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Reduced Number of Power electronic devices for Three-Phase Cascaded Multilevel Inverter fed Induction Motor

TERUKOTI DIVYA M-tech Student Scholar Department of Electrical & Electronics Engineering, Baba Institute of Technology & Sciences, Visakhapatnam (Dt), A.P, India. Mail id: divyaterukoti56@gmail.com

Abstract-Multilevel inverters have an attracted a great deal of attenuation in medium voltage and high power application Due to their lower switching losses, EMI, high efficiency. This paper proposes to Cascade H bridge multilevel inverter to reduced total harmonic Distortion by increase the output voltage level. In this paper Three-Phase Cascaded Multilevel Inverter Based on a New Basic Unit with Reduced Number of Power Switches fedinduction motor. Thus multilevel inverter topologies are becoming more popular. A multilevel inverter topology is discussed. The inverter consists of series connection of a number of basic units. Therefore, multilevel inverters had been introduced and are being developed now. With an increasing number of dc voltage sources in the input side, a sinusoidal like waveform can be generated at the output. As a result, the total harmonic distortion (THD) decreases, and the output waveform quality increases, which are the two main advantages of multilevel inverters. In addition, lower switching losses, lower voltage stress of dv/dt on switches, and better electromagnetic interference are the other most important advantages of multilevel inverters. These features are obtained by the comparison of the conventional cascaded multilevel inverters with the proposed cascaded topology. The ability of the proposed inverter to generate all voltage levels (even and odd) is reconfirmed by using the simulation results of a 15-level inverter and three phase 15-level inverter fed induction mot or. Induction motors are widely used in industries, because they are rugged, reliable and economical. Induction motor drive requires suitable converters to get the required speed and torque without or negligible ripples. The simulation results are presented by using Matlab/Simulink Model.

Index Terms—Basic unit, cascaded multilevel inverter, developed cascaded multilevel inverter, H-bridge, Induction motor.

I. INTRODUCTION

In recent years the energy demand is moving on increasing toward generating power with renewable energy source that may be dispersed in a wide area, and most of them are renewable, as they have greater advantages due to their environmentally friendly nature. The solar can be used by all in universe which doesn't need more investigations of producing electricity. This leads to research in multilevel inverters [1-3]. The multilevel inverters are classified into three types namely: Mr. M. Sai Ganesh Assistant Professor Department of Electrical & Electronics Engineering, Baba Institute of Technology & Sciences, Visakhapatnam (Dt), A.P, India. Mail id: saiganesh.eee@bitsvizag.com

- Diode clamped multilevel inverters;
- Flying capacitor multilevel inverter;
- Cascaded H bridge multilevel inverter.

Of these the cascaded H bridge multilevel inverter topologies give better results. The research goes on increasing to propose a new structure of inverter with reduced semiconductor devices with increased multilevel at the output waveform [4]. This system uses only switches and DC sources. The clamping diode and capacitor are avoided but here they have used 8 switches to produce an output of five-level which is same as that of the conventional one. Though the SPWM technique is implemented the THD is not reduced since the structure of the inverter remains same it fails to achieve the desired THD. Therefore the switching losses remain the same. propose the study of the multi sampled multilevel inverters and their control techniques to improve the performance of the multilevel inverters. This also deals with the different control techniques to be implemented in multilevel inverters in order to reduce the THD [5-7]. But they don't concentrate on the structure of the multilevel inverters.

The cascade inverter has drawn great interest due to the great demand of medium-voltage high-power inverters. The cascade inverter is also used in regenerative-type motor drive applications. Recently, some new topologies of multilevel inverters have emerged. This includes generalized multilevel inverters [8], mixed multilevel inverters, hybrid multilevel inverters [9] and softswitched multilevel inverters [10]. These multilevel inverters can extend rated inverter voltage and power by increasing the number of voltage levels. They can also increase equivalent switching frequency without the increase of actual switching frequency, thus reducing ripple component of inverter output voltage and electromagnetic interference effects. As the multilevel converter is broadly applied in the industries because the demand to operate switching, power converters in high power application has the growth constantly. The capacity of multilevel converters to operate at highvoltages of the AC waveforms has low distortion, highquality and high



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efficiency [11-12]. However, the multilevel converter topology has improved efficiency by using various controls to attain high efficiency and increase to save energy.

In this paper, the topology proposed is three phase fifteenlevel cascaded multilevel H bridge inverter for three phase grid connected system. A fifteen level cascaded multilevel H bridge inverter to reduce the Total Harmonic Distortion (THD)of the inverter output voltages for threephase induction motor system are presented [13].

