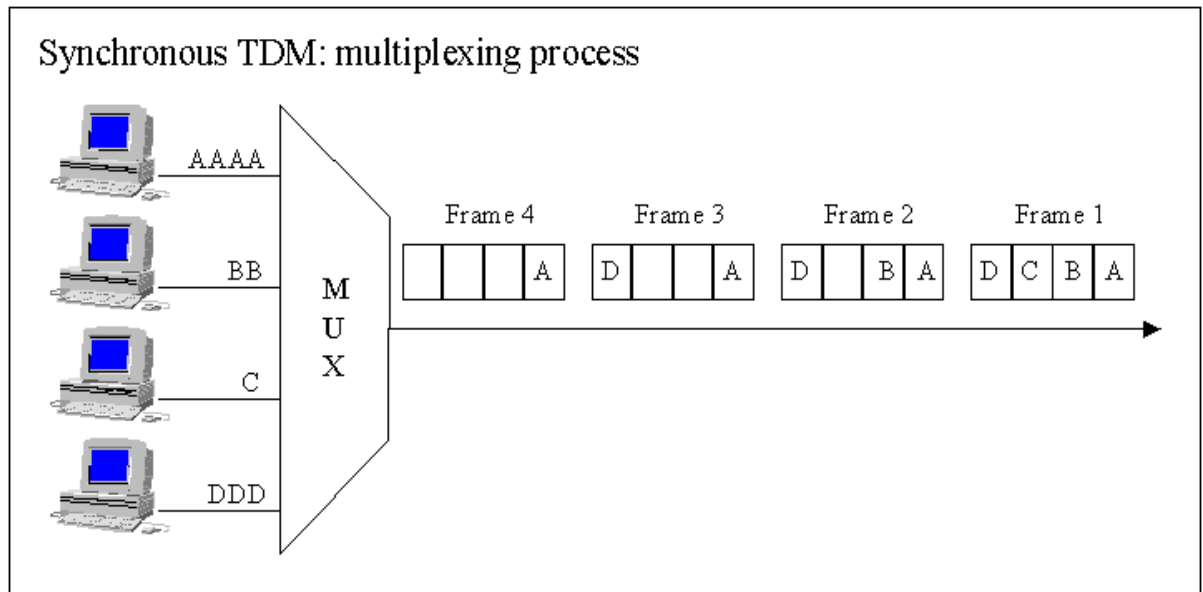
When two communicating nodes are connected through a media, it generally happens that bandwidth of media is several times greater than that of the communicating nodes. Transfer of a single signal at a time is both slow and expensive. The whole capacity of the link is not being utilized in this case. This link can be further exploited by sending several signals combined into one. This combining of signals into one is called multiplexing.

1. **Frequency Division Multiplexing (FDM):** This is possible in the case where transmission media has a bandwidth than the required bandwidth of signals to be transmitted. A number of signals can be transmitted at the same time. Each source is allotted a frequency range in which it can transfer its signals, and a suitable frequency gap is given between two adjacent signals to avoid overlapping. This type of multiplexing is commonly seen in the cable TV networks.

