

Ripple Controlling MMC For Circulating DC Current

M.Mahesh ; P V Samrat ; G.Isaac

M.Tech (Electrical Power Systems), Ellenki College of Engineering
M.E., College of Engineering,Osmania University

M.Tech(Power Electronics and Industrial Drives), JNTU College Of Engg, Hyd

ABSTRACT: *MMC is an evolving topology that is capable of take care of high voltage and power rankings.Under the unbalanced circumstance, the principle subject matter of controlis to lower the bad-sequence line contemporary. Moreover,the circulating cutting-edge of a MMC includes now not most effective double-lineneegative-collection thing, which appears below the balancedcondition, however also superb- and zero-series double-line components. Thus the controller have to be able to cast off all the ones components of the circulating cutting-edge. A proportional-resonantcontroller (PR controller) is applied to adjust the fine- andnegative-sequence components of circulating cutting-edge. In addition,the 0-series issue of circulating contemporary is controlledby a dc modern-day controller. The proposed manipulate approach isconfirmed in MATLAB/simpowersystem.*

KEYWORDS-Modular multilevel converter (MMC), Circulating Current Suppression Control, DC Current Ripple Control,Proportion Resonance Controller

I. INTRODUCTION

AC has been the preferred global platform for electric transmission to homesand companies for the beyond 100 years. And but high-voltage AC transmission hassome limitations, beginning with transmission ability and distance constraints, andthe impossibility of right now connecting two AC electricity networks of various frequencies. With the dawn of a ultra-modern strength technology and the need to construct a better grid,HVDC is predicted to develop far past its conventional feature as a complement to atransmission [2].

Excessive Voltage Direct current (HVDC) is the electrical energy transmission desire carried out in

massive quantity of strength over lengthy distances with minimal losses. Thinking about the reality that in a traditional three segment gadget the energy delivered is conformed by way of its RMS charge, HVDC lets in transmitting energetic strength with higher voltagevariety. Moreover, the impedance created in AC transmission systems are avoidablelowering the power losses. Consequently, the initial set up fee of HVDC is betterthan HVAC systems but because of lower losses it turns into price powerful over the time.as an example, strength delivered from remote offshore wind farms may be successfully fedinto power grids onshore through HVDC technology. Moreover, HVDC systems are useful to interconnect asynchronous AC grids reliably. Using HVDC system lets in theopportunity of the use of underground and susea cables. Hence, HVDC is considered asa extraordinarily green alternative for transmitting massive amounts of energy over lengthydistances and for special reason packages. As a key enabler in the future strengthsystem based on renewables, HVDC is in reality shaping the grid of the future.this period includes a converter station wherein the AC device is transformed into DC then transmitted via a strength transmission cable after which converted lower back into AC. The cable connection can be overhead or every underground orsubmarine under water. An HVDC transmission system is depicted in figure 1.1.

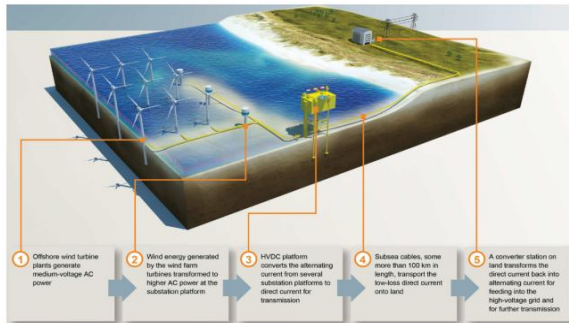


Figure 1.1: HVDC transmission system from an offshore to onshore grid [1]

