



Design and Implementation of MPC-SVM Method for Vienna Rectifier with PMSG

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ABSTRACT: *In this paper to design and implement the permanent magnet synchronous generator (PMSG) based wind energy conversion system (WECS) using with an Vienna rectifier. To combined with grid with two back to back connected converters with a common DC link. The permanent magnetic synchronous generator (PMSG) which feeds alternating current (AC) power to the utility grid connection. In this paper a learning of WECS is done by using a constant speed direct using MATLAB software. Even that dc link voltage at its reference value, the output ac voltage of the inverter can be kept constant. An effective control techniques to extract grid side controller also called voltage and current controller, three phase transformer.*

KEYWORDS- Permanent magnet synchronous generator (PMSG), wind energy conversion system (WECS), converter using MOSETs based

I. INTRODUCTION

The world consumption of energy has known enormous increase these last years, because of the massive industrialization that has tendency to intensify rapidly in some geographical areas in the world, notably in countries of Asia. The risks of shortage of fossil matters and their effects on the climatic change indicate once more the importance of renewable energies. Several sources of renewable energies are under exploitation and search, in order to develop power extraction techniques aiming to improve the reliability, lower the costs (of manufacture,

use, and retraining), and to increase the energizing efficiency [1]. In this general context, wind energy is one of the most promising renewable energy resources for producing electricity due to its cost competitiveness compared to other conventional types of energy resources. It takes a particular place to be the most suitable renewable energy resources for electricity production.

In wind energy conversion systems, normally there are two operating modes of wind turbine generators system: fixed speed and variable speed operating modes. In order to extract maximum power wind, the turbine rotor speed needs to be changed proportional to wind speed. This requires variable-speed operation. Most modern wind turbine generators are designed for variable speed operation [2]. Compared with fixed speed operation, variable speed systems offer some advantages including overall efficiency, reduced mechanical stresses and audible noise at low wind speed. In recent years, numerous topologies of power conditioning systems, varying in cost and complexity, have been developed for integrating PMSG wind turbine systems into the electric grid. In modern PMSG wind turbine generators system designs, the power conditioning systems is typically built using a full-scale power converter made up of a two-stage power conversion hardware topology that meets all the constraints of high quality electric power, flexibility and reliability imposed for applications of modern distributed energy resources [3], [4]. This power conditioning systems design is composed of a back-to-back converter that enables to control simultaneously and independently the active and reactive power flows exchanged with the electric grid, as described in Fig. 1.

Many control methods for the Vienna rectifier have been proposed. In the Vienna rectifier, one of the main control aims is to make the input currents to have sinusoidal waveforms. The hysteresis current control method is used and it is a classic control method. The switching set is determined by the rule defined from the hysteresis current control.

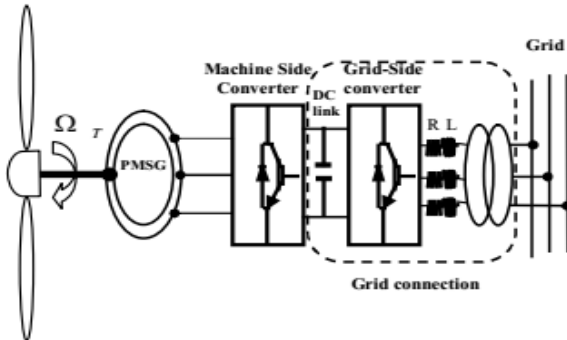


Fig.1. Typical configuration of PMSG based variable speed wind energy conversion system

The classic linear controllers such as the proportional integral controller are used and the switching set is generated by comparing the reference voltages with the carrier voltages or by the space vector modulation method. The aforementioned control methods have been widely used in other topologies such as two-level converter and three-level converter. The Direct Torque Control (DTC) method and the Model Predictive Control (MPC) method with cost function have been proposed for the applications using a motor or generator. Research on the DTC and MPC methods at two-level converter, three-level converter, and matrix converter are being carried out consistently. Recently, DTC method for the Vienna rectifier was proposed.

Disadvantages:

Neutral-point voltage unbalancing problem
Variation of the power factor

1) Continuous- and discrete-time modeling of power converters and WECS

The optimal control actions of the predictive control strategy are mainly based on the model of the system. A poor modeling of the system will lead to an inferior control performance. The continuous-time models should

be converted to discrete-time with a suitable method such that control delay and prediction horizon can be incorporated. In this work, the third objective is set to accurately model different control variables in terms of converter switching states.

2) Performance improvement of predictive control strategy

Despite many best features of FCS-MPC strategy, several challenges are reported in the state-of-the-art literature. A few examples include: weighting factors selection, control delay compensation, accurate extrapolation of reference control variables, variable switching frequency nature, prediction of variables over two or more samples with reduced computational burden, and enhancement of robustness against perturbations in the system model. In this paper, the next objective is defined to address the above challenges, and to promote the FCS-MPC strategy as the one of the next generation control tools.