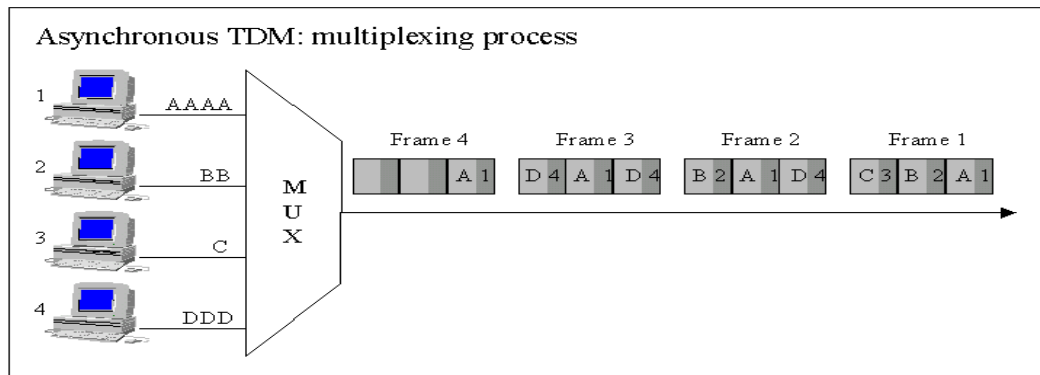


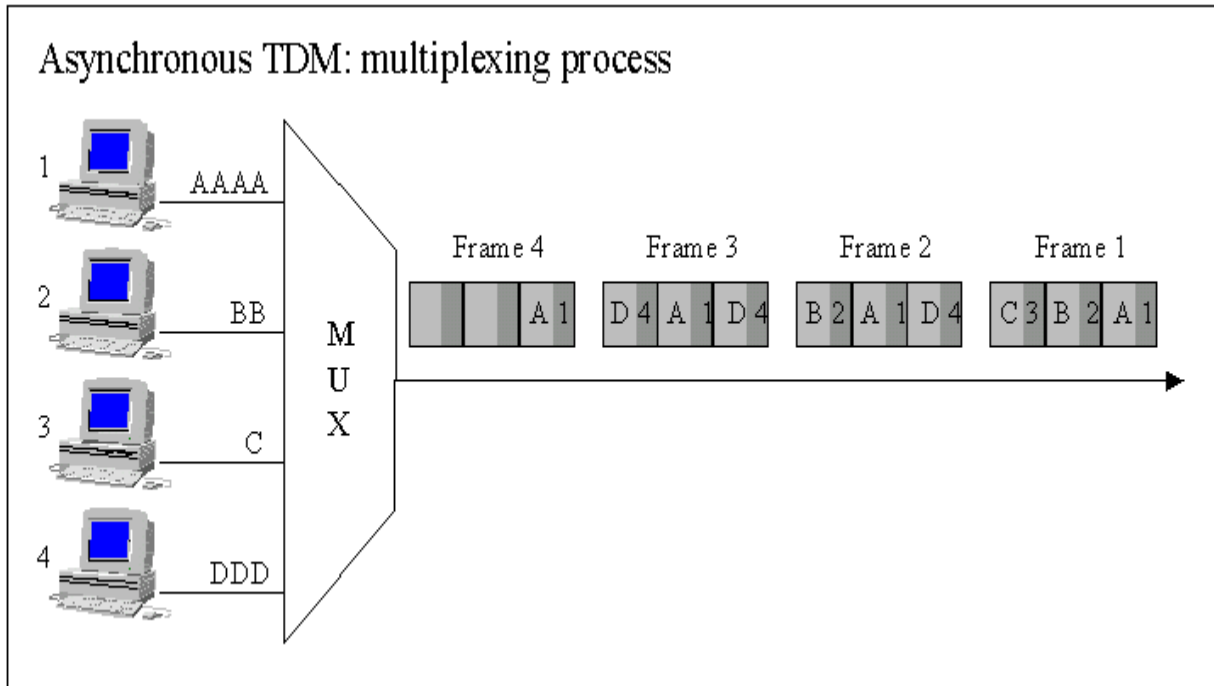
2. Time Division Multiplexing (TDM): This is possible when data transmission rate of the media is much higher than that of the data rate of the source. Multiple signals can be transmitted if each signal is allowed to be transmitted for a definite amount of time. These time slots are so small that all transmissions appear to be in parallel.

1. Synchronous TDM: Time slots are preassigned and are fixed. Each source is given its time slot at every turn due to it. This turn may be once per cycle, or several turns per cycle, if it has a high data transfer rate, or may be once in a no. of cycles if it is slow. This slot is given even if the source is not ready with data. So this slot is transmitted empty.



2. Asynchronous TDM: In this method, slots are not fixed. They are allotted dynamically depending on speed of sources, and whether they are ready for transmission.

