

Fuzzy Logic Controller based Interleaved PFC Power Factor Correction with Output Voltage

B.Himabindu & M.Purushothm

¹PG Scholar, SHREE Institute of Technical Education, Tirupati, Andhra Pradesh, India.

²Associate.Prof & HOD, SHREE Institute of Technical Education, Tirupati, Andhra Pradesh, India.

Abstract: A power factor Correction (PFC) usually serves as the first stage of active two-stage AC/DC converters in a variety of applications including inductive heating systems, wireless charging systems, and onboard chargers for plug-in electric vehicles (PEVs). Conventionally, boost-type PFCs are utilized to regulate the DC-link voltage at a fixed voltage; however, a variable DC-link voltage can enhance the overall efficiency of the converters. In this paper, Fuzzy Logic Control based interleaved PFC converter with coupled inductors is proposed as the PFC stage for two-stage AC/DC converters. The converter is designed to operate in discontinuous conduction mode (DCM) in order to achieve soft switching for switches and diodes. The directly coupled inductors are utilized to reduce the number of magnetic components and decrease the input current ripple. A 500W FLC Based interleaved PFC Converter is designed to verify the benefits of this converter. The MATLAB/SIMULINK results show that the converter can maintain high efficiency over a wide range of DC-link voltage and input power factor maintaining approximately at unity.

Keywords—Power factor Correction (PFC), single ended primary inductor converter (PFC), discontinuous conduction mode (DCM), coupled inductors, interleaved converter, Fuzzy Logic Control (FLC).

I. INTRODUCTION

To improve the power quality of the grid, high power factor (PF) and low total harmonics distortion (THD) are required for the grid-connected AC/DC converters. Nowadays, two-stage active AC/DC converters have been widely used in a variety of applications such as onboard chargers for plug-in electric vehicles (PEVs), inductive heating systems, and wireless charging systems [1]-[3]. The two-stage AC/DC converters are typically composed of a PFP stage followed by an isolated DC/DC stage, as shown in Fig. 1 [1]. A DC/DC resonant converter is usually selected as the second stage due to its attractive features such as soft switching, galvanic isolation, and high efficiency near resonant frequency. AC/DC PFP Converter Vgrid Isolated DC/DC Converter DC Load DC Link Bus Capacitors DSP Controllers

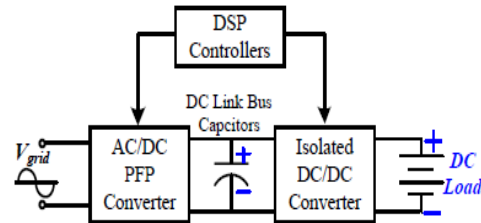


Fig. 1. Typical structure of two-stage active AC/DC converters.

The objective of PFP stage is to improve power quality and reduce harmonic contamination. The topology for the PFP stage is a diode bridge followed by a boost-type converter [1]. Although the boost-type PFP converters can provide efficiencies over 98% [4]-[5], the overall efficiency of the two-stage converter is reduced significantly if the second-stage resonant converter cannot operate near the resonant frequency.

In the application of onboard battery chargers for PEVs, as shown in Fig. 2, a LLC resonant converter stage follows a boost-type PFP stage [6]-[8]. The output voltage of the LLC converter is regulated by pulse frequency modulation. The resonant frequency is the optimal operation frequency associated with the highest efficiency. The operating frequency of the LLC converter moves away from the resonant frequency when the battery voltage is lower than the rated voltage at a lower state of charge (SOC). Consequently, the efficiency of the LLC converter drops significantly. To achieve the highest possible efficiency, i.e. ensure operation at resonant frequency, the input voltage of the LLC converter can be regulated to follow the output battery voltage [9]-[11]. Due to the wide variation of the battery pack, the DC-link voltage should be regulated over a wide range and sometimes become less than the PFP's input voltage [12], [13]. However, the output voltage of boost-type topologies cannot be lower than the input voltage.

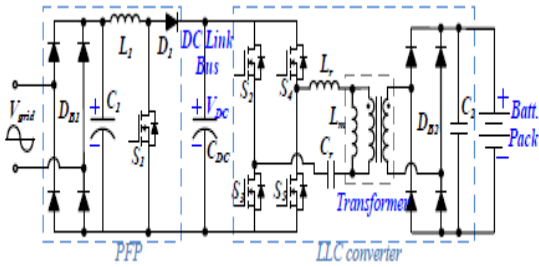


Fig. 2. Two-stage battery charger system.

Additionally, the boost-type PFPs are not the most suitable topologies for inductive heating applications, where the high frequency AC magnetic field should be generated to deliver power over a distance by a subsequent resonant converter stage [3]. A wide output voltage variation is required in this application due to a need for variable power levels for heating. Similar to onboard charger application, a fixed DC-link voltage would result in lower overall efficiency particularly in light loads by using a resonant DC/DC converter stage controlled by pulse frequency modulation. For such applications, a PFP stage capable of providing a wide regulated DC-link voltage, such as a single-ended primary-inductor converter (PFC) PFP, can improve the overall efficiency of the systems to a great extent.