3) Development of generalized control strategy for multilevel diode-clamped converters (MLDCCs)

In this work, 3L and 4L converters are proposed for the MW-WECS, and thus the control scheme developed for one converter should work for the other, too. In classical control (which is a mature subject matter), many works have been presented to generalize the control of load current, dc-link capacitor voltages and common-mode voltage in MLDCCs. But in the current predictive control research area, this issue is not addressed yet.

4) Development of efficient controllers for the grid-tied MLDCCs

The grid-tied MLDCCs play a crucial role in dispatching wind power and also to meet grid codes. The control techniques for the grid-side converter should perform multiple tasks to ensure proper and reliable operation of WECS. The next objective is specified to design efficient controllers such that grid-tied MLDCC control requirements such as net dc-bus voltage/grid active power control, reactive power generation to meet grid operator request, dc-link capacitor voltages balancing, and lower

switching frequency operation can be fulfilled simultaneously.

5) Design of decoupled control system for the PMSG-WECS

In order to achieve decoupled operation for the generator and grid-side converters, the control systems should be properly designed. In addition to the aforementioned grid-side control requirements, the MPPT operation should be performed by the generator-side converter. The control systems should generate reference control variables in order for the WECS to operate at higher efficiency. The next objective of this work is the design and implementation of sophisticated control systems for efficient operation of three-level and four-level converter-based WECS.

6) LVRT enhancement for the proposed WECS using FCS-MPC strategy

The state-of-the-art LVRT solutions for PMSG-WECS include pitch control system, over sizing of dc-link capacitors, dissipation of surplus energy in dc-link crowbar (resistor), storage of surplus energy in the battery banks and fly-wheel systems, use of power quality conditioning devices. The surplus energy can be stored in the mechanical system inertia during the grid voltage dips, and this issue is previously analyzed with CSC and NPC converters, and with classical control techniques. The complete WECS response with passive generator-side converters has not been explored yet. The last objective is defined to develop a FCS-MPC control system such that the power converters operate in a safe mode (by maintaining constant dc-bus voltage), while meeting the grid code requirements.

II. PROPOSED STRATEGY

This project proposes the MPC method for the Vienna rectifier used in WTS with a Permanent Magnet Synchronous Generator (PMSG). The proposed MPC method considers the feasible eight voltage vectors of the Vienna rectifier; moreover, the additional voltage vectors, which are the center voltage vectors of two feasible adjacent voltage vectors, are taken into consideration to improve the performance of the MPC method. In the proposed MPC method, the errors in d/q-

axis current are predicted based on model of the PMSG, and then, the optimized voltage vector is selected by cost function for the current ripple minimization. Additionally, from the optimized voltage vector, N-type and P-type voltage vectors, which give the different effect on the neutral-point voltage, are considered in selecting the final switching set to solve the neutral-point voltage unbalancing problem. The final switching set is generated by the Space Vector Modulation (SVM) method.

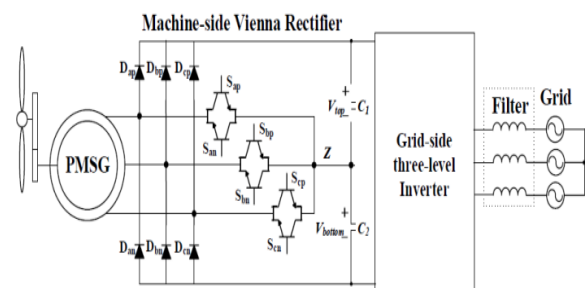


Fig. 2 : Proposed system of Vienna rectifier

Advantages:

- Ripple minimization of PMSG currents
- No neutral-point voltage unbalancing problem

Applications:

- Telecommunication systems
 - Wind turbine systems (WTS)
- Simulation parameters are as listed are:

The parameters are designed to get the output of desired levels. Simulation time is 5 μ S and switching frequency or frequency of repetitive sequence is 50 KHz for various input voltages the output is the value for wind power generation and we get varying the input voltage.

In the three phase three switch level is called Vienna rectifier has been applied mostly as power supply. The Vienna rectifier can generate three phase voltage levels with power switches to control. In low power and low cost applications, the AC conversion is a diode bridge rectifier with capacitor and their voltage filter. For high power applications, the sinusoidal current must be active shaped by using either a type front-end converter or at the input. As wind generators as a energy source became used in this mode. Based on generator generates the variable three phase AC input voltage. In the three switch three

phase and three levels VIENNA rectifier in the interfaces. The Vienna rectifier consists of three switches MOSFETs; It converts the AC voltage into control output voltage. It can also provide sinusoidal input currents and control output voltage. The AC voltage from the three phase generator is given to the Vienna rectifier. The current flows through the three MOSFETs and the capacitors in the fully charged it. The phase current rises, through a MOSFETs, during that pulse period, charge the capacitor. When the MOSFETs is turned off, current through the diode upper or lower depending on direction of the current flow. By adjust the width of the pulse that turns ON the MOSFETs, corresponding line current is forced to be sinusoidal and in phase with the Voltage. When the MOSFETs is turned ON the corresponding phase is connected the line inductor, to the center point between the two output capacitors.