Modular Multilevel Converters (mmcs) have received researcher's attention due to their potential to deal with excessive voltage and energy rankings. VSC-HVDC is getting increasingly more essential for integrating renewable power assets together with large offshore wind farms, supplying flexible interconnection amongst vulnerable AC grid network the use of again-to-returned configuration, or actually transmitting power the use of underground cables. The VSC-HVDC moreover has fast and unique manipulate over the lively electricity-flow in addition to it is able to independently control the reactive energy injection on the close by ac grid. There are numerous operational MMC-HVDC duties which encompass HVDC PLUS (Siemens) with an 88km undersea transmission hyperlink among San Francisco's city centre electric energy grid and a substation near Pittsburg. The crucial supporting functions HVDC PLUS gives are AC voltage Control, black-start functionality, compact converter station area utilization, four quadrant operation, repayment of asymmetrical loads, flexible integration into HVDC multi terminal systems or future HVDC grids. Its primary going for walks principle and specific benefits each on the technical similarly to on the finances friendly issue can be described in [3] [4].

Another MMC-HVDC set up named HVDC Light with the aid of the use of ABB, is an version of HVDC traditional used to transmit power in electricity ranges (50-2500MW) transmitted the usage of overhead strains and environmental first-rate underground and sub-sea cables. It is used for grid interconnections and offshore hyperlinks to wind

farms. With hvdc light, it's far viable to transmit power in both instructions and to manual current ac grids an awesome manner to growth robustness, balance, reliability and controllability. Hvdclight offers many different advantages and may be utilized in awesome packages which is defined in [5]. As stated before, the principle problem of the 2 degree converter is its immoderate switching losses due to pretty excessive switching frequency which necessitates excessive insulation necessities of the transformer, in addition to filters. The use of modular multilevel converters overcomes maximum of the aforementioned shortcomings, but at the rate of times as many semi-carrying out devices and a massive allotted capacitor for each submodule. The principle concept of the hybrid VSC-HVDC, as used in HVDC max sine advanced by using Alstom, is to apply a stage converter as the principle switching component with low switching frequency and an MMC to offer a voltage wave shaping function on the AC facet so you can take away the harmonics [6] [7].

II. PROPOSED SYSTEM

Multilevel converters are classified into diode-clamped multilevel converters (dcmcs), flying-capacitor multilevel converters (fcmcs), cascaded H-bridge converters (chbcs), and modular multilevel converters (mmcs). Mmcs have been broadly followed in VSC-HVDC systems. Fig. 1 shows the shape of an MMC which includes six arms. Each arm is composed of an inductor and a series of linked half-bridge sub-modules (sms). HVDC-MMC systems require several design strategies. (1) System parameter design includes inductance and capacitance layout and switching device cutting-edge capability design. (2) System control design includes electricity (DC-link voltage) manipulate, AC-side current manipulate, circulating current modern-day manage, and SM voltage balancing [2-6].

A layout technique for the SM capacitance of the MMC was delivered in [7]. This design technique calculated the difference in input electricity consistent with the amplitude of the grid voltage and the lively strength. The SM capacitance is designed by using the

enter strength and the SM capacitor voltage ripple on the idea of the restrict cost.

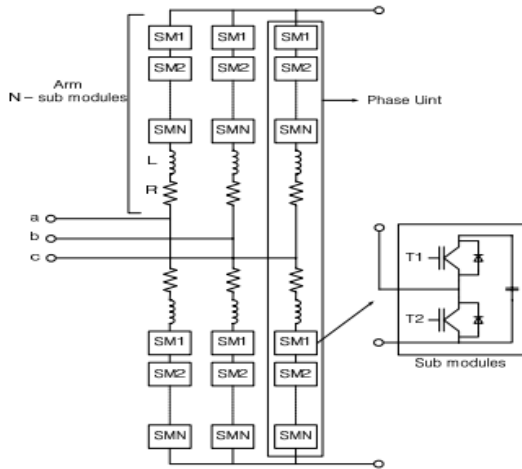


Fig. 1. Basic structure of MMC.

The SM capacitor voltage ripple has line-frequency and double-line-frequency components. However, this design method did not separate line-frequency and double-line-frequency components; the capacitor voltage ripple was only calculated using integrated components.