The PFC topology, shown in Fig. 3, has been investigated as the PFP in AC/DC converters in various applications including standalone photovoltaic systems and LED lighting systems [14]-[23]. In a PFC PFP, the output voltage can be either higher or lower than the input voltage. The voltage and current stresses of diodes and switches, in a traditional PFC converter, are much higher than a boost-type topology at the same power level. Thus, the traditional PFC topology is not widely used for high power applications [24]. The bridgeless PFC PFP converters have been investigated to reduce the conduction loss of the diode bridge in [15]-[18]. However, the voltage and current stresses of switches are not reduced, and the power level is usually limited to less than 150W, due to voltage and current limitations of switches in the orders of 300V and 10A, respectively. In addition, in the continuous conduction mode (CCM), the PFC converters have large hard-switching losses, especially in high frequency operation. Therefore, the efficiencies are low for a traditional PFC converter operated in CCM. In [3], the power level is increased by interleaving two PFC converters. However, this topology is constructed by directly paralleling two traditional PFC converters, and consequently the input current ripple is large in discontinuous conduction mode (DCM) operation.

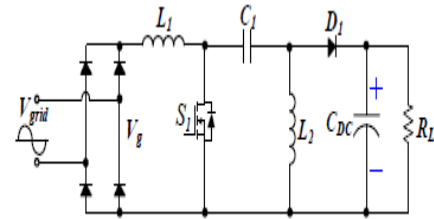


Fig. 3. Traditional PFC PFP converter.

In this paper, a two-phase interleaved PFC AC/DC converter with coupled inductors is proposed to serve as the PFP stage with a wide range of output DC-link voltage. Its topology is shown in Fig. 4. The input power is shared evenly between two phases to reduce the current stresses of the switches and diodes; and consequently, the power level can be increased. Since the CCM operation causes large switching losses, the DCM operation is selected to enable soft switching. The ZVS can be realized for the MOSFET's to reduce the switching losses, while the ZCS can be realized for diodes, $D1$ and $D2$, to eliminate reverse recovery losses [14]. In order to reduce the number of magnetic components, the corresponding inductors in two phases are directly coupled. The input current ripple could be significantly reduced through proper design of the coupled inductors.

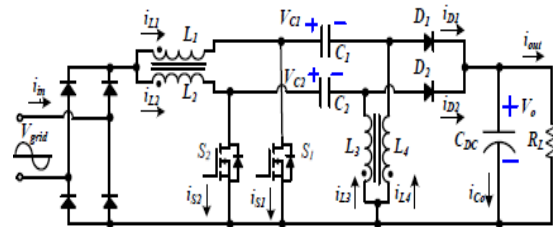


Fig. 4. Proposed interleaved PFC PFP converter.

This paper is organized as follows. The principle of operation is presented in Section II. The theoretical analyses are elaborated in Section III. Furthermore, experimental results of a 500W prototype are demonstrated in Section IV for validation of the analyses. Finally, Section V concludes the manuscript.

II OPERATION PRINCIPLE

In Fig. 4, the rectified voltage after the diode bridge can be modeled as an equivalent variable DC source V_g . Assuming that the DC-link capacitor C_{DC} and two middle capacitors $C1$, $C2$ are large enough and their voltage ripples are negligible compared with their steady-state voltages. The output capacitor can be modeled with an equivalent DC source V_o . Since the middle capacitors $C1$ and $C2$ have the same steady-state voltages as the input rectified voltage V_g , the two middle capacitors can be

modeled as the equivalent variable DC source V_g [24], as shown in Fig. 5.

The analyses are separated into the higher output voltage case and the lower output voltage case as the output voltage of a PFC converter can be either higher or lower than the input peak voltage. These two cases are analyzed in this section using the derived equivalent model.

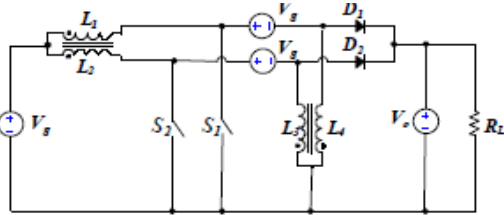


Fig 5. Equivalent circuit of the proposed interleaved PFC converter.

A. Lower Output Voltage Case

The output voltage of PFP stage can be lower than the input peak voltage. In DCM operation, the duty cycle is less than 0.5, and it is also less than the duty cycle derived in CCM operation with the same output voltage [24].

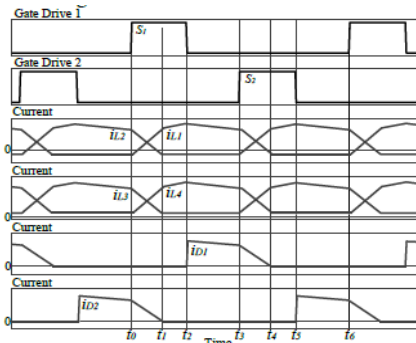


Fig 6. Typical waveforms of the interleaved PFC converter in DCM.

The typical waveforms of the converter in DCM are shown in Fig. 6, in which there are six modes in one switching cycle. There are three modes in each of the positive and the negative half cycle operations. Here, only three modes in positive half cycle are analyzed due to the symmetry of operation. The equivalent circuit for each mode is shown in Fig. 7.

In this two-phase interleaved topology, the corresponding inductors in two phases are coupled using the same cores with the same coupling coefficients. The inductor $L1$ is coupled with $L2$, while the inductor $L3$ is coupled with inductor $L4$. These four inductors have the same self-inductances and mutual inductances. In each operation mode, the voltages across inductors $L1$ and $L4$ are the same in each operation mode. Thus, the inductor

currents $iL1$ and $iL4$ have similar waveforms as shown in Fig. 6. Similar waveforms are valid for inductors $L2$ and $L3$.

