

Enhancing Downlink Performance in Wireless Networks

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ABSTRACT: In this paper we consider using simultaneous Multiple Packet Transmission (MPT) to improve the downlink performance of wireless networks. We also give analytical bounds for maximum allowable arrival rate which measures the speedup of the downlink after enhanced with MPT and our results show that the maximum arrival rate increases significantly even with a very small compatibility probability. We also use an approximate analytical model and simulations to study the average packet delay and our results show that packet delay can be greatly reduced even with a very small compatibility probability

KEYWORDS- Multiple packet transmission, wireless LAN, matching, approximation algorithm, maximum allowable arrival rate, delay Multiple packet transmission, wireless LAN, matching, approximation algorithm, maximum allowable arrival rate, delay.

I. INTRODUCTION

Traditionally, in wireless networks, it's miles assumed that one device can send to simplest another device at a time. However, this restrict is not proper if the sender has greater than one antennas. By processing the records in keeping with the channel state, the sender could make the records for one user seem as zero at other users such that it can send wonderful packets to wonderful users concurrently. We call it Multiple Packet Transmission (MPT) and will explain the info of it in Section 2. For now, we need to point out the profound effect the MPT technique has on wireless LANs. A wireless LAN is typically composed of an Access Point (AP) that is linked to the stressed out community and numerous users which communicate with the AP via wi-fi channels. In wireless LANs, the maximum commonplace type of traffic is the downlink visitors, i.e., from the AP to the users whilst the users are browsing the Internet and downloading data. In these

days' swi-fi LAN, the AP can send one packet to at least one person at a time. However, if the AP has two antennas and if MPT is used, the AP can ship two packets to 2 users every time viable, for this reason doubling the at some point of of the downlink in the suitable case. MPT is feasible for the downlink because it is not difficult to equip the AP with two antennas, in fact, many wireless routers today have two antennas. Another advantage of MPT which makes it very commercially appealing is that although MPT needs new hardware at the sender, it does not need any new hardware at the receiver. This means that to use MPT in a wireless LAN, we can simply replace the access point and upgrade software protocols in the user devices without having to change their wireless cards, and thus incurring minimum cost.

In this paper we study problems related to MPT and provide our solutions. We formalize the problem of sending out buffered packets in minimum time as finding a maximum matching in a graph. Since maximum matching algorithms are relatively complex and may not meet the speed of real time applications, we consider using approximation algorithms and present an algorithm that finds a matching with size at least $3/4$ of the size of the maximum matching in $O(|E|)$ time where $|E|$ is the number of edges in the graph. We then study the performance of wireless LAN enhanced with MPT and give analytical bounds for maximum allowable arrival rate. We also use an analytical model and simulations to study the average packet delay.

Enhancing wireless LANs with MPT requires the Media Access Layer (MAC) to have more knowledge about the states of the physical layer and is therefore a form of cross-layer design. In recent years cross-layer design in wireless networks has attracted much attention because of the great benefits in breaking the layer boundary. For example, [5, 6] considered packet scheduling and transmission power control in cross-layer wireless networks. However, to the best of our

knowledge, packet scheduling in wireless networks in the context of multiple packet transmission has not been studied before. [3, 4] have considered Multiple Packet Reception (MPR) which means the receiver can receive more than one packets from distinct users simultaneously. MPR is quite different from MPT since MPR is about receiving multiple packets at one node while MPT is about sending multiple packets from one node to multiple nodes.

