



# Analytical Study on Seismic Response Control of Multistory RC Building Frame Using Various Types of Bracing Systems

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## Abstract:

Seismic design relies on inelastic deformation through hysteretic behavior. During severe earthquakes the structural system undergoes extensive damage that result in high cost of repair. Research these days has elevated and surpassed common human instinct. One such research that backed structural systems to sustain tremors of earthquake is metallic braces. These components are predominantly the lateral force resisting system in any building structure. The installation of braces within a structure system will magnetize substantial part of destruction while the parent elements persist elastically with inferior inelastic deformation. Dissipation of seismic energy occurs through inelastic yielding and buckling of bracing member in tension and compression respectively. In the present work structured in a reinforced concrete G+7 storied moment resisting frame building which modeled using (Software for Analysis and Design) SAP-2000. The building modeled in accordance with the provisions prescribed by IS:1893 2012 part I. Three patterns of bracing will be fabricated on the peripheral frame of erection, where pattern being X, V and Inverted V. Both types of non linear analysis i.e. dynamic time history (NTH). Results for NTH will described in the form of storey displacement, storey drift, shear force, bending moment and energy dissipated by frame and bracing.

## Keywords

Bracing, SAP-2000, Pushover analysis, Non linear Time history analysis.

## 1. Introduction

### 1.1 General

A seismic design is based upon combination of strength and ductility. For small, frequent seismic

disturbances, the structure is expected to remain in the elastic range with all stress well below the yield level. However it is not reasonable to expect that the traditional structure will respond elastically when subjected to major earthquake. Instead the design engineer relies upon the inherent ductility of the building structure to prevent catastrophic failure while accepting certain level of structural and non structural damage. Ultimately, with these approaches, the structure is designed to resist an equivalent static load and results have been reasonably successful. Even an approximate accounting for lateral effects will almost certainly improve building survivability. However, by considering the actual dynamic nature of environmental disturbances, more improvements were made in the design procedures.

### 1.2 Modern Structural Protective System

The modern structural protective system is categorized into three major categories: Seismic Isolation System, Passive Energy Dissipation Devices and Semi Active and Active Energy Dissipation Devices. These energy dissipation devices When gets installed inside any structure curtails response due to the seismicity of earthquake ground motion. All these devices have their advantages and disadvantages but prove to be effective in improving response of structure.

#### 1.2.1 Seismic Isolation System

The technique of seismic isolation is now widely used in many parts of the world. A seismic isolation system is typically placed below the foundation of the structure. This isolation device is a flexible system due to which it possesses good energy absorbing capability. Some of the seismic isolation devices proposed for dissipation of energy include Elastomeric Bearings, Lead Rubber Bearings, Combined Elastomeric and Sliding Bearings, Sliding



Friction Pendulum Systems and Sliding Bearings with Restoring Forces.[22]

### **1.2.2 Active and Semi-Active Control System**

On the other hand there are semi-active and active control systems. Semi-active and active structural control is an area of structural protection in which the motion of a structure is controlled or modified by means of the action of a control system through some external energy supply. The technology is now at the stage where actual systems have been designed, fabricated and installed in full-scale structures. Some of the existing active and semi-active control devices are Active Bracing Systems, Active Mass Dampers, Variable Stiffness and Damping Systems Smart Materials.[22]

### **1.2.3 Passive Energy Dissipation Devices**

While all these technologies are likely to have an increasingly important role in structural design, the scope of the present monograph is limited to a discussion of passive energy dissipation systems. Research and development of passive energy dissipation devices for structural applications have roughly a 25-year history. In recent years, serious efforts have been undertaken to develop the concept of energy dissipation or supplemental damping into a workable technology, and a number of these devices have been installed in structures throughout the world. Because of the added damping force that passive device provides, their distribution over the height of the building is critical towards reducing vibration and preventing large structural damage. [22]

#### **1.2.3.1 Metallic Damper**

One such passive energy dissipation device is a Metallic Damper. Metallic dampers are one of the most effective mechanisms available for the dissipation of energy, input to a structure during an earthquake, is through the inelastic deformation of metallic substances. This metallic damper is also called as a metallic fuse or structural fuse. The concept behind this device comes from the fuse of an electric circuit. What happens in an electric circuit is that excess of electric current flows through a circuit the electric fuse wire break down by self-sacrificing itself thereby protecting the electric appliances. Examples of metallic dampers that have received significant attention in recent years include the X-shaped and triangular plate dampers. Force-deformation characteristics. Since this overall response is intimately linked with the cyclic stress-strain behavior of the metal, it is beneficial at this point to briefly review the typical inelastic stress-strain response of structural steel. [22]

### **1.2.3.2 Bracing as Passive Energy Dissipation Devices**

Besides these devices different type of bracing system could be thought upon to dissipate the seismic energy through the structure functioning unlike the metallic damper. These bracings are essentially made of mild steel. These bracings also dissipate energy through their inelastic yielding capabilities. There are mainly two type of bracing system that exist they are concentric type and eccentric type of bracing system. Different type of bracing system that attained the focus of the structural designers includes X bracing system, V bracing system, Inverted V bracing system and K bracing system which are a part of concentric bracing system.