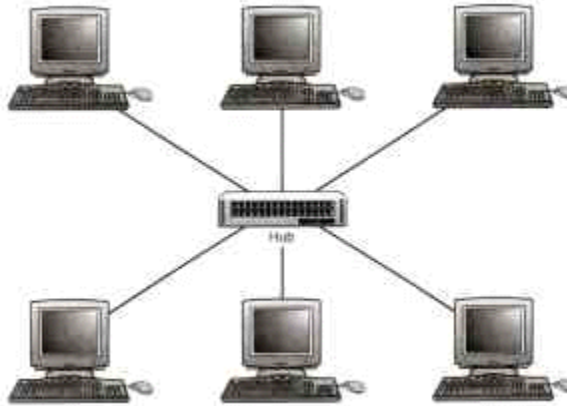




Network Topologies

A network topology is the basic design of a computer network. It is very much like a map of a road. It details how key network components such as nodes and links are interconnected. A network's topology is comparable to the blueprints of a new home in which components such as the electrical system, heating and air conditioning system, and plumbing are integrated into the overall design. Taken from the Greek work "Topos" meaning "Place," Topology, in relation to networking, describes the configuration of the network; including the location of the workstations and wiring connections. Basically it provides a definition of the components of a Local Area Network (LAN). A topology, which is a pattern of interconnections among nodes, influences a network's cost and performance. There are three primary types of network topologies which refer to the physical and logical layout of the Network cabling. They are:

1. **Star Topology:** All devices connected with a Star setup communicate through a central Hub by cable segments. Signals are transmitted and received through the Hub. It is the simplest and the oldest and all the telephone switches are based on this. In a star topology, each network device has a home run of cabling back to a network hub, giving each device a separate connection to the network. So, there can be multiple connections in parallel.



Advantages

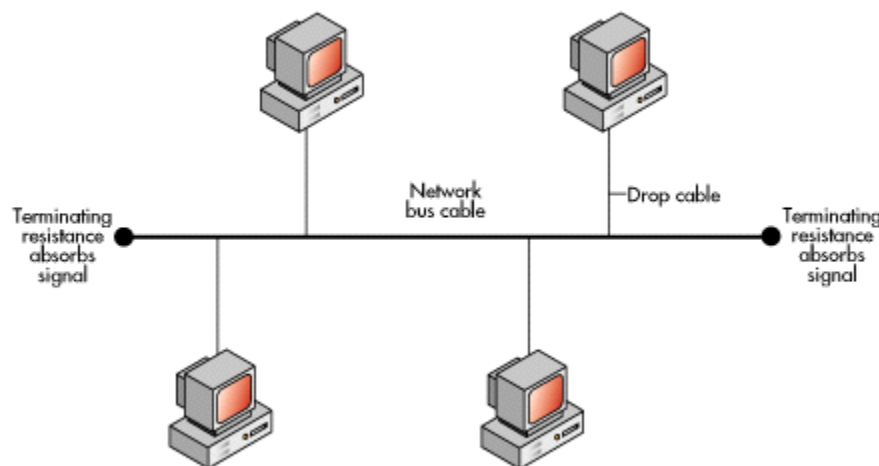
- Network administration and error detection is easier because problem is isolated to central node
- Networks runs even if one host fails
- Expansion becomes easier and scalability of the network increases
- More suited for larger networks

Disadvantages

- Broadcasting and multicasting is not easy because some extra functionality needs to be provided to the central hub

- If the central node fails, the whole network goes down; thus making the switch some kind of a bottleneck
- Installation costs are high because each node needs to be connected to the central switch

2. **Bus Topology:** The simplest and one of the most common of all topologies, Bus consists of a single cable, called a Backbone, that connects all workstations on the network using a single line. All transmissions must pass through each of the connected devices to complete the desired request. Each workstation has its own individual signal that identifies it and allows for the requested data to be returned to the correct originator. In the Bus Network, messages are sent in both directions from a single point and are read by the node (computer or peripheral on the network) identified by the code with the message. Most Local Area Networks (LANs) are Bus Networks because the network will continue to function even if one computer is down. This topology works equally well for either peer to peer or client server.