II. BACKGROUND WORKS

The AP keeps the record for the channel coefficient vectors of all nodes that have been reported to it previously. If, based on the past channel coefficient vectors, U1 and U2 are likely to be compatible and there are two packets that should be sent to them, the AP sends out a Require To Send (RTS) packet, which contains, in addition to the traditional RTS contents, a bit field indicating that the packet about to send is an MPT packet. If U1 appears earlier than U2 in the destination field, upon receiving the RTS packet, U1 will first reply a Clear To Send (CTS) packet containing the traditional CTS contents plus its latest channel measurements. After a short fixed amount of time, U2 will also reply a CTS packet. After receiving the two CTS packets, the AP will update their channel coefficient vectors. It will then decide whether U1 and U2 are still compatible, and if so, the

AP will send two packets to them. In the rare case that the channels have changed significantly such that they are no longer compatible, the AP can choose to send to only one node. Therefore, before sending the data packets, the AP first sends 2 bits in which bit i is "1" means the packet for U_i will be sent. After the data packet is sent, U1 and U2 can reply an acknowledgment packet in turn.

III. PROPOSED WORK

The simplest and most well known approximation algorithm for maximum matching simply returns a maximal matching. It is known that this simple algorithm has $O(|E|)$ time complexity where $|E|$ is the number of edges in the graph and has a performance ratio of $1/2$, which means that the matching it finds has size at least half of M^* where M^* denotes the maximum matching. In this section we give a simple $O(|E|)$ approximation algorithm for maximum matching with an improved ratio of $3/4$. To the best of

our knowledge it is the first linear time approximation algorithm for maximum matching with $3/4$ ratio.

A. Eliminating Augmenting Paths of Length 3

We start with a maximal matching denoted by S and the output of our algorithm is denoted by M . For each vertex, a list is used to store its neighbors. An array is used to store the matching, that is, the i th element in the array is the vertex matched to the i th vertex. Note that with this array, it takes constant time to augment the matching with fixed length augmenting paths or to check whether a particular vertex is saturated or not. The algorithm is summarized in Table 1. Initially, let $M = S$. We will check edges in S from the first to the last to augment M . When checking edge (u, v) , we check whether both u and v are adjacent to some distinct unsaturated vertices.

Table 1. Finding Augmenting Paths of Length 3

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Initially,  $M = S$  where  $S$  is a maximal matching.
for  $i = 1$  to  $|S|$  do
  Let  $(u, v)$  be the  $i^{th}$  edge in  $S$ .
  Check if  $u$  and  $v$  have distinct unsaturated neighbors.
  if yes
    Let the neighbors of  $u$  and  $v$  be  $x$  and  $y$ , respectively.
     $M \leftarrow M \cup \{(x, u), (v, y)\} \setminus \{(u, v)\}$ .
  end if
end for
```

If there are such vertices, say, u is adjacent to x and v is adjacent to y , there is an M -augmenting path of length 3 involving (u, v) which is $x - u - v - y$. We can eliminate this augmenting path and augment M by removing (u, v) from M and adding (u, x) and (v, y) to M . We call (u, x) and (v, y) the new matching edges. The algorithm terminates when all edges in S have been checked this way.

B. Eliminating Augmenting Paths of Length 5

After eliminating augmenting paths of length 3, we search for augmenting paths of length 5. We first check all edges in the current matching to construct a set T . A vertex v is added to set T if v is matched to some vertex u and u is adjacent to at least one unsaturated vertex. We call v an "outer vertex" and u an "inner vertex." Note that v can be both an outer vertex and an inner vertex when v and u are both adjacent to the same unsaturated vertex and are not adjacent to any other unsaturated vertices. Clearly, to find augmenting paths of length 5 is to find adjacent outer vertices. Also note that T can be constructed in $O(|E|)$ time. The algorithm is summarized in Table 2

and works as follows. We check the vertices in T from the first to the last. When checking vertex v , let u be the inner vertex matched to v . We first get or update $l(u)$ which is the list of unsaturated neighbors of u : If $l(u)$ has not been established earlier, we search the neighbor list of u to get $l(u)$; otherwise, we check the vertex in $l(u)$ (in this case, there can only be one vertex in $l(u)$, for reasons to be seen shortly) and remove it from $l(u)$ if it has been matched. After getting $l(u)$, if $l(u)$ is empty, we quit checking v , remove v from T and go onto the next vertex in T . Otherwise, we check the neighbors of v to find an outer vertex.

Table 2. Finding Augmenting Paths of Length 5