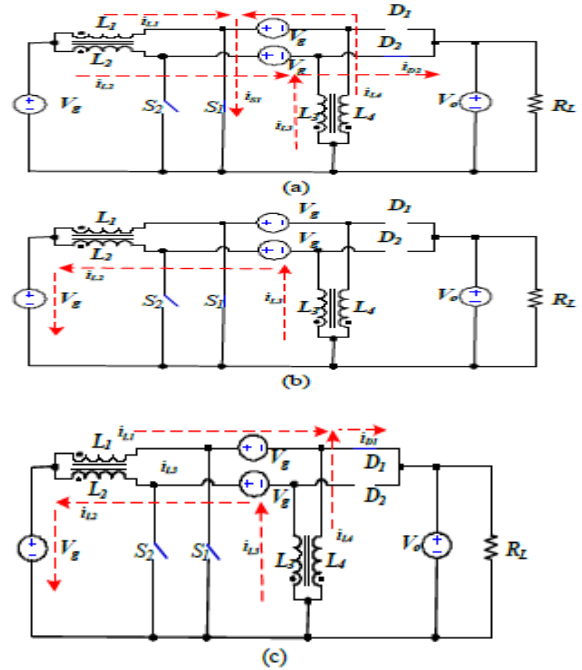


Fig 7. Equivalent circuits in DCM, (a) Mode I, (b) Mode II, (c) Mode III.

1) Mode I (t_0-t_1):

In this mode, as shown in Fig. 7(a), the switch $S1$ is on, while the switch $S2$ is off. The diode $D1$ is off, and diode $D2$ is on. The voltages across both inductors $L1$ and $L4$ are V_g . Therefore, the inductor currents $iL1$ and $iL4$ increase at the same rates. The current through $S1$, $iS1$, is the sum of the inductor currents $iL1$ and $iL4$. Meanwhile, voltages across both inductors $L2$ and $L3$ are $-Vo$. Thus, the inductor currents $iL2$ and $iL3$ decrease at the same rates, and the current through diode $D2$, $iD2$, is the sum of these two inductor currents.

As the inductors $L1$ and $L2$ are directly coupled, the core flux is affected by both inductor currents $iL1$ and $iL2$. The mutual inductance, M , is defined as,

$$M = \sqrt{L_{12} \cdot L_{21}} \dots \dots (1)$$

where, $L12$ is the mutual inductance induced by the inductor current $iL1$ in inductor $L2$, and $L21$ is the mutual inductance induced by the inductor current $iL2$ in inductor $L1$. Since the mutual inductance of inductors $L1$ and $L2$ are the same, the mutual inductance M has the same value as $L12$ and $L21$. Additionally, the coupling coefficient, k , is defined as,

$$K = \frac{M}{\sqrt{L_1 \cdot L_2}} \dots \dots (2)$$

where, L_1 and L_2 are self-inductances of the first coil and the second coil.

The voltages and currents of the mutually coupled inductors can be expressed as,

$$V_g = L_1 \frac{di_{L1}}{dt} + M \frac{di_{L2}}{dt} \quad \dots (3)$$

$$-V_o = M \frac{di_{L1}}{dt} + L_2 \frac{di_{L2}}{dt} \quad \dots (4)$$

Eq. (3) and Eq. (4) can be rearranged as,

$$\frac{di_{L2}}{dt} = \frac{V_o + kV_g}{(1-k^2)L_2} \quad (5)$$

$$\frac{di_{L2}}{dt} = \frac{V_o + kV_g}{(1-k^2)L_2} \quad (6)$$

Seen from the Fig. 6, the inductor current i_{L2} decreases all the time and changes the flowing direction in this mode. The current through diode D_2 , i_{D2} , keeps on decreasing. The variations of inductor currents, Δi_{L1} and Δi_{L2} , can be expressed as

$$\Delta i_{L1} = \frac{V_g + kV_o}{(1-k^2)L_1} D'T$$

$$\Delta i_{L2} = \frac{V_o + kV_g}{(1-k^2)L_2} D'T \quad (7)$$

Where, T is the switching period, and $D'T$ is the time interval between t_0 and t_1 .

2) Mode II (t_1-t_2):

At t_1 , the current through diode D_2 , i_{D2} , which is the sum of inductor currents i_{L2} and i_{L3} , drops to zero. Then, the diode turns off with ZCS. Meantime, the inductor currents i_{L3} and i_{L2} flow in a loop composed of the inductor L_3 , the capacitor C_2 , the inductor L_2 , and the equivalent voltage source V_g , as shown in Fig. 7(b).

The variations of inductor currents i_{L3} and i_{L2} are the same due to the same voltages across inductors L_3 and L_2 . In addition, the average current of i_{L3} is higher than the average current of i_{L2} [17]. Thus, at t_1 , when the inductor currents i_{L3} and i_{L2} drop to minimum, the inductor current i_{L3} is higher than i_{L2} with i_{L3} as positive value and i_{L2} as negative value, as shown in Fig. 6. The current flows from inductor L_3 to inductor L_2 in the aforementioned loop containing inductors L_3 and L_2 . Assuming that the resistances of inductors and capacitors in this loop are negligible, the loop current remains constant from t_1 to t_2 , as expressed in Eq. (9).

$$i_{L3} = -i_{L2} = \text{const} \quad (8)$$

The inductor current i_{L1} changes with a higher rate in comparison to Mode I as expressed in Eq. (10). The current of coupled inductor L_2 is constant, and only sets the flux bias.

$$\frac{di_{L1}}{dt} = \frac{V_g}{L_1} \quad (9)$$

Consequently, the variation of inductor current, Δi_{L1} , can be expressed as,

$$\Delta i_{L1} = \frac{V_g}{L_1} (D-D')T \quad (10)$$

Where, D is the duty cycle. Similar expressions are valid for the inductor L_4 .