The purpose of the terminators at either end of the network is to stop the signal being reflected back.

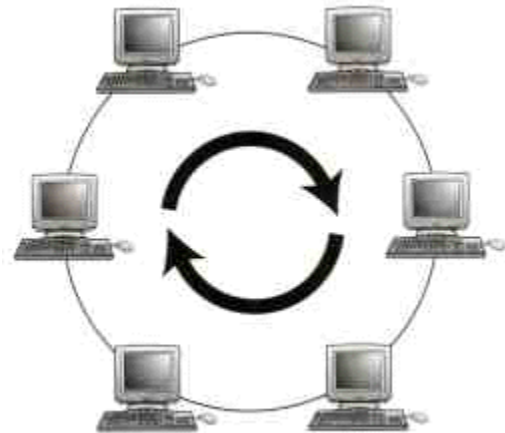
Advantages

- Broadcasting and multicasting is much simpler
- Network is redundant in the sense that failure of one node doesn't effect the network. The other part may still function properly
- Least expensive since less amount of cabling is required and no network switches are required
- Good for smaller networks not requiring higher speeds

Disadvantages

- Trouble shooting and error detection becomes a problem because, logically, all nodes are equal
 - Less secure because sniffing is easier
 - Limited in size and speed
3. **Ring Topology:** All the nodes in a Ring Network are connected in a closed circle of cable. Messages that are transmitted travel around the ring until they reach the computer that they are addressed to, the signal being refreshed by each node. In a ring topology, the network signal is passed through each network card of each device and passed on to the next device. Each device processes and retransmits the signal, so it is capable of supporting many devices in a somewhat slow but very orderly fashion. There is a very nice feature that everybody gets a chance to send a packet and it is

guaranteed that every node gets to send a packet in a finite amount of time.



Advantages

- Broadcasting and multicasting is simple since you just need to send out one message
- Less expensive since less cable footage is required
- It is guaranteed that each host will be able to transmit within a finite time interval
- Very orderly network where every device has access to the token and the opportunity to transmit
- Performs better than a star network under heavy network load

Disadvantages

- Failure of one node brings the whole network down
- Error detection and network administration becomes difficult
- Moves, adds and changes of devices can effect the network
- It is slower than star topology under normal load

Generally, a BUS architecture is preferred over the other topologies - ofcourse, this is a very

subjective opinion and the final design depends on the requirements of the network more than anything else. Lately, most networks are shifting towards the STAR topology. Ideally we would like to design networks, which physically resemble the STAR topology, but behave like BUS or RING topology.

. Conclusion

The Future It's risky to predict the future of something as dynamic as the Internet. It seems safe to say that we will see a continuing explosion of new services. Today, at least a dozen companies are engaged in providing electronic funds transfers on the Internet in support of electronic commerce. Other companies are exploring the provision of packetized video, videoconferencing, packetized voice (packet telephone!), and increasingly sophisticated tools for securing Internet operation for intra- and inter-corporate use. Projections of Internet-related business range to \$50 billion at the end of the decade. While this is still small compared to the total telecommunications business (estimated at about \$300 billion today), its rapid growth and the rich evolution of new products and services suggest that the modest research investments of the federal government have paid off in myriad ways, not all of them merely monetary. There is every reason to believe that the Internet will transform education, business, government, and personal activities in ways we cannot fully fathom. Virtually none of this would have happened as rapidly, or in the same open and inclusive fashion, had not the federal government consciously provided sustained research funding and encouragement of open involvement and open standards, and then wisely stepped out of the picture as the resulting systems became self-sustaining. The Internet is truly a global infrastructure for the 21st century -- the first really new infrastructure to develop in nearly a century.

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