## **2. Modeling and Analysis of Frame**

From literature surveyed it is concluded that using bracing element is very economical way to reduce seismic weight of any type of building structure. Shear wall also help in curtailing the lateral force effect due to ground motion but it add on to a greater seismic weight. So using bracing and metallic damper as fuse element improves the performance of building during earthquake thereby reducing the seismic weight. So in the present work for evaluating the concept of metallic fuse a G+7 storey reinforced concrete (RC) moment resisting frame situated in zone IV is modeled. Concentric type bracing metallic X-plate damper (XPD) imparted to structure is modeled as fuse element. Concentric bracing includes three different pattern of bracing where there are varying numbers of plates in XPD. Both type of analysis nonlinear dynamic time history analysis (NTH) and nonlinear static procedure (NSP) is carried out using SAP-2000 version 4.2. Pushover or nonlinear static analysis is performed as per the guidelines provided by federal emergency and management agency (FEMA) - 356 and applied technical council (ATC) - 40.

### **2.1. Modeling of Building Frame**

Metallic fuse is the easiest and simplest way of reducing response of building. To verify the concept of metallic fuse bracing system and metallic plate damper are considered as variables. This has resulted analysis of seven models. The details of the models is as follows

Model In - G7RCFWOSED: G+7 storey Reinforced Concrete Frame Without Supplemental Energy Dissipating Device

Model II - G7RCFWXBS: G+ 7 storey Reinforced Concrete Frame with X Bracing System.

Model III - G7RCFWVBS: G+ 7 storey Reinforced Concrete Frame with V Bracing System.

Model IV - G7RCFWIVBS: G+ 7 storey Reinforced Concrete Frame with IV Bracing System.

Model V- G7RCFW10XPD: G+ 7 storey Reinforced Concrete Frame with 10 X Plate Damper.

Model VI - G7RCFW15XPD: G+ 7 storey Reinforced Concrete Frame with 15 X Plate Damper.

Model VII - G7RCFW20XPD: G+ 7 storey Reinforced Concrete Frame with 20 X Plate Damper.

**2.1. Details of the Models**

**2.2.1. Column and Beam Sizes for Modeling of Building**

Table 3.1 Column and Beam Sizes for Modeling of Building

Sr. No.	Element	Notation	Size (mm)
1	Column	C1	350 X 400
		C2	450 X 500
2	Beam	B1	300 X 350
		B2	350 X 400

**2.2.2 Assumed Data for Models**

- Building = G + 7 Storey
- Slab Thickness = 150 mm
- Live Load = 3 kN/m<sup>2</sup>
- Floor Finish = 1 kN/m<sup>2</sup>
- Concrete Grade = M20
- Concrete Density = 25 kN/m<sup>3</sup>
- Steel Grade = Fe415
- Steel Density = 7850 kN/m<sup>3</sup>
- Earthquake Used = North Ridge, Imperial Valley and Loma Prieta Earthquake.

**2.2.3. Description of Bracing**

- Section Used = ISMB125
- Material Used = Mild Steel

**2.2.4. Mechanism of X Plate Damper**

X-plate dampers consist of one or multiple X-shaped steel plates, each plate having a double curvature and arranged in parallel; this number of plate depends upon required amount of energy to be dissipates in the given system. Material used for manufacturing of X-plate may possibly be any metal which allow large deformation such as mild steel, although sometimes lead or more exotic metal alloy are employed. In order to reduce the response of structure by dissipating the input seismic energy such damper can be used with an appropriate supporting system, intrinsically in building structure combination of bracing and XPDs can be used and such assembly is known as device-brace assembly. They can sustain many cycles of stable yielding deformation, resulting in high level of energy

dissipation or damping. The aim behind the use of X-shape of damper is it will have a constant strain variation over its height, thus ensuring that yielding occur simultaneously and uniformly over the full height of the damper. XPDs allow it to behave nonlinearly but restrict behavior of the structure up to the linear elastic range [27]. A view of XPD and its set up is depicted in Figure 3.6