3) Mode III (t_2-t_3):

As shown in Fig. 7(c), both switches are off in this mode. The diode D_2 is off, while the diode D_1 turns on. The constant current flows in the aforementioned loop consisting of inductors L_2 and L_3 . The inductor currents i_{L1} and i_{L4} decrease from maximum values, and the sum of them flows through the diode D_1 . The voltages across both inductors L_1 and L_4 are $-V_o$. The inductor current i_{L1} decreases at a rate expressed as,

$$\frac{di_{L1}}{dt} = -\frac{V_o}{L_1} \quad (11)$$

Consequently, the variation of inductor current, Δi_{L1} , can be shown as,

$$\Delta i_{L1} = -\frac{V_o}{L_1} (0.5-D)T \quad (12)$$

Similar expressions are applicable for the inductor L_4 .

B. Higher Output Voltage Case

The waveforms of higher output voltage case are similar to those of lower output voltage case. In DCM, the operation principles of higher output voltage case are similar to those of lower output voltage case. In a switching cycle, there are six modes, among which only three modes are analyzed due to the symmetry of operation.

1) Mode I:

The inductor currents i_{L1} and i_{L2} increase simultaneously at small rates. Similar to the lower output voltage case, the slow rate of inductor current i_{L1} and i_{L2} are expressed as,

$$\frac{di_{L1}}{dt} = \frac{V_g}{(1+k)L_1} \quad (13)$$

$$\frac{di_{L2}}{dt} = \frac{V_g}{(1+k)L_2} \quad (14)$$

Thus, the inductor current variations, Δi_{L1} and Δi_{L2} , can be expressed as,

$$\Delta i_{L1} = \frac{V_g}{(1+k)L_1} (D-0.5)T \quad (15)$$

$$\Delta i_{L2} = \frac{V_g}{(1+k)L_2} (D-0.5)T \quad (16)$$

Since the $L3$ and $L4$ have the same inductance values as $L1$ and $L2$, similar equations can be derived for the inductor currents i_{L3} and i_{L4} .

2) Mode II:

$$\frac{di_{L2}}{dt} = \frac{V_o + kV_g}{(1-k^2)L_2} \quad (17)$$

$$\frac{di_{L1}}{dt} = \frac{V_g + kV_o}{(1-k^2)L_1} \quad (18)$$

Similar to the lower output voltage case, the slew rate of inductor current i_{L1} and i_{L2} are expressed as,

$$\Delta i_{L1} = \frac{V_g + kV_o}{(1-k^2)L_1} D'T \quad (19)$$

$$\frac{di_{L2}}{dt} = \frac{V_o + kV_g}{(1-k^2)L_2} \quad (19)$$

The inductor current i_{L3} decreases and changes the direction in this mode. The current through diode, $D2$, keeps on decreasing. $D'T$ is the time interval between the diode $D2$ turn-on and turn-off. The variations of inductor currents, Δi_{L1} and Δi_{L2} , can be expressed as,

$$\Delta i_{L1} = \frac{V_g + kV_o}{(1-k^2)L_1} D'T \quad (20)$$

$$\Delta i_{L2} = \frac{V_o + kV_g}{(1-k^2)L_2} D'T \quad (21)$$

3) Mode III ($t2-t3$):

At $t2$, the current through diode, $D2$, drops to zero. Then, the diode turns off with ZCS. Meanwhile, the currents of inductors $L2$ and $L3$ circulate in a loop composed of the inductor $L3$, the capacitor $C2$, the inductor $L2$, and the equivalent voltage source Vg . The constant current flows from inductor $L2$ to inductor $L3$. Thus, Eq. (22) can be obtained as,

$$i_{L3} = -i_{L2} = \text{const}$$

The inductor current i_{L1} changes with a higher rate in comparison to Mode I as expressed in Eq. (23). The current of coupled inductor $L2$ is constant, and only sets the flux bias.

$$\frac{di_{L1}}{dt} = \frac{V_g}{L_1} \quad (22)$$

Therefore, the inductor current variations, Δi_{L1} , can be expressed as,

$$\Delta i_{L1} = \frac{V_g}{L_1} (D-D')T \quad (23)$$

Similar expressions are valid for inductor $L4$.

III. ANALYSIS OF THE PROPOSED PFP TOPOLOGY

Based on the operation principles for higher output voltage and lower output voltage cases, the detailed analysis can be conducted to set the critical parameters of power components and to assess the circuit performance. Relevant expressions are derived in this section. The analyses are based on the assumption of unity power factor and a constant output voltage due to a large output filter capacitance.

A. Reduced Input Current Ripple by Coupled Inductors

In this section, the input current ripple is calculated in DCM operation. Although the two PFC converters work in DCM operation individually, the input current maintains CCM features with a small input current ripple.

As shown in Fig. 6, from $t0$ to $t1$, the current of $L1$ increases, and the current of $L2$ decreases. In this interval, the input current variation, Δi_1 , is the sum of the current variations of inductors $L1$ and $L2$. It can be expressed as,

$$\Delta i_1 = \left(\frac{V_g + kV_o}{(1-k^2)L_1} - \frac{V_o + kV_g}{(1-k^2)L_2} \right) D'T$$

From t_1 to t_2 , the current of L_2 becomes constant, and the current of L_1 increases at a different rate. The input current variation, Δi_2 , is expressed as,

$$\Delta i_2 = \frac{V_{\xi}}{L_1} (D-D')T$$

The input current ripple is the sum of the two variations, Δi_1 and Δi_2 . Thus

$$\Delta i = \Delta i_1 + \Delta i_2 = a \cdot D' T + b \cdot (D-D') T$$

where, a and b are the weighted coefficients

$$a = \frac{V_{\xi} - V_o}{(1+k)L}, \quad b = \frac{V_{\xi}}{L}$$

where, $L = L_1 = L_2$.