The output of sub-module is either U_c or 0 depending on the gate statement. When N is big enough or the switching frequency is high enough, the voltage injection to each arm by sub-modules can be considered as continuous. For DC side voltage, with big DC-side capacitor, the dc-side voltage can be considered as a constant value. Thus, the single phase equivalent circuit of a MMC can be expressed as Fig. 2.

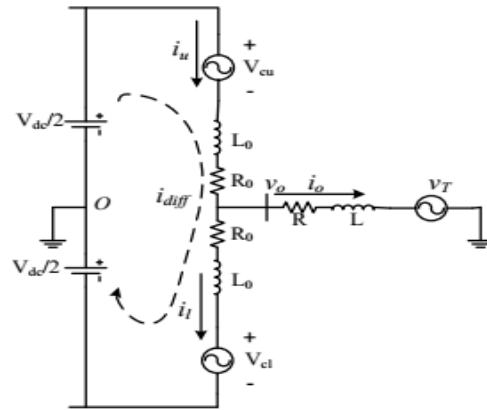


Fig. 2. Single phase equivalent circuit of MMC

In Fig. 2, The upper and lower arm current are named as i_u and i_l ; the converter's output current and voltage are named as i_o and v_o respectively. The circulating current flowing within the converter is denoted as i_{diff} . Since the upper and lower arm are symmetric, ideally both lower and upper arm currents contain half of the converter output current.

II. CONTROL SYSTEM UNDER UNBALANCED VOLTAGE

A. PR Controller

PR control can achieve high bandwidth at certain resonant frequency. Through PR control, measurement signal can track the reference signal without steady-state error at the resonance frequency.

B. Outer Loop Power Control

When the grid side voltage is under unbalanced condition, the line current and power flow are separated in positive-, negative- and zero-sequence components. With a zero-sequence current controller, the zero-sequence current can be reduced to zero. Therefore the objective of the unbalance controller is the negative component of line current.

C. Inner Loop Current Control

Different control objectives have been set for MMC under unbalanced condition. Reference [15] tried to

reduce the negative components of the line current to zero.

D. Grid-side Zero-Sequence Current Control

The overall control structure is shown in Fig.4. The zero sequence current occurs during the unbalanced condition. A Y-to- Δ transformer can stop the zero sequence current. However, when the fault happens on the transformer or between the transformer and MMC, zero-sequence current will not be stopped by transformer.

E. Circulating Current Control and Dc Current Ripple Control

In an MMC, the difference between each phase's total sub-module capacitor voltage leads to the circulating current. Under balanced condition, it has been evaluated that circulating current consists of only negative-sequence double line frequency component, since the instantaneous power for each phase has a negative-sequence double line frequency component.

When the ac-side voltage has negative component, the instantaneous power of each phase consist not only negative sequence but also positive- and zero-sequence double-line frequency components. Therefore, to eliminate the circulating current under unbalanced condition, the controller in positive-, negative- and, zero-sequence are all needed.

Its dc component is set as the reference of the PR controller. The output of PR controller is the positive- and negative-sequence components of the reference inner unbalanced voltage, which is noted as $e_{diff,abc}$ in Fig. 3.

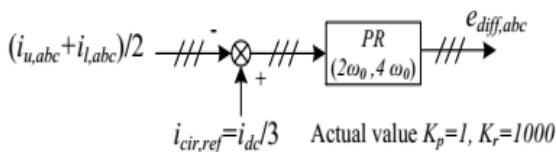


Fig. 3. Circulating current suppression controller.

For a three-phase system, the sum of positive- and negative-sequence current are zero. However the sum of zero-sequence component is not zero. And i_{dc} is the sum of three-phase current. Therefore, if the three-phase current has zero-sequence component, then i_{dc} includes the zero-sequence component triple. Normally, a Y-to- δ transformer can stop the zero sequence line current. However, when the fault happens between the transformer and MMC, or the system has no transformer, it is necessary to eliminate the zero-sequence line current. The controller to eliminate zero-sequence current is shown in Fig. 4. As shown in Fig. 3, the output of the zero sequence line current controller is added to the output of the inner loop current controller as a zero-sequence component.