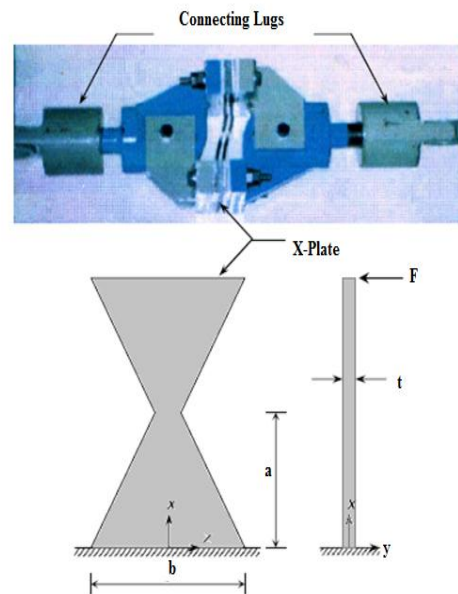


Figure 3.6 Actual Setup and X Plate Damper

**2.2.5. Properties of XPD**

- Height of triangular portion (a) = 40mm
- Breadth of triangular portion (b) = 60mm
- Thickness of plate (t) = 4mm
- Number of X- Plates Used (n) = 10, 15, 20
- Modulus of Elasticity (E) = 1.922X10<sup>5</sup> N/mm<sup>2</sup>
- Yield Stress (σ<sub>y</sub>) = 235 N/mm<sup>2</sup>

A series of experimental tests were conducted at Bhabha Atomic Research Center (BARC) and IIT Bombay to study the behavior of these XPDs by Bakre et al. [27] also studied the behavior of XPDs and observed the subsequent results (i) it exhibits smoothly nonlinear hysteretic loops under plastic deformation; (ii) it can sustain a large number of yielding reversals; (iii) there is no significant stiffness or strength degradation and (iv) it can accurately modeled by Wen’s hysteretic model or as a bilinear elasto-plastic material. A typical XPD with holding device used in the present work.

Using beam theory the properties of XPD are expressed as



$$F_y = \frac{\sigma_y b t^2}{6 a} \quad (3.1)$$

$$q = \frac{2 \sigma_y a^2}{E t} \quad (3.2)$$

$$K_d = \frac{F_y}{q} = \frac{E b t^3}{12 a^3} \quad (3.3)$$

a, b and t are height, width and thickness of the XPD. Using equation 3.1, 3.2 and 3.3 properties of mild steel such as yield force, yield displacement and initial stiffness respectively of X-plate damper are calculated. These properties are required as input for the modeling.

$$F_y = \text{Yield Force} = (235 * [10]^{(3)}) * 0.06 * [(4 * [10]^{(-3)})^2] / (6 * 0.04) = 0.94 \text{ kN} \quad (3.1 a)$$

$$Q = \text{Yield Displacement} = \frac{(2 * 235 * [10]^{(3)} * (0.04)^2) / (1.922 * [10]^{(8)} * 4 * [10]^{(-3)})}{[10]^{(-4)}} = 9.78 \text{ m} \quad (3.2 b)$$

$$K_d = \text{Initial Stiffness} = 0.94 / (9.78 * [10]^{(-4)}) = 961.1 \text{ kN/m} \quad (3.3 c)$$

### 2.3. Non Linear Time History Analysis

In this method of dynamic analysis, the earthquake motion is directly applied to the base of a given structure with the help of the computer program. Instantaneous stresses throughout the structure are calculated at small intervals of time for the full duration of the earthquake or the significant portion of it. The maximum stresses in any member that occurs during the earthquake can then be found by scanning the output record and the design reviewed. The actual plot of three ground motion record considered for study is shown in Figure 3.7.

The procedure to maximum stress includes the following steps:

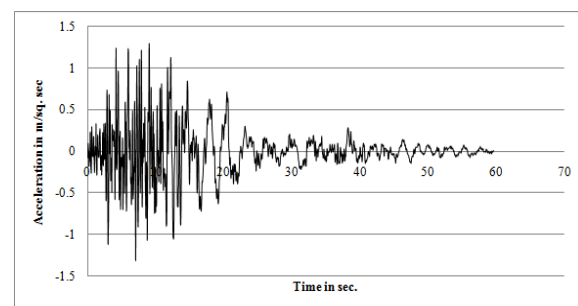
1. The earthquake record is selected which represents the expected earthquake. The record is digitized as a series of ground accelerations at small time intervals of about 1/40 to 1/25 of a second with given levels of acceleration occurring for each interval.
2. The digitized record is applied to the building model as accelerations at the base of the structure.
3. The computer integrates the equations of motion of the multi degree of freedom system as it is subjected to increments of elastic and damping forces and gives a complete record of the acceleration, velocity, and displacement of each lumped masse.
4. The accelerations and relative displacements of the lumped masses are translated into member

stresses. The maximum values can then be found by scanning the output record. This procedure automatically includes various modes of vibration and combines their effect.