The coefficient a is much smaller than coefficient b , and consequently the input current ripple is mostly determined by second term based on Eq. (27). Thus, the input current becomes larger as the converter works in deeper DCM operation. In order to reduce the input current ripple, the converter should operate under DCM in close proximity to boundary conduction mode (BCM). When D' becomes equal to D , the converter works in BCM with minimum input current ripple. Compared with the input current ripples of traditional PFC and interleaved PFC with non-coupled inductors, the input current ripple is significantly reduced. The expressions for input current ripples are listed in Table I.

TABLE I
INPUT CURRENT RIPPLES OF THREE TOPOLOGIES

Topology	Input current ripple
Traditional SEPIC	$T \frac{V_{\xi}}{L} D'$
Interleaved SEPIC (non-coupled)	$\frac{V_{\xi} - V_o}{L} D' T + \frac{V_{\xi}}{L} (D-D') T$
Interleaved SEPIC (coupled)	$\frac{V_{\xi} - V_o}{(1+k)L} D' T + \frac{V_{\xi}}{L} (D-D') T$

VI. FUZZY LOGIC CONTROL

L. A. Zadeh presented the first paper on fuzzy set theory in 1965. Since then, a new language was developed to describe the fuzzy properties of reality, which are very difficult and sometime even impossible to be described using conventional methods. Fuzzy set theory has been widely used in the control area with some application to power system [5]. A simple fuzzy logic control is built up by a group of rules based on the human knowledge of system behavior. Matlab/Simulink simulation model is built to study the dynamic behavior of converter. Furthermore, design of fuzzy logic controller can provide

desirable both small signal and large signal dynamic performance at same time, which is not possible with linear control technique. Thus, fuzzy logic controller has been potential ability to improve the robustness of compensator. The basic scheme of a fuzzy logic controller is shown in Fig.3 and consists of four principal components such as: a fuzzy fication interface, which converts input data into suitable linguistic values; a knowledge base, which consists of a data base with the necessary linguistic definitions and the control rule set; a decision-making logic which, simulating a human decision process, infer the fuzzy control action from the knowledge of the control rules and linguistic variable definitions; a de-fuzzification interface which yields non fuzzy control action from an inferred fuzzy control action [10].

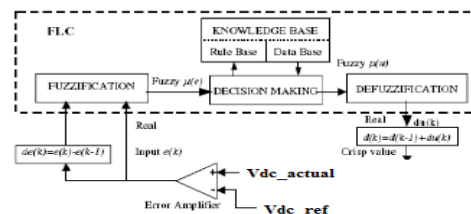


Fig.8. Block diagram of the Fuzzy Logic Controller (FLC).

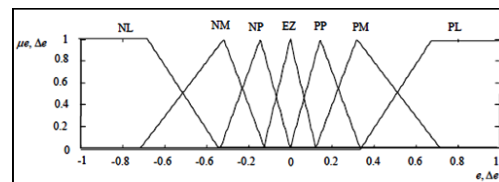


Fig.9 Membership functions for Input, Change in input, Output.

Rule Base: the elements of this rule base table are determined based on the theory that in the transient state, large errors need coarse control, which requires coarse input/output variables; in the steady state, small errors need fine control, which requires fine input/output variables. Based on this the elements of the rule table are obtained as shown in Table 1, with „ V_{dc} “ and V_{dc-ref} as inputs. In this section, a 500W interleaved PFC converter with coupled inductors is designed to validate the theoretical analysis. The experiments are conducted to validate the advantages of proposed topology.

A. Control Scheme

The proposed control scheme requires three sensors (input voltage, input current, and output voltage). The topology and the control scheme are shown in Fig. 10. Only one current sensor is used to sample the total current of the two-phase interleaved PFC converter. The sawtooth

carrier signals of switches $S1$ and $S2$ have 180o phase shift. The control is implemented in a DSP controller. In the voltage control loop, the voltage error between the output voltage and its reference voltage is fed to the voltage-loop PI controller, Gv , to generate the reference signal of the input current.

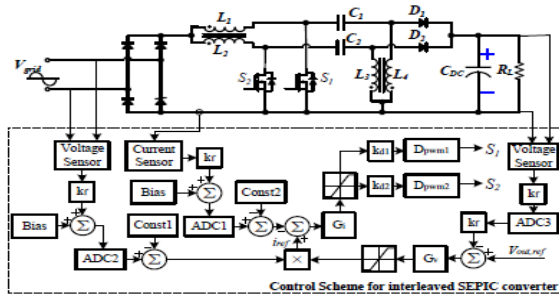


Fig 10. Topology and control scheme of proposed interleaved PFC converter.

Then, the current error between this generated current reference and input current is fed to current-loop PI controller, G_i , to adjust the duty ratio for switches $S1$ and $S2$.

B. Design of Critical Components

1) Intermediate capacitor

In a PFC converter, the intermediate capacitor has two tasks: (i) to keep a constant voltage in a switching period; and (ii) to follow the variation of the input voltage [14]. Thus, the selection of this capacitor is constrained by the grid frequency, f_l , and the switching frequency, f_s . The resonant frequency of the intermediate capacitor and the input inductor has to be much larger than the line frequency to avoid the oscillation of the input current. On the other hand, this resonant frequency has to be much lower than the switching frequency to reduce the voltage ripple of the intermediate capacitor. The large voltage ripple causes large power loss on the intermediate capacitor, which reduces the efficiency and reduces the life of the intermediate capacitor.

$$f_r = \frac{1}{2\pi} \sqrt{\frac{1}{C(L_1 + L_2)}} \quad (23)$$

$$f_l < f_r < f_s$$

In the experiment, the operation frequency of the PFP, f_s , is set as 150kHz, and the f_r is set as 10kHz. Thus, the intermediate capacitor can be selected as 1μF.

