

Stability Criteria For Ac Power Systems With Regulated Loads

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ABSTRACT

In this paper the voltage source converters are taken for getting the improved d c voltage at the AC source. In the distribution system, power grid is nonideal. with input as voltage source and which consists of some ripples here the power converters or rectifiers are connected to the nonideal grid .interacting with each other in this paper we are maintains the constant voltage or stable power at the line by using the converters. We consider the effect of both source (grid) impedance and transmission line impedance between converters, It is shown that the system of interacting converters can become unstable. Moreover, results are presented in design-oriented forms so facilitate the identification of as to variation trends of stable operation The boundaries. Experimental results verify in simulink/MAT LAB.

I.INTRODUCTION

The Power system faces many problems when distributed generation is added in the already existing system; this is because the power system is not designed with distributed generation in mind. The addition of generation could influence power quality problems, degradation in system reliability, reduction in the efficiency, over voltages and safety issues. On the other side's the power system distribution are well designed which could handle the addition of Generation if there is Proper grounding, transformers and protection is provided. But there are limits to the addition of distributed generations if it goes beyond its limit then it is important to modify and change the already designed distributed system equipment and protection, which could in a result facilitate the integration of new generation. One of the important aspects is that, power electronic devices and sensitive equipment's are designed to work in nonpolluted power systems. So, they would suffer from malfunctions when the supply voltage is not pure sinusoidal. As these devices are the most important Cause of harmonics, inter harmonics, notches and neutral currents, the power quality should be improved.



Fig. 1. Multiple VSCs connected to power grid.



The voltage source inverter topology uses a diode rectifier that converts utility/line AC voltage (60 Hz) to DC. The converter is not controlled through electronic firing like the CSI drive. The DC link is parallel capacitors, which regulate the DC bus voltage ripple and store energy for the system. The inverter is composed of insulated gate bipolar transistor (IGBT) semiconductor switches. There are other alternatives to the IGBT: insulated gate commutated thyristors (IGCTs) and enhanced injection gate transistors (IEGTs). This paper will focus on the IGBT as it is used extensively in the MV VSI drives market. The IGBT switches create a PWM voltage output that regulates the voltage and frequency to the motor.



Fig.2 voltage source converter

As the spectrum of applications of VSCs widens, it can be appreciated that multiple VSCs may connect to the power grid at also called common point of coupling (PCC), while each VSC works under its own specific condition, as shown in the usual representationofFig.1.The same structure is also employed in some specific application scenarios, including aircraft power systems, shipboard power systems, micro grid etc. As each converter is designed separately for its own load condition, the mutual coupling in practice via the grid may pose a stability concern as the grid is nonideal in reality and presents at the point of common coupling a significant amount of impedance, which is not always predictable. As a result, the stability of the system should be considered with the coupled system model in mind rather than the unrealistic though simple model, where each converter is assumed to behave independently.

II.MODEL DISCRIPTION

To maintain generality of our study, the VSCs are controlled under a typical feedback configuration that contains an outer voltage loop, which operates in conjunction with a sinusoidal PWM inner current loop for achieving a constant output dc voltage, as presented. The two converters have been designed separately according to their respective application conditions. However, when they are connected to the grid, their interaction may have an impact on stability. Furthermore, in practice, the effect of transmission line impedance LL.

The stability issue of grid-connected VSCs in the presence of varying grid impedance has been discussed in several prior publications. For instance, presented an impedance based approach to evaluate the stability of ac interfaces in the dq-frame by employing age neralized Nyquist stability criterion based on small-signal modeling, and for three-phase rectifiers, the analysis assumed an ideal power grid.



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Fig.3. Basic model of two VSCs connected to the nonideal grid.

Have reported the effects of grid impedance on grid-connected interacting converters, but these works focused on the stability of one converter and avoided the complication of analysing the more realistic situation where two or more converters' interact in the presence of significant grid impedance. While literature abounds with studies of threephase rectifiers, in-depth study of variation of control parameters on stability of interacting three-phase rectifiers is still glaringly insufficient. Furthermore, from previous study of nonlinear behaviour of power converters, some bifurcation phenomena have been observed and reported, which provide effective analytical tools for some in depth study of stability of interacting converters.



Fig 4.Controller diagram of Simulink file

In this paper, we attempt to address the important issue of the effect of interaction between the grid-connected converters under nonideal power grid conditions, which has remained largely unexplored despite its practical importance. Our study will problem in to the key control parameters and examine how variation of these parameters alters the stability regions under the effect of converters' interaction. Specifically, we focus on the loss of stability corresponding to emergence of allow frequency oscillation as commonly under studied the broad class of Hopftypebi furcation phenomena. We show that the bi furcation boundaries (stability regions from an engineering view point) generally shrink when converters interact via the nonideal grid. In other words, results obtained from analysis that independent (uncoupled) assumes converters under ideal grid condition, therefore, provide overoptimistic stability prediction. In Section II, we present several instability phenomena arising from converters' interaction. In Section III, in the presence and absence of transmission line impedance, a detailed stability assessment employing an impedancebased approach is presented. In Section IV, we present our results in a design-oriented format that reveals the way in which



stability would be affected by variation of selected parameters, and hence, facilitates the choice of parameters for stable operation. Moreover, Section V presents the observed instability phenomenon experimentally. Finally, Section VI concludes the paper.