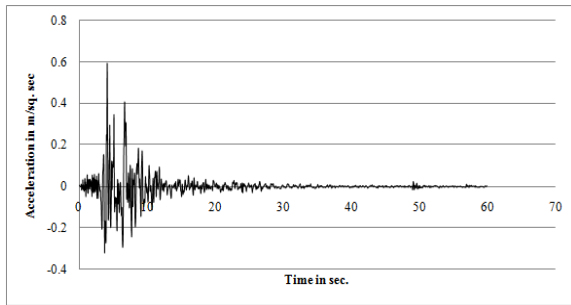
According to the code, dynamic analysis may be performed using either response spectrum method or the time history method. In either method the design base shear (VB) is compared with the base shear  $V_B$  calculated using the fundamental period  $T_a$ . It suggests that when  $V_B$  is less than  $V_B$  all the response quantities (for example member forces, displacements, storey force, storey shear and base reactions) must be suitably scaled by multiplying with  $(V_B / V_B)$ .

#### 2.3.1. Procedure for Non Linear Time History Analysis

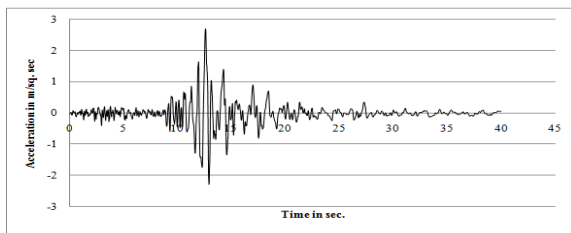
1. Define time history function for applying time histories on the models.
2. Then define a new load case of time history function.
3. Write the function name and define the load case as time history from the dropdown menu.
4. Then select the analysis type as nonlinear and time history type as modal.
5. Load is applied to the modal in form of acceleration in X direction with predefined time history function and scale factor as one.
6. The whole procedure includes only material non linearity.
7. After defining function and load case run the analysis and access the results.



(a)



(b)



(c)

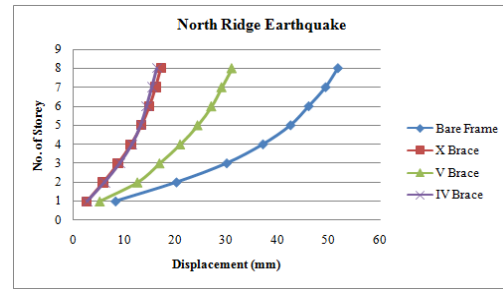
Figure 3.7 Input Acceleration Time History (a) Imperial Valley (b) North ridge (c) Loma Prieta Earthquake.

### 3. Results and Discussion

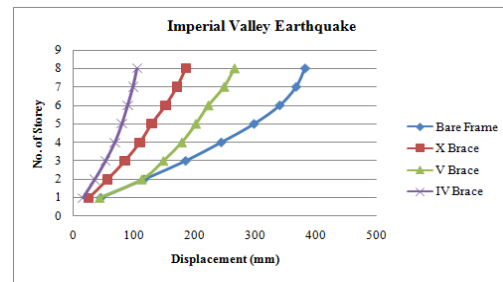
The main purpose of applying nonlinear dynamic time history analysis is to examine the response of modeled building structure under real earthquake ground motions. The analysis exhibits actual behavior caused due to seismic disturbances. The resulting response found from such an evaluation is very realistic in nature. Therefore the consequences of installing PED's in structure could be investigated on a factual basis. NTH is carried out by imposing three time histories on to the modeled structure which are applied in the horizontal direction and their outcomes are discussed in following points.

#### 3.1. Effect of Bracing on Storey Displacement

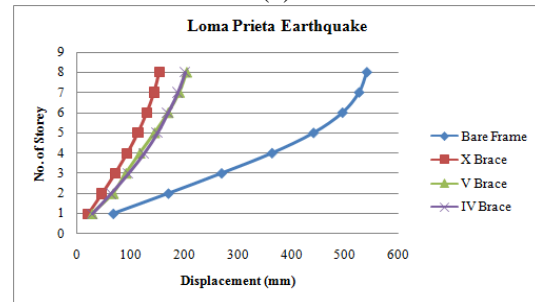
Figure 3.1. presents storey displacement occurred at various stories for different pattern of bracing. Figure compares the effect of bracing on displacement of each storey with bare frame for earthquake of three different intensities.