2) Inductors and coupling coefficient

A proper coupling coefficient for the entire range of output DC-link voltage is critical for the performance of the circuit. A coupling coefficient much higher than the

minimum value, k_{min} , increases the input current ripple. On the other hand, a low coupling coefficient increases the size of the coupled inductor because a larger magnetic core would be needed without significantly increasing coil turns.

In order to select a proper coupling coefficient, the inductance of coupled inductors should be taken into consideration. On one hand, the inductance cannot be too small. As shown in Table II, the k_{min} value of the higher output voltage case is much smaller than that of the lower output voltage case given a small inductance $L2$. However, the k_{min} should not be too much different for these two cases. Otherwise, the converter would enter deep DCM in higher output voltage case, resulting in significantly increased input current ripple in this case. On the other hand, the inductance $L2$ cannot be too large because the coil turns increase largely for higher inductance $L2$, resulting in much larger size of the coupled inductors.

According to Table II, the inductance of 400uH with a minimum coupling coefficient of 0.8391 is selected for both coupled inductors. To ensure the DCM operation, the coupling coefficient is chosen as 0.85.

To implement the coupled inductor, the ETD44 core is selected, and Litz wire is adopted to build the coils due to the high switching frequency. Coils of both coupled-inductors have 24 turns. The air gap is tuned to be 0.3mm to set the coupling coefficient as 0.85. As the voltage stress between the two coupled-inductors is really high, a large air gap (5mm) is incorporated between the two coils. An image of the coupled inductor, designed for this application, is shown in Fig. 8.

The parameters of all the components in the two-phase interleaved PFC converter with coupled inductor s are listed in Table II.

TABLE IV
DESIGN PARAMETERS OF THE CONVERTER

Parameter	Symbol	Value
Input voltage	V_m	85Vac-135Vac, 60Hz
Output voltage	V_o	50V-200V
SEPIC capacitor	C_1, C_2	1uF
Input inductor	L_1, L_2	400uH
Output inductor	L_3, L_4	400uH
Coupling coefficient	k	0.85
Switching Frequency	f_s	150kHz
Output capacitor	C_{dc}	2mF

IV MATLAB SIMULINK RESULTS

In order to validate the advantages of the proposed topology and the designed parameters, simulations are conducted for 90V output voltage and 180V output voltage cases. The inductance is set as 400μH for all the inductors with 0.85 coupling efficient. The input voltage

is 110Vac. The simulation results are shown in Fig. 12 and Fig. 13. The DCM operation can be observed from the inductors current waveforms. According to the simulation results in Fig. 12, the input voltage is in phase with the input current. The power factor is 0.998, and the THD of the input current is 3.5%. According to Fig. 13, the power factor is 0.996, and THD of the input current is 3.1%. As the output voltage is higher than the input voltage, the currents of $L1$ and $L2$ are mostly positive. In simulation, an ideal diode bridge is utilized to rectify the AC input voltage.

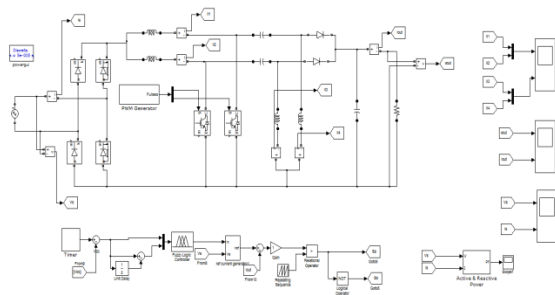


Fig 11 MATLAB SIMULINK Model of the Proposed FLC Base PFC Converter

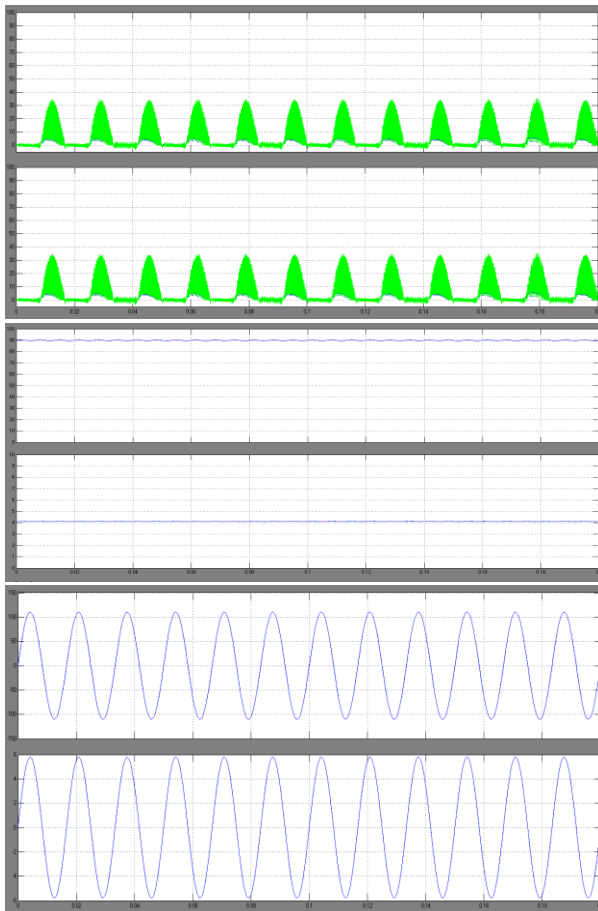


Fig.12 Simulation result for $V_{in}=110\text{Vac}$, $V_o=90\text{V}$, and $P_{out}=370\text{W}$.