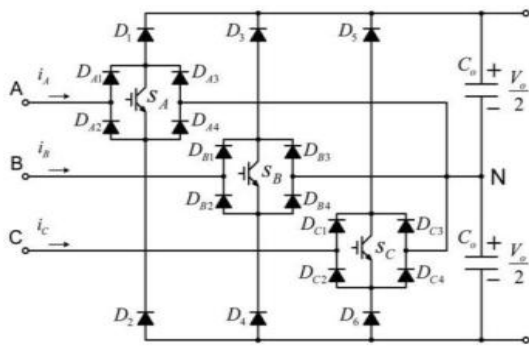


Fig. 3 Vienna rectifier

Table 1: List Of Simulation Parameters And Its Values

Parameter	Symbol	Value
Simulation time	Ts	5µF
Inductance	L	220mH
Load Capacitance	C	1000Nf
Resistor	R	500KΩ
Three phase Input Voltage	V _{in}	100-420V
Input Frequency	F	50HZ

III. SIMULATION RESULTS

The given simulation Output result gives us power factor input voltage and current across the capacitor, finally output.

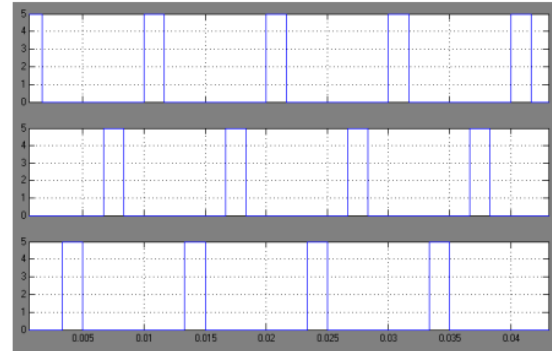


Fig.

4 : Three Phase Switching Waveform

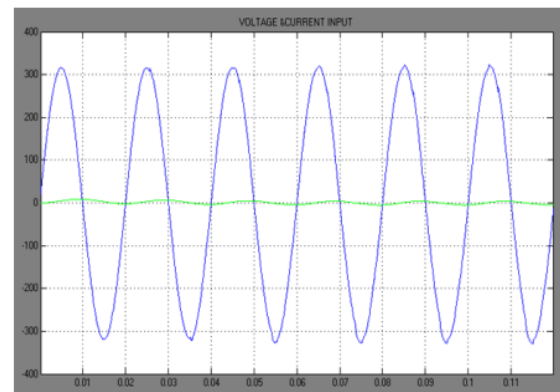


Fig. 5 : Phase A Input Voltage And Current Waveform

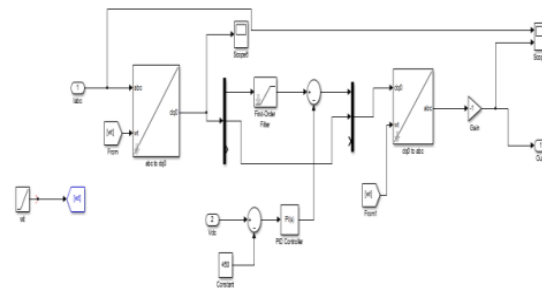


Fig. 6 : Synchronous Reference Frame Based Reference Current Generation

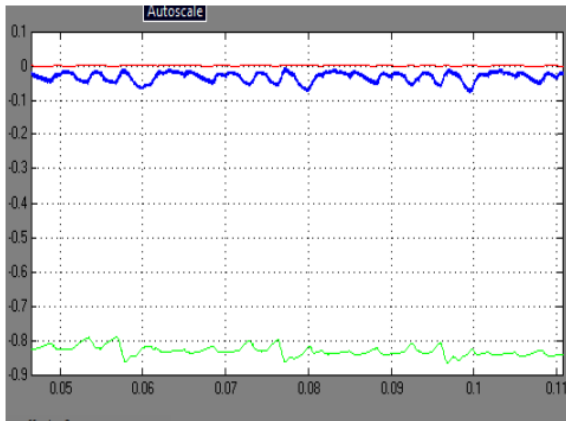


Fig. 7 : Reference Current Waveform

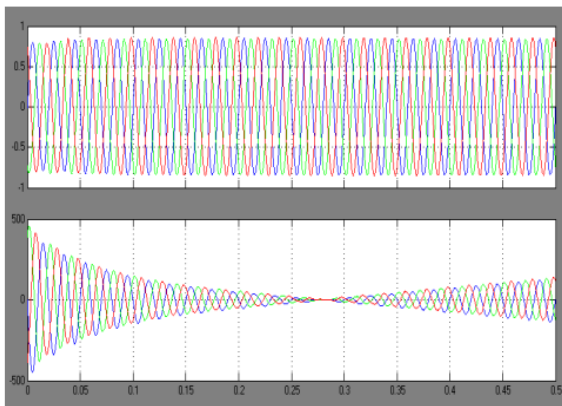


Fig. 8 : Reference Voltage And Current Generation

IV. CONCLUSION

To study the control strategies and designs the simulation of system PMSG in AC power to the utility grid in Matlab. The simulation results display that the AC to connected the DC capacitor link output. DC-link voltage is kept at stable level for control of active and reactive power. Henceforth, the output will get the power supply for the systems.

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