(a)



(b)



(c)

Figure 3.1 Displacement Comparisons for Model I, II, III and IV (a) North Ridge Earthquake (b) Imperial Valley Earthquake (c) Loma Prieta Earthquake

Figure 3.1 it observed that, for bare frame model-I the displacement is maximum at top storey for the entire three earthquakes. But displacement is lowest in case of Northridge earthquake and increases for Imperial Valley and Loma Prieta earthquake. Same phenomenon has also occurred for models II, III, and IV. Amongst all the considered bracing patterns X and inverted V proved to very effective in reducing displacement at all the storey levels. Top storey displacement reduced by 63.35%, 44.25% and 67.85% for models II, III and IV respectively as compared to model-I. The increase in stiffness of bare frame structure due to the installation of bracing is the reason for reduction in storey level displacement.

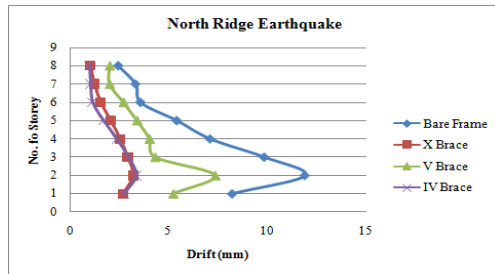
#### 3.2. Effect of Bracing on Storey Drift

P- $\delta$  effect due to storey drift affects building. Therefore Figure 3.2 depicts storey drift at each

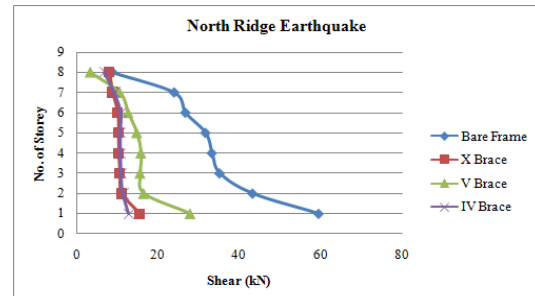


storey level for different pattern of bracing with varying intensities of earthquake.

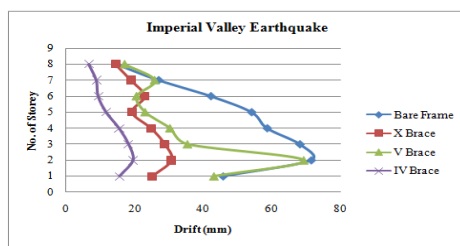
utilized for three different ground motion in Figure 3.3.



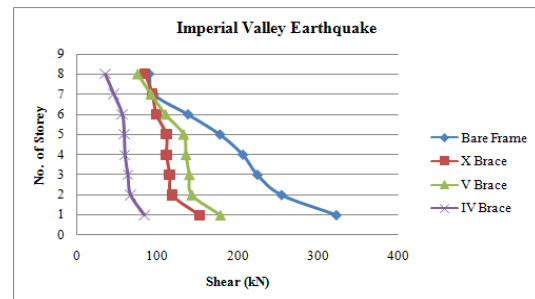
(a)



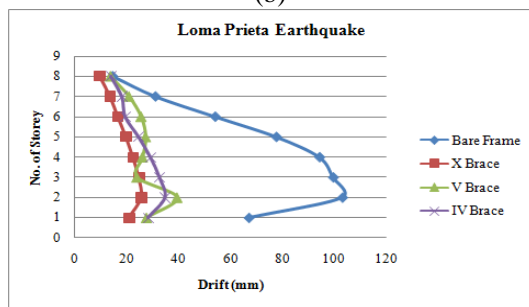
(a)



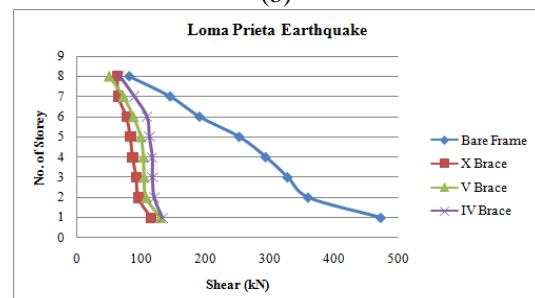
(b)



(b)



(c)



(c)

Figure 3.2 Storey Drift Comparisons for Model I, II, III and IV (a) North Ridge Earthquake (b) Imperial Valley Earthquake (c) Loma Prieta Earthquake

Figure 3.3 Shear Force Comparisons for Model I, II, III and IV (a) North Ridge Earthquake (b) Imperial Valley Earthquake (c) Loma Prieta Earthquake

A comparative study of storey drift from Figure 4.2 reveal that, for models I, II, III and IV maximum storey drift has occurred at second storey. Storey Drift is least for North Ridge earthquake and increases for Imperial Valley and Loma Prieta earthquake. Within the considered bracing system, X and Inverted V brace system effectively decreased storey drift in comparison to V brace system. The reduction in storey drift occurred due to decrease in storey displacement. A 68.48%, 34.26% and 70.21% decrease in is observed for models II, III and IV as compared to bare frame model-I.