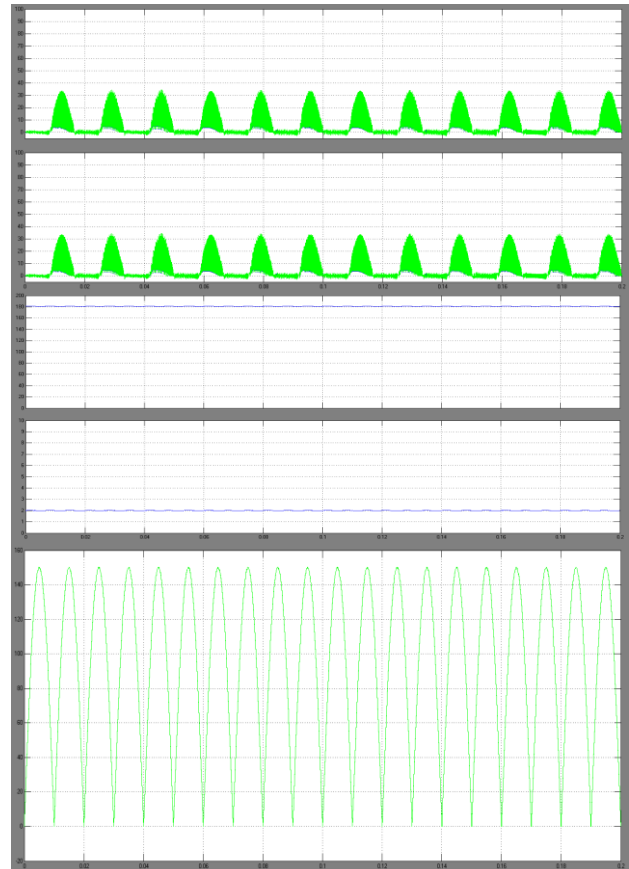


Fig.13 Simulation result for $V_{in}=110\text{Vac}$, $V_{out}=180\text{V}$, and $P_{out}=360\text{W}$.

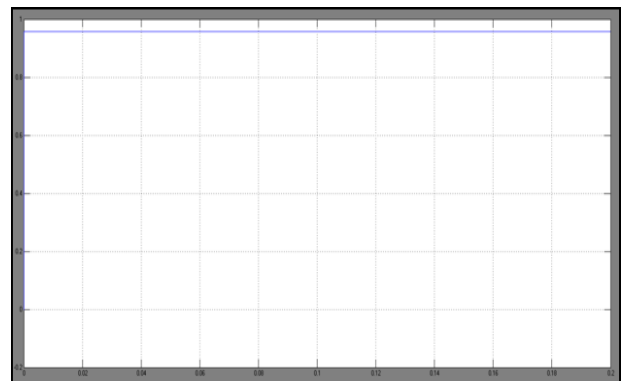


Fig 14 Power Factor of the input source using FLC based PFC Converter

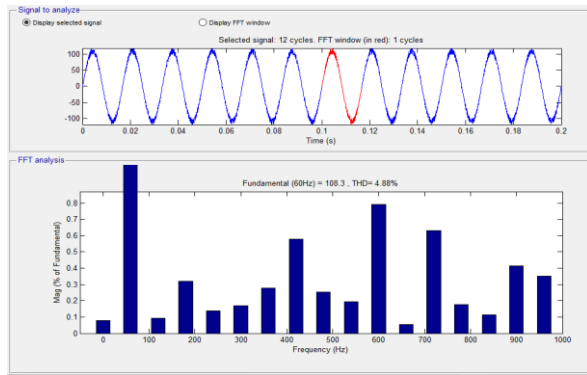


Fig 14 Source Current THD values in % of the Proposed PFC Converter with PI Controller

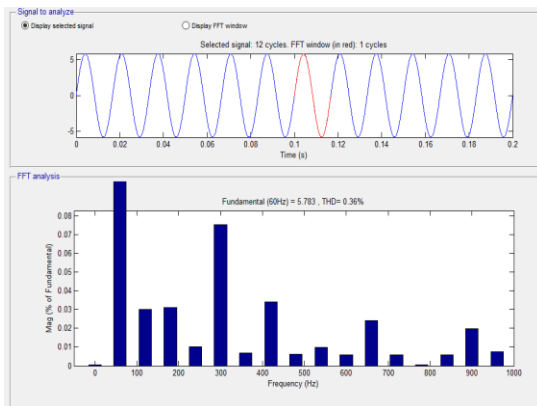


Fig 14 Source Current THD values in % of the Proposed PFC Converter with Fuzzy Logic Controller

V. CONCLUSION

This paper proposed a novel Fuzzy Logic Control based interleaved two phases PFC Converter with inductors directly coupled. The directly coupled inductors can reduce the number of magnetic components, decrease the input current ripple. The key circuit and design features are summarized as follows. The power level of PFC is improved by interleaving two AC/DC converters, the voltage and current stresses of the diodes and switches are largely reduced, improving the power level up to 500W. High efficiency, low harmonics is maintained over a wide range of DC-link voltage. The converter is designed to operate in DCM in order to achieve ZVS for switches and ZCS for diodes. The input current ripple is reduced by properly designing the coupled inductors. The inductance and coupling coefficient are carefully selected for the coupled inductors to ensure the DCM operation in close proximity to BCM operation over the wide range of DC-link voltage. A 500W prototype is built to validate the advantages of this proposed PFC. The MATLAB SIMULINK results show the proposed interleaved FLC based PFC Converter can provide a wide output DC-Link

voltage from 90V to 190V at 110Vac input voltage, and the efficiency is over 96% at 500W over a wide range of DC-link voltage with power factor over 0.95845.