Basic Model: The Standalone Converter Following the formulation of Sun, the three-phase VSC can be represented by an averaged model in the dq rotating coordinate. Since converters 1 and 2 share the same model, we provide, for brevity, the equations for converter 1.

B.ANALYSIS

Literature abounds with conventional analyzing methods for converter's stability. For an individual grid-connected VSC, control models and their closed-loop stability analysis have been studied, employing techniques like root locus analysis and Bode diagrams. Moreover, the state-space approach is also used to determine stability in the time domain. For grid-connected converters, prior studies have pointed out that the impedance-based approach is more advantageous and flexible. For the case of the grid connected system under study, the impedance-based analysis is highly suitable, as will be demonstrated in the subsequent sections.

Moreover, the two converters may not be connected at the same PCC in practice. Thus, LL =0. When the converters are connected to the same grid at different points of coupling, the presence of nonzero transmission line impedance LL between the two converters' connection points could affect stability, as shown in Fig. 5. We see that the two converters connected to the nonideal grid at the same PCC are originally stable, as shown in Fig. 5(a), but can become unstable when the coupling points are separated by nonzero transmission line impedance, as shown in Fig. 5(b). Thus, the converters connected to a nonideal grid can be made unstable by presence of transmission the line impedance separating the points of coupling.

C.THE INSTABILITY

We begin by taking a quick glimpse at the in which way a VSClosesstability.ThecircuitofFig.2isstudi edinfullcircuit implementation using MATALAB. The values of the circuit components used in the simulation are summarized in Tables I. Converters 1 and 2 employ the same control method that is described in Fig.. shows stable operation of the two converters with different load conditions when separately connected to the same nonideal grids with impedance Ls =1 .2 mH. Thus, the converters are stable when analyzed separately. However, when the converters are connected at the same time to the nonideal grid having the same impedance at the PCC, i.e., LL =0, as shown in Fig. 2, the converters' output voltages have manifested low frequency oscillations that are typical Hopf-type instability, as shown in Fig. The dc voltage Udc of both converters oscillate at 255 Hz around the regulated level, while all converters' parameters have remained the same as in the case of independent (uncoupled) operation. Thus, it can be inferred that the converters could interact with each other and lose stability via a Hopf-type bifurcation when the values of parameters are selected beyond a specific region in the parameter space (referred to as stability region here)



III.RESULTS AND VERIFICATION

The foregoing analysis provides a precise tool for determining the system's stability using interface impedance. However, for engineering design purposes, it is more useful to identify the system parameters and their variation trends that have significant impact on the stable region of operation. In this section, we derive stability boundaries using the foregoing analysis and present them in designoriented forms. Results from simulations of the actual switching circuits will also be presented for comparison and verification. Relevant to our present study is the region of stable operation bounded by the bifurcation boundary corresponding to the loss of stability via a Hopf-type bifurcation (practically known as low-frequency oscillation). For the system of two converters connected to a nonideal power grid, we focus on the following conditions

parameters: 1) the grid impedance Ls; 2) the transmission line impedance LL; 3) thedcgainsofthetwoconverters'voltageloop kvp1,kvp2; 4) the converters' load resistance RL1,RL2; 5) the dc-link capacitance Cdc1,Cdc2.

Moreover, for the purpose of comparison, the stability regions of converters coupled via the power grid and those of the independently operating (uncoupled) converters are presented. Our results are generated from simulations of the complete switching model, which provides viable verification of the actual physical system.



Fig.5 Simulink model of basic circuit.

IV. RESULTS :

a) Vdc1, Vabc1, & labc1

III.SIMULINK MATLAB MODEL





b) Vdc2 Vabc2, & labc2



V.CONCLUSION

Three-phase VSCs connected to a nonideal power grid are studied in this paper. This

study is important as converters are increasingly deployed being for applications involving power conversion functions that require interfacing with power grid, which is often nonideal. The significant impedance present in the grid poses an issue deserving attention as converters' stability is no longer a standalone problem. Through mutual interaction, converters become more prone to instability under certain conditions. Analysis has been developed using the impedance approach, and stability boundaries are derived in various parameter planes. Findings reported in this paper would facilitate engineers in making design choices related to the selection of parameter values that would guarantee stability in a sufficiently wide parameter range.

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