### 3.3. Effect of Bracing on Shear Force

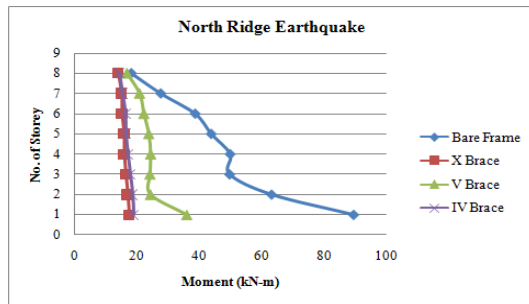
A comparison is made between shear force values of bare frame and different configuration of bracing

Lateral shear force is maximum in bottom storey column for models I, II, III and IV which is evident from Figure 3.3 Shear force is minimum in case of Northridge earthquake and increases thereby for Imperial Valley and Loma Prieta earthquake. From Figure 4.3 it is observed that X and inverted V bracing system effectively reduce shear demand on columns as compared to V brace system. Shear in column decreased due to the participation of bracing which shared the lateral load along with column. The maximum shear in bottom storey column reduced by 67.61% for model-I, 56.81% for model-II and 74.92% for model-III as compared to bare frame model-I

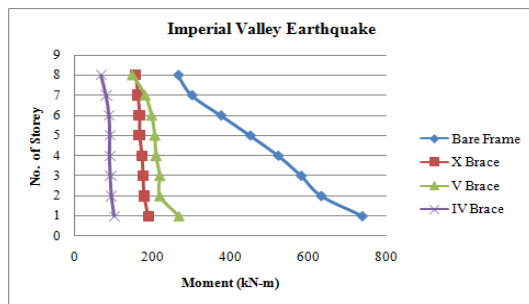


### 3.4 Effect of Bracing on Moment

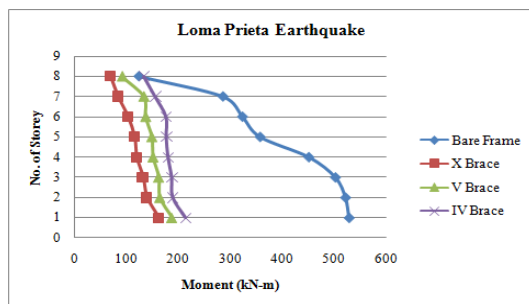
The moment value recorded at each floor level for comparative study of bracing system with bare frame considering three earthquakes is depicted in Figure 3.4.



(a)



(b)



(c)

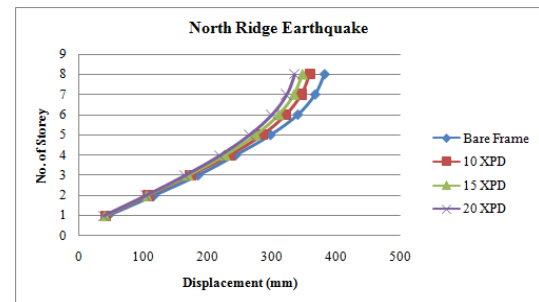
Figure 4.4 Moment Comparison for Model I, II, III and IV (a) North Ridge Earthquake (b) Imperial Valley Earthquake (c) Loma Prieta Earthquake

It is evident from Figure 4.4 that, maximum biaxial moment is observed in bottom storey column for the entire three considered earthquake. The values of moment are greater in case of Imperial Valley and Loma Prieta earthquake as compared to North Ridge earthquake. X bracing proved to be the most effective in reducing moment when compared to V and inverted V bracing configuration. Due to the partial transfer of force in brace elements shear in column reduced thereby reducing moment on columns. There was 74.81%, 62.76% and 74.85%

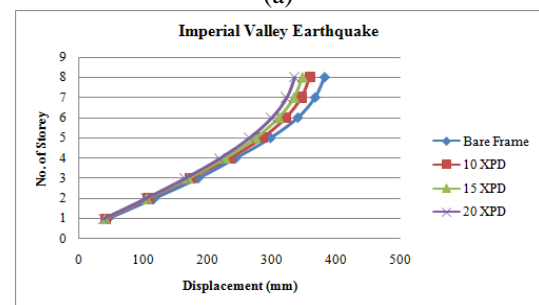
decrease in moment value for models I, II and III as compared to model-I.