REFERENCES

- [1] Singh, Bhim, Brij N. Singh, Ambrish Chandra, Kamal Al-Haddad, Ashish Pandey, and Dwarka P. Kothari. "A review of single-phase improved power quality AC-DC converters", *IEEE Trans. Ind. Electron.*, vol. 50, no. 5, pp. 962-981, 2003.
- [2] Musavi, Fariborz, Wilson Eberle, and William G. Dunford, "A high-performance single-phase bridgeless interleaved PFC converter for plug-in hybrid electric vehicle battery chargers," *IEEE Trans. Ind. Appl.*, vol.47, no.4, pp. 1833-1843, Apr. 2011.
- [3] Chen, Rui, and Jih-Sheng Lai, "Analysis and design of DCM PFC with adjustable output voltage," in *Proc. IEEE APEC*, 2015, pp. 477-484.
- [4] Fei Zhang and Jianping Xu, "A Novel PCCM Boost PFC Converter With Fast Dynamic Response", *IEEE Trans. Ind. Electron.*, vol. 58, no. 9, pp. 4207-216, Sept. 2011.
- [5] A. Khaligh and S. Dusmez, "Comprehensive topological analysis of conductive and inductive charging solutions for plug-in electric vehicles," *IEEE Trans. Veh. Technol.*, vol.61, no.8, pp. 3475-3489, Aug. 2012.
- [6] F. Musavi, M. Craciun, D.S. Gautam, W. Eberle, and W.G. Dunford, "An LLC resonant DC-DC converter for wide output voltage range battery charging applications," *IEEE Trans. Power Electron.*, vol. 28, no. 12, pp. 5437-5445, 2013.
- [7] S. Dusmez, , and A. Khaligh, "Generalized technique of compensating low-frequency component of load current with a parallel bidirectional DC/DC converter," *IEEE Trans. Power Electron.*, vol. 29, no. 11, pp. 5892-5904, Nov. 2014.
- [8] H. Wang, S. Dusmez, and A. Khaligh, "Maximum Efficiency Point Tracking Technique for LLC Based PEV Chargers through Variable DC Link Control," *IEEE Trans. Ind. Electron.*, vol. 61, no. 11, pp. 6041-6049, Nov. 2014.
- [9] J. Deng, S. Li, S. Hu, C. C. Mi, and R. Ma, "Design Methodology of LLC Resonant Converters for Electric Vehicle Battery Chargers," *IEEE Trans. Veh. Technol.*, vol. 63, no. 4, pp. 1581-1592, Apr. 2014.
- [10] W. Guo, H. K. Bai, G. Szatmari-voicu, A. Taylor, J. Patterson, and J. Kane, "A 10kW 97%-efficiency LLC Resonant DC/DC Converter with Wide Range of Output Voltage for the Battery Chargers in Plug-in Hybrid Electric Vehicles," in *Proc. IEEE ITEC*, 2012, pp.1-4.
- [11] H. Wang, S. Dusmez, and A. Khaligh, "Design and analysis of a full-bridge LLC-based PEV charger optimized

- for wide battery voltage range," *IEEE Trans. Veh. Technol.*, vol. 63, no. 4, pp. 1603-1613, Apr. 2014.
- [12] S. Dusmez, and A. Khaligh, "A compact and integrated multifunctional power electronic interface for plug-in electric vehicles," *IEEE Trans. Power Electron.*, vol. 28, no. 12, pp.5690-5701, Dec. 2013.
- [13] S. Dusmez, , and A. Khaligh, "A charge-nonlinear-carrier-controlled reduced-part single-stage integrated power electronics interface for automotive applications," *IEEE Trans. Veh. Technol.*, vol. 63, no. 3, pp. 1091-1103, Mar. 2014.
- [14] LyrioSimonetti, DomingosSavio, Javier Sebastian, and Javier Uceda, "The discontinuous conduction mode PFC and Cuk power factor preregulators: analysis and design," *IEEE Trans. Ind. Electron.*, vol.44, no.5, pp. 630-637, May 1997.
- [15] Mahdavi, Mohammad, and HoseinFarzanehfard. "Bridgeless PFC PFC rectifier with reduced components and conduction losses," *IEEE Trans. Ind. Electron.*, vol.58, no.9, pp. 4153-4160, Sept.2011.
- [16] Jae-Won Yang and Hyun-Lark Do, "Bridgeless PFC Converter With a Ripple-Free Input Current", *IEEE Trans. Power Electron.*, vol. 28, no. 7, pp. 3388–3394, Jul. 2013.
- [17] Ahmad J. Sabzali, Esam H. Ismail, Mustafa A. Al-Saffar and Abbas A. Fardoun, "New Bridgeless DCM PFC and Cuk PFC Rectifiers With Low Conduction and Switching Losses," *IEEE Trans. Ind. Appl.*, vol.47, no.2, pp. 873-881, Mar. 2011.



Ms.B.Himabindu is pursuing her Master of Technology in Power Electronics, EEE Department, SHREE Institute of Technical Education, Tirupati, and Andhra Pradesh, India.



Mr.M.Purushotham is currently working as an Associate Professor & HOD in EEE department, SHREE Institute of Technical Education, Published in several papers in national & International Journals on area of power electronics & Electrical Drives, Tirupati, Andhra Pradesh, India.