

Observer for Lithium-Ion Battery State of Charge Estimation in Electric Vehicles

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Abstract: This paper recommends a new method for SOC estimation. In this technique, a new equivalent circuit battery model with one RC block is designed considering self-discharge. Associated with the conventional methods, some improvements have been achieved. Firstly, a Sliding Mode Observer (SMO) is adopted to estimate the SOC. Secondly, the new method divides the SOC estimation into two stages which include charging stage and discharging stage according to the battery status. The series resistance and parallel resistance of RC block in the battery model are taken into account to estimate the SOC in discharging of battery. It enhances the SOC estimation accuracy especially for large discharge current. Finally, a simulation is conducted to verify the performance of the method.

Keywords: Lithium-ion Batteries, SOC Estimation, Sliding Mode Observer, Battery Status

I. INTRODUCTION

Increasingly along with the fossil energy depletion, air pollution and more and more serious global climate changes, people have begun to realize the great importance of the utilization and development of non-fossil energy [1]. Governments all over the world have introduced a variety of incentives to reduce pollutant emissions and greenhouse gas emissions [2–6]. Since transportation consumes a large amount of energy, it is necessary to develop and utilize electric vehicles (EVs) to realize green mobility. Lithium-ion batteries (LIBs) have many advantages, such as high power density and durability, and therefore they have been widely used in EVs. However, when overcharging occurs, the LIBs are more likely to burn and explode than other batteries, necessitating higher requirements for battery

management system (BMS) [7–10]. A few parameters, such as maximum discharge current, specific energy of weight, specific energy of volume, and power density, determine an EV's performance [11–15]. The most important index for a BMS is state of charge (SOC). Because of the inherently time-varying and non-linearity characteristics of LIB under working conditions, accurate estimation of SOC remains a challenge [16–19].

In general, many SOC estimating methods do not consider battery status (including charging, discharging and rest) and parasitic parameters. In this paper, a new SOC estimation based on SMO method and battery status is proposed. The proposed method uses equivalent circuit model with one RC block to model the battery. It requires little computation and memory resources and can be applied to real application with lower hardware configuration. The method divides the SOC estimation into two stages, i.e., charging and discharging. When the battery is discharging,

II. BACKGROUND WORKS

The aforementioned methods can enhance the robustness and accuracy of the SOC estimation. However, they may engender a significant number of calculations for implementation because an error covariance matrix must be propagated at each sampling instance [20]. Other model-based approaches with constant gains, such as Luenberger observer [21,22], sliding mode observer [23,24], and nonlinear observer [25], have also been adopted to estimate the SOC. These methods depend on the exhaustive understanding of battery dynamics for the appropriate selection of the gains, which affect the estimation accuracy and convergence rate of the

observer. Nevertheless, the significant nonlinearity of SOC-OCV function means the sensitivity of the output with respect to the state varies greatly and constant gain is not suitable [26]. More recently, the SOC estimation methods based on sliding mode observer with gains adaption has been proposed to overcome the limitation [4,27]. They are able to reduce the chattering magnitudes and improve the SOC estimation accuracy by dynamically adjusting the switching gains of the observer. In addition, nonlinear observers with gains adaption proposed in [28,29] have been used to balance the estimation accuracy and convergence rate of the SOC. However, the methods proposed in [28,29] need additional calculation to obtain the Jacobian of the output with respect to currently estimated states, which is used to weight the gain at each sampling instance. It is worth noting that the computational cost of SOC estimation algorithm is important for its implementation on embedded hardware.

III. SYSTEM CONFIGURATION

The Equivalent circuit model of the Li-ion battery used in this paper is shown in Fig.1. The model can mimic the precise dynamic behavior of the lithium-ion battery. In this model, the open circuit voltage (OCV) is represented by a controlled voltage source, $V_{oc}(V_{soc})$. It is a function of battery's SOC, which is denoted by V_{soc} . Furthermore, an instantaneous terminal voltage variation due to the battery current I_b is given by inserting a series resistance denoted by R_s . R_s is also called ohmic resistance. It can expend the energy and reduce SOC when the battery is discharging. Nevertheless, the RC block (C_f , R_f) shows the dynamics response of battery voltage when a step load current is applied. The whole charge capacitor R_{sd} is denoted by C_n ($C_n = 3600C_Q$, C_Q is norm capacity (A*h)) and the self-discharge energy loss due to long time storage. Although the Li-ion has low self-discharge, it still influences the accuracy of SOC especially for large current I_b . Since there are modeling errors, uncertainties and time-varying elements in the model, 'IS', 'IRF' and 'IVRF' stand for these errors and uncertainties.

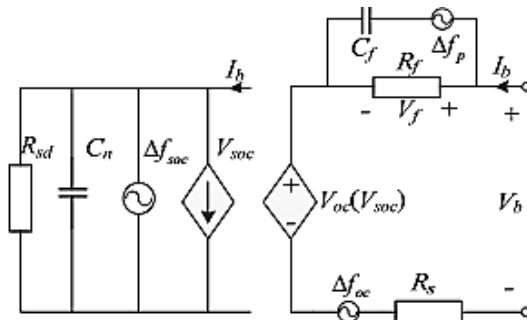


Fig.1. Equivalent circuit model of the Li-ion battery

Since the battery is a highly nonlinear device, SMO is well suited for solving the nonlinear problem. It needs fairly accurate battery model to eliminate the model uncertainties and requires little time for implementing and this solves the problems of coulomb counting method. The SOC can be estimated by the SMO designed. However, it is worth noting that the SOC estimation is different between battery charging and discharging. The new SOC estimation method in this paper makes some improvements to the common SOC algorithm. Firstly, the new SOC estimation method takes into account the effect of self-discharge resistor when charging and discharging the battery. It's still necessary for the Li-ion battery with low self-discharge. Secondly, the new SOC estimation method calculates the energy consumption of R_{sd} and R_f on the basis of SMO when the battery is discharging. So the proposed SOC estimation in this paper is divided into two parts. When the battery is charging, the SOC estimation uses the SMO.