### 3.5. Effect of X Plate Damper (XPD) on Storey Displacement

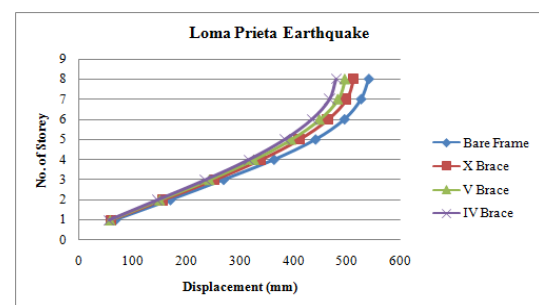
Effect on storey displacement at each storey level due to variation in number of plates for three different earthquakes is presented in Figure 3.5



(a)



(b)



(c)

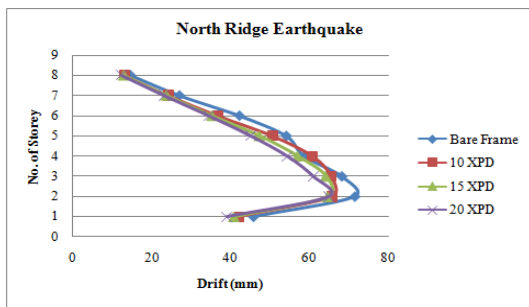
Figure 3.5 Displacement Comparisons for Model I, V, VI and VII (a) North Ridge Earthquake (b) Imperial Valley Earthquake (c) Loma Prieta Earthquake

Storey displacement is minimum at storey one and maximum at top storey which can be observed from Figure 3.5 for models I, II, III and IV. For the entire considered earthquake storey displacement is minimum for Northridge earthquake and increases thereby for Imperial Valley and Loma Prieta earthquake. For the entire considered earthquake top storey displacement is minimum for X-plate damper

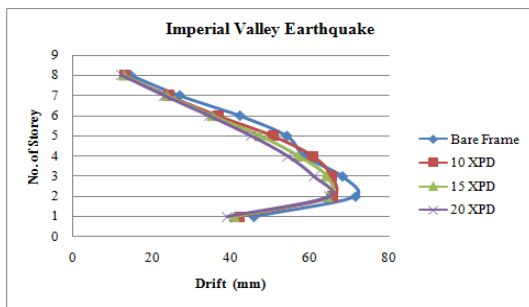


with twenty plates. This is because increase in number of plates increases the stiffness consequently curtailing storey displacement. 10XPD decreased top storey displacement by 11.88% in model-V, 15XPD by 17.09% in model-VI and 20XPD by 24.99% in model-VII as compared to bare frame model-I.

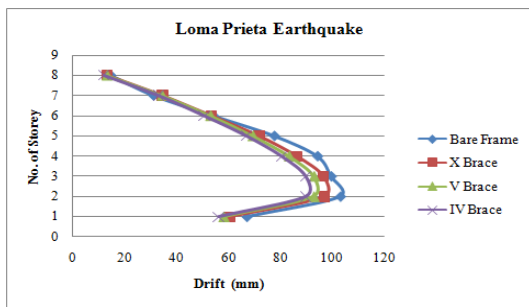
### 3.6 Effect of X Plate Damper (XPD) on Storey Drift



(a)



(b)



(c)

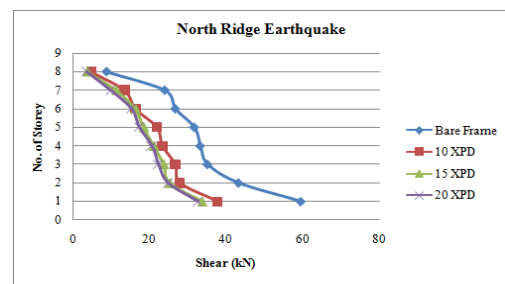
Figure 3.6 Storey Drift Comparison for Model I, V, VI and VII (a) North Ridge Earthquake (b) Imperial Valley Earthquake (c) Loma Prieta Earthquake

Maximum storey drift occurred at second storey for all earthquake under consideration is evident from Figure 4.6 for models I, V, VI and VII. Higher values of storey drift are observed for Imperial Valley and Loma Prieta earthquake whereas these get reduced for North Ridge earthquake. For every

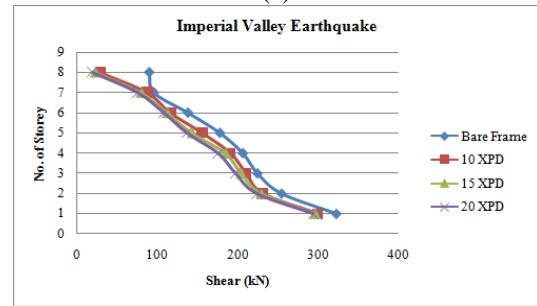
increase of five plates there is 3% to 4% curtailment in percentage reduction in storey drift and is found to be least in case of 20XPD which occurred due to decrease in storey displacement. Reduction in storey drift for model V, VI and VII as compared to model-I is 17.22%, 20.95% and 21.54% respectively.