```

Construct  $T$ , the set of outer vertices.
while  $T$  is not empty
  Let  $v$  be a vertex in  $T$  that has not been checked.
  Suppose  $v$  is matched to  $u$ . Get or update  $l(u)$ ,
  the unsaturated neighbor list of  $u$ .
  if  $l(u)$  is empty
    Remove  $v$  from  $T$  and continue to the next outer
    vertex in  $T$ .
  end if
  while not all neighbors of  $v$  have been checked
    Let  $w$  be an outer vertex neighbor of  $v$  and suppose
     $w$  is matched to  $z$ .
    Get or update  $l(z)$ , the unsaturated neighbor list of  $z$ .
    if  $l(z)$  is empty
      Remove  $w$  from  $T$  and continue to the next
      neighbor of  $v$ .
    end if
    Based on  $l(u)$  and  $l(z)$ , determine if there is a
    length-5 augmenting path.
    if an augmenting path is found
      Augment  $M$  according to this path and
      remove both  $v$  and  $w$  from  $T$ ;
      break from the inner while loop.
    end if
  end while
  if no augmenting path is found
    Remove  $v$  from  $T$ 
  end if
end while

```

If an outer vertex w is found to be adjacent to v , let z be the inner vertex matched to w . We get $l(z)$ which is the unsaturated neighbor list of z in the same way as for u . If $l(z)$ is empty, we remove w from T and go on to the next neighbor of v . Otherwise, we check if there is an augmenting path of length 5 involving (u, v) and (w, z) , and note that this can be in constant time. This is because (1) if $l(z)$ contains at least 2 vertices, there must be such a path; (2) if $l(z)$ contains exactly 1 vertex, there is such a path if and only if $l(u)$ is different from $l(z)$. If an augmenting path is found, we augment M according to this path and remove both v

and w from T ; otherwise, we continue to check the next outer vertex neighbor of v . If all neighbors of v have been checked and no augmenting path is found, we remove v from T and continue to the next vertex in T . Now we can see why if an outer vertex is still in T after it has been checked, the unsaturated neighbor list of the inner vertex matched to it must contain exactly one vertex. This is because if it contains more than 1 vertex, an augmenting path must have been found when checking this outer vertex and it would have been removed from T . The algorithm terminates when T is empty. Note that this algorithm makes sure that it will find an augmenting path of length 5 involving (u, v) if such a path exists when checking outer vertex v . Also note that removing an element in a set is equivalent to marking this element which takes constant time.

IV. PERFORMANCE STUDY

The performance of a wireless network depends on many factors, for example, the physical environment, the locations of the wireless nodes, etc., such that the performance of one network could be different from that of another even when they are using the same devices. In many cases the performance of the same network may also be changing due to the occasional movements of the wireless nodes. This makes the performance evaluation in general a difficult job. However, we note that the performance gain of adopting MPT is mainly determined by the probability of two nodes being compatible, and this probability should be the same in networks under similar environments and with same devices.

A. Maximum Arrival Rate

The first and the most important question is: After using MPT, how much faster does the downlink become? This can be measured by the maximum allowable arrival rate, where an arrival rate is allowable if it does not cause the buffer of the AP to overflow. More specifically, suppose once the AP has got access to the media, on average it has to wait T seconds to be able to get access to the media again. In the following, for convenience, we refer to T as a time slot.

B. Average Packet Delay

As we have seen, adopting MPT can greatly increase the maximum allowable arrival rate. Note that MPT can also reduce the queuing delay of the packets comparing to Single Packet Transmission (SPT).

V. CONCLUSION

We studied the performance of wireless LAN after enhanced with MPT. We gave analytical bounds for maximum allowable arrival rate which measures the speedup of the downlink and our results show that the maximum arrival rate increases significantly even with a very small compatibility probability. We also used an approximate analytical model and simulations to study the average packet delay and our results show that packet delay can be greatly reduced even with a very small compatibility probability.

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