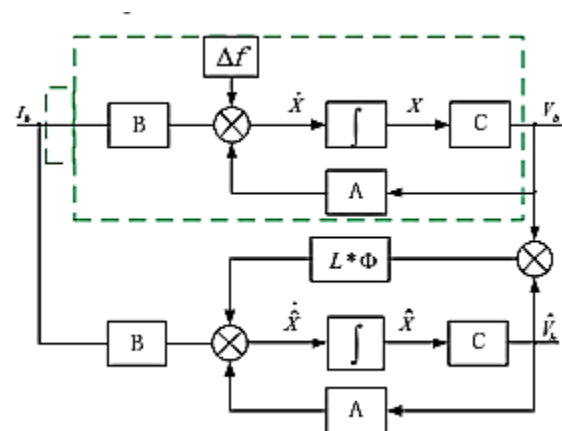


Fig.2. The structure of sliding-mode observer

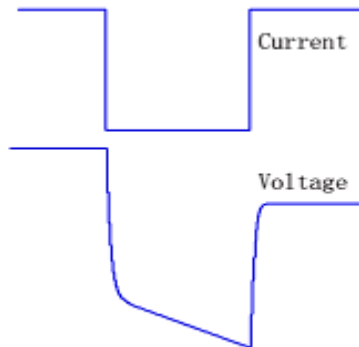


Fig.3. The experiment of battery discharge

The discharge experiments are conducted to get the parameters of the battery model in Fig.1. The experiment process is shown in Fig.3. Firstly, charging the battery up to 100% and leave the battery for two hours. Secondly, discharging the battery for ten minutes at 1C (6A) rate current and then leaving it unused for one hour. The SOC of the battery declines by 10%. Repeating the second steps six times until the SOC of the battery reaches zero. By these steps, the parameters of battery model can be recognized. The relationship between SOC and OCV can also be obtained.

IV. SIMULATION RESULTS

To verify the performance of the proposed SOC estimation in this paper, a digital simulation for 6000mAh Li-ion battery based on MATLAB/Simulink R2013A is conducted.

To simulate the noises in the real applications, the pseudorandom noise is added to the Li-ion battery (6000mAh). The frequency of the pseudorandom noise is 100Hz. The maximum value is 0.1V and the minimum value is -0.05V. The value of discharge current is 6A. The battery discharges for 4 seconds and stop discharging for 1 second. Repeat this process till the voltage of battery drops to 2.75V. The part of the discharging current is shown in Fig.4. The

initial value of battery voltage is 4.2V and the SOC is 1.

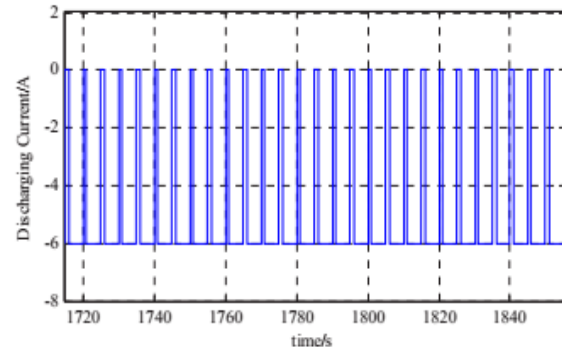


Fig.4 The part of the discharging current in simulation.

The simulation result of \hat{V}_b is shown in Fig.5. And the error between estimated value and real value is shown in Fig.6. As we can see from Fig.5 and Fig.6, the accuracy of \hat{V}_b estimation using sat function can be higher than sgn function.

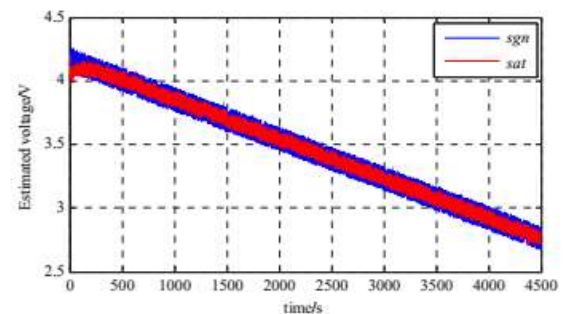


Fig.5. The estimated voltage of battery using sat and sgn

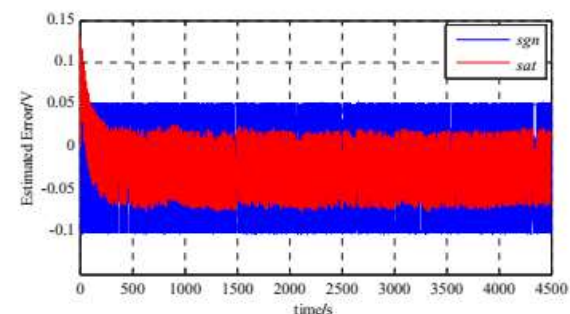


Fig.6. The estimated error of battery voltage using sat and sgn

V. CONCLUSION

This paper put forward a new SOC estimation method for Li-ion battery. A new equivalent circuit

battery model considering self-discharge is adopted in this method. Besides, the use of SMO can compensate the model errors and solves the problems of coulomb counting method. In addition, the SOC estimation method in this paper considers the influence of inner resistance of battery according to the battery status. The saturation function is designed to reduce the chattering phenomena. Finally, the simulation results show that it's better than the traditional method. In a word, the proposed SOC estimation method is valuable in engineering practice since a lower hardware configuration and software design

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