### 3.7. Effect of X Plate Damper on Shear Force

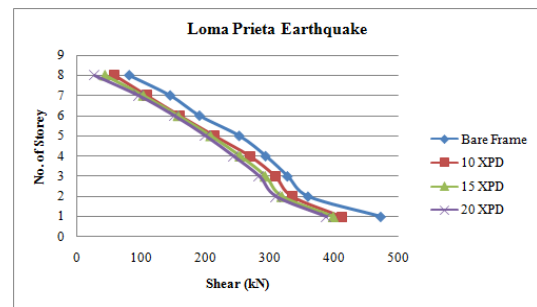
Figure 3.7 depicts values of shear force at each storey level. The shear force values of bare frame are compared with 10XPD, 15XPD and 20XPD for three earthquakes.



(a)



(b)



(c)

Figure 3.7 Shear Force Comparison for Model I, V, VI and VII (a) North Ridge Earthquake (b) Imperial Valley Earthquake (c) Loma Prieta Earthquake

The resisting horizontal force component applied by metallic damper counteracts seismic forces thereby reducing the shear force on columns which is observed from Figure 4.7 for models I, V, VI and

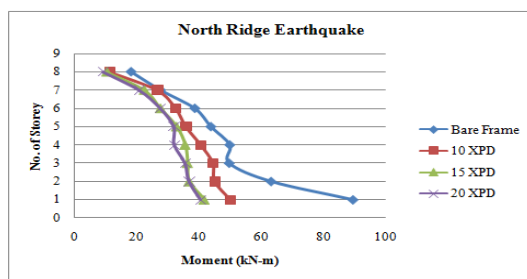




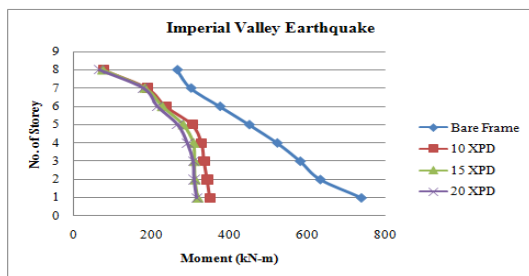
VII. These seismic forces acting on frames are transferred from joints to the damper thus reducing shear force demand on columns for all the applied ground motions with varying number of plates. It is also observed that North Ridge earthquake had least response as compared Imperial Valley and Loma Prieta earthquake.

### 3.8 Effect of X Plate Damper on Moment

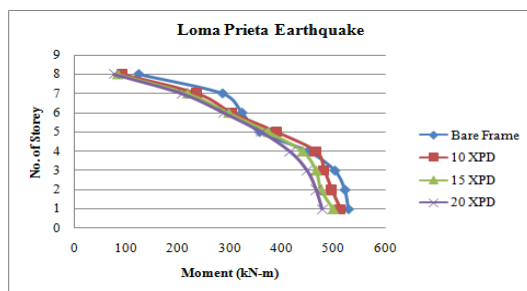
Moments induced in columns for bare frame and X-plate damper with plate variation is shown in Figure 3.8. The moment value recorded for different system is analyzed for three earthquakes.



(a)



(b)



(c)

Figure 3.8 Moment Comparison for Model I, V, VI and VII (a) North Ridge Earthquake (b) Imperial Valley Earthquake (c) Loma Prieta Earthquake

Figure 3.8 shows that moment are maximum in bottom storey column for model I, V, VI and VII. The moments on frames are reduced due to axial transfer of force in XPD thereby reducing shear force demand and consequently moments. Using 10XPD,

15XPD and 20XPD in model V, VI and VII reduced the moment value by 33.26%, 38.55% and 40.39% respectively as compared to bare frame model-I.

## 4. Conclusion

Nonlinear dynamic time history analysis gives accurate results due to earthquake ground motions. Three time histories of different earthquakes are imposed on models. Based on the time history analysis of various models, following conclusions are drawn.

A significant reduction in the top storey displacement and storey drift have been observed for X, V and Inverted V bracing models II, III and IV as compared to bare frame model-I.

The maximum shear in bottom storey column and biaxial moment in columns have been reduced significantly for X, V and Inverted V bracing models as compared to bare frame model.

Reduction in the top storey displacement and storey drift is not so significant between models V, VI and VII as compared to bare frame model-I.

A minor variations in the maximum shear in bottom storey column and biaxial moment in columns have been observed in models V, VI and VII as compared to bare frame model-I.

The input energy dissipated through hysteretic behavior of metallic damper in models V, VI and VII is not significant.

X bracing system proved to be the most effective system in curtailing response due to ground motions.

All the plates in X-Plate Damper have yielded well and dissipated considerable amount of energy.



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