A multilevel inverter consists of a series of H-bridge inverter units connected to three phase induction motor. The general function of this multilevel inverter is to synthesize a desired voltage from several DC sources. The AC terminal voltages of each bridge are connected in series.



Permitted Turn On and Off States forSwitches in the Proposed Basic Unit

		v				
state	<i>S</i> ₁	<i>S</i> ₂	<i>S</i> ₃	S_4	S_5	v _o
1	off	off	off	off	on	0
2	on	off	on	on	off	$V_1 + V_3$
3	on	on	on	off	off	$V_1 + V_2 + V_3$

Fig. 1 shows the proposed basic unit. As shown in Fig. 1, the proposed basic unit is comprised of three dc voltage sources and five unidirectional power switches. In the proposed structure, power switches (S2, S4), (S1, S3, S4,

S5), and (S1, S2, S3, S5) should not be simultaneously turned on to prevent the short circuit of dc voltage sources. The turn on and off states of the power switches for the proposed basic unit are shown in Table I, where the proposed basic unit is able to generate three different levels of 0, V1 + V3, and (V1 + V2 +V3) at the output. It is important to note that the basic unit is only able to generate positive levels at the output.

It is possible to connect n number of basic units in series. As this inverter is able to generate all voltage levels except V1, it is necessary to use an additional dc voltage source with the amplitude of V1 and two unidirectional switches that are connected in series with the proposed units. The proposed cascaded inverter that is able to generate all levels is shown in Fig. 2(a). In this inverter, power switches S'1 and S'2 and dc voltage source V1 have been used to produce the lowest output level. The amplitude of this dc voltage source is considered V1 = Vdc (equal to the minimum output level). The output voltage level of each unit is indicated by Vo, 1, Vo, 2, ..., Vo, n, and V'o. The output voltage level vo of the proposed cascaded multilevel inverter is equal to

$$v_o(t) = v_{o,1}(t) + v_{o,2}(t) + \dots + v_{o,n}(t) + v'_o(t)$$
 (1)

The generated output voltage levels of the proposed inverter are shown in Table II. As aforementioned and according to Table II, the proposed inverter that is shown in Fig. 2(a) is only able togenerate positive levels at the output.



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Generated Output Voltage Levels Vo Based On the Off And On States of Power Switches

34	31	81	S_{\Box}	8.21	\$17	843	\overline{s}_{32}	512	\$21	811	54.2	542	+++	$\delta_{1,n}$	520	\$3,0	\$4.0	85,
0	eff	UI.	ď	æff	off.	eff	88	ιđ	υŰ.	đŤ	off	UE.		off	$\alpha\overline{f}$	eff	ΰŰ.	.tt
<u>P</u> ₁	on.	off	đ	eff	υff	ıff	01	ŧff	٢ff	sff	off	00		υff	${\rm off}$	eff	vff	н
7 (j + F3)	eff	10	08	eff	а	on.	off	eff	ıff	σī	đĨ	00		off	đ	eff	eff	н
$V_{ij} + V_{jj} + V_{ij}$	eff	18	10	opi	т	off	off	off.	nff	off	off	08	-	off	ať	nff	nff	я
F12+F32	vf	18	đ	वॉ	əff	ŧΠ	78	œ	۶ff	-11	н	đŤ		off	đ	đ	nff	-
1'12+1'22+1'32	vit	08	đ	eff	off	eff	70	an.	0£	=	đť	off		off	ať	eff.	uff	- 11
$V_{13} + V_{12} + V_{13} + V_{13} + V_{23} + V_{23}$	đ	0	08	<i>.</i> 06	-	eff	off	00	.00		.01	eff	j.	off	of	eff	iπ.	-
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1	3	÷	Ŧ	÷	ł	1	4	2	E	्रे	÷	Ð	1	2	1	2	1	÷
$\sum_{j=1}^{n} \theta'_{1,j} * F_{2,j} * F_{3,j}$	eff	in.	m	ie.	m	eff	off	an	m	m	off	aff	-	off	at	eff	eff	in
$y_{ij} + \sum_{j=1}^{N} (\vec{r}_{1,j} + \vec{r}_{2,j} + \vec{r}_{3,j})$	00	đ	or.	.00		ıfī	off	00	m		off	aff		αŤ	đ	eff	đ	

TABLE III Proposed Algorithms and Their Related Parameters

Proposed algorithm	Magnitude of its voltage sources	N _{ini}	V _{o,min}	V _{isiost}	
First proposed algorithm $\left(P_{j}\right)$	$V_{1,j} = V_{2,j} = V_{3,j} = V_{ik}$ for $j = 1, 2,, n$	fie+3	(31+1)V _d	(21n+6)V _é	
Second proposed algorithm (P_2)	$\begin{split} V_{1j} = V_{1j} = V_{2j} = V_{di} \\ V_{1j} = V_{2j} = V_{1j} = V_{di} \\ for \ j = 2, 3, \cdots, n \end{split}$	12e-3	6n-2	(4)a-13)/ _{de}	
Third proposed algorithm $\left(P_{j}\right)$	$\begin{split} & V_{12} = V_{12} = V_{23} = V_{24} \\ & V_{13} = \frac{1}{2} V_{13} = V_{13} = \frac{1}{2} V_{24} = \frac{1}{2} V_{2$	5(3 ^{e-1})+4	$\left[\frac{5(3^{n+1})+3}{2}\right]_{dr}^{p}$	(10) ⁹⁺¹)-79/	
Fourth proposed algorithm $\left(P_{d}\right)$	$V_{1,j} = 0.5V_{2,j} = V_{3,j} = 2^{j-1}V_{ij}$ for $j = 1, 2, -, \pi$	2 ^{#+]} -5	(2** ¹ -3)) _k	(1(2 ⁺⁺²)-22))	

Therefore, an H-bridge with four switches T1–T4 is added to the proposed topology. This inverter is called the developed cascaded multilevel inverter and is shown in Fig. 2(b). If switches T1 and T4 are turned on, load voltage vL is equal to vo, and if power switches T2 and T3 are turned on, the load voltage will be –vo. For the proposed inverter, the number of switches Nswitch and the number of dc voltage sources Nsource are given by the following equations, respectively,

$$N_{\rm switch} = 5n + 6$$
 (2)

$$N_{\text{source}} = 3n + 1$$
 (3)

Where n is the number of series-connected basic units. As the unidirectional power switches are used in the proposed cascaded multilevel inverter, the number of power switches is equal to the numbers of IGBTs, power diodes, and driver circuits. The other main parameter in calculating the total cost of the inverter is the maximum amount of blocked voltage by the switches. If the values of the blocked voltage by the switches are reduced, the total cost of the inverter decreases [12]. Inaddition, this value has the most important effect in selecting the semiconductor devices because this value determines the voltage rating of the required power devices. Therefore, in order to calculate this index, it is necessary to consider the amount of the blocked voltage by each of the switches. According to Fig. 2(b), the values of the blocked voltage by switches are equal to

$$V_{S'1} = V_{S'2} = V_{1,1} \tag{4}$$

$$V_{S1,j} = V_{S3,j} = \frac{V_{1,j} + V_{2,j} + V_{3,j}}{2}$$
(5)

$$V_{S4,j} = V_{S2,j} = V_{2,j} \tag{6}$$

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$$V_{S5,j} = V_{1,j} + V_{2,j} + V_{3,j}_{(7)}$$
$$V_{T1} = V_{T2} = V_{T3} = V_{T4} = V_{o,\max}$$
(8)

Where Vo, max is the maximum amplitude of the producible output voltage. Therefore, the maximum amount of the blocked voltage in the proposed inverter Vblock is equal to



Fig. 3. Cascaded multilevel inverters. (a) Conventional cascaded multilevel inverter R2 for V1 = V2 = ··· = Vn = Vdc, R3 for V1 = Vdc, V2 = ··· = Vn = 2Vdc [12], and R4 for V1 = Vdc, V2 = ··· = Vn = 3Vdc. (b) Presented topology, with R7 for V1 = V2 = ··· = Vn = Vdc. (c) Presented topology, with R8 for V1 = V2 = ··· = Vn = Vdc and R9 for V1 = Vdc, V2 = ··· = Vn = 2Vdc. (d) Presented topology with R10. (e) Presented topology with R6 for V1 = V2 = ··· = Vn = Vdc. (f) Presented topology with R5 for V1 = V2 = ··· = Vn = Vdc. (f) Presented topology in [13], with R1 for V1 = V2 = ··· = Vn = Vdc.

In (9), Vblock, j, Vblock , and Vblock, H indicate the blocked voltage by the jth basic unit, the additional dc voltage sources, and the used H-bridge, respectively. In the developed inverter, the number and maximum amplitude of the generated output levels are based on the value of the used dc voltage sources. Therefore, four different algorithms are proposed to determine the magnitude of the dc voltage sources. These proposed algorithms and all their parameters are calculated and shown in Table III. According to the fact that the magnitudes of all proposed algorithms except the first algorithm are different, the proposed cascaded multilevel inverter based on these algorithms is considered an asymmetric cascaded multilevel inverter. In addition, based on the equations of the maximum output voltage levels and its maximum amplitude, it is clear that these values in the asymmetric cascaded multilevel inverter are more than those in the symmetric cascaded multilevel inverter are sources and power switches.

III. COMPARING THE PROPOSED TOPOLOGY WITH THE CONVENTIONAL TOPOLOGIES

The main aim of introducing the developed cascaded inverter is to increase the number of output voltage levels by using the minimum number of power electronic devices. Therefore, several comparisons are done between the developed proposed topology and the conventional cascaded inverters from the numbers of IGBTs, driver circuits, and dc voltage sources points of view. In addition, the maximum amount of the blocked voltage by the power switches is also compared between the proposed inverter and the other presented topologies. In this comparison, the proposed cascaded inverter that is shown in Fig. 2(b) with its proposed algorithms is represented by P1 to P4, respectively. In [13], a symmetric cascaded multilevel inverter has been presented that is shown by R1 in this comparison. The Hbridge cascaded multilevel inverter has been presented. This inverter is represented by R2. In addition, two other algorithms have been presented for the H-bridge cascaded inverter in [12] and that are represented by R3 and R4, respectively. In, three other symmetric cascaded multilevel inverters have been presented.



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Fig. 4. Cascaded 15-level inverter based on the proposed basic unit.

These inverters are shown by R5-R7, respectively. The other cascaded multilevel inverter with two different algorithms has been presented. This inverter with its algorithms is represented by R8 and R9, respectively. Another symmetric cascaded multilevel inverter that has been presented is represented by R10 in this comparison. Fig. 3 indicates all of the aforementioned cascaded multilevel inverters. In this section, the investigations are done on a cascaded multilevel inverter that is shown in Fig. 4. This inverter consists of two proposed basicunits and one additional series-connected dc voltage source that lead to the use of 7 dc voltage sources and 12 unidirectional power switches. The first proposed algorithm is considered to determine the magnitude of the dc voltage sources with Vdc =20 V. According to (5), this inverter is able to generate 15 levels (seven positive levels, seven negative levels, and one zero level) with the maximum amplitude of 140 V at the output.

It is important to note that the load is assumed as a resistive-inductive (R-L) load, with R=70 Ω , and L=55 mH. It is important to point out that the used control method in this inverter is the fundamental control method. The main reason to select this control method is its low switching frequency compared with other control methods that leads to reduction in switching losses.

IV.INDUCTION MOTOR

Induction Motor (1M) An induction motor is an example of asynchronous AC machine, which consists of a stator and a rotor. This motor is widely used because of its strong features and reasonable cost. A sinusoidal voltage is applied to the stator, in the induction motor, which results in an induced electromagnetic field. A current in the rotor is induced due to this field, which creates another field that tries to align with the stator field, causing the rotor to spin. A slip is created between these fields, when a load is applied to the motor.

Compared to the synchronous speed, the rotor speed decreases, at higher slip values. The frequency of the stator voltage controls the synchronous speed [12]. The frequency of the voltage is applied to the stator through power electronic devices, which allows the control of the speed of the motor. The research is using techniques, which implement a constant voltage to frequency ratio. Finally, the torque begins to fall when the motor reaches the synchronous speed. Thus, induction motor synchronous speed is defined by following equation,

$$n_s = \frac{120f}{p}$$

Where f is the frequency of AC supply, n, is the speed of rotor; p is the number of poles per phase of the motor. By varying the frequency of control circuit through AC supply, the rotor speed will change.



V.MATLAB/SIMULATION RESULTS



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Fig.6.Matlab/Simulation Model Of Cascaded 15-Level Inverter Based On The Proposed Basic Unit.



Fig.7.Proposed Basic Unit 1 of Voltage (Vo1).



Fig.8.Proposed Basic Unit 2 of Voltage (Vo2).



Fig.9.Output Voltage of Vo'.





Fig.11.Output Voltage and Current of Fifteen Level Inverter.



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Fig.13. current, speed and Torque of 3 Phase MLI connected with induction motor drive.

VI. CONCLUSION

In this paper, a cascaded multilevel inverter based on a new basic unit is proposed. The proposed unit is only able to generate positive levels at the output. Therefore, in order to generate all voltage levels (positive and negative) the H-bridge is added to the proposed topology. The proposed inverter has the advantages of reducing the number of switches and gate drives circuits by 25 % compared with the conventional Multi-level inverter. Therefore, the proposed inverter exhibits the merits of simplified gate drive, low cost compared to the other topologies for the same number of phase voltages levels.A Three-Phase Cascaded Multilevel Inverter Based on a New Basic Unit with Reduced Number of Power Switches.A three phase Cascade H-Bridge Inverter is designed and implemented practically. The components used in the practical implementation of H-Bridge Inverter are described. The drive system can be used in industries where adjustable speed drives are required to produce output with reduced harmonic content. The simulation results of voltage, current, speed and spectrum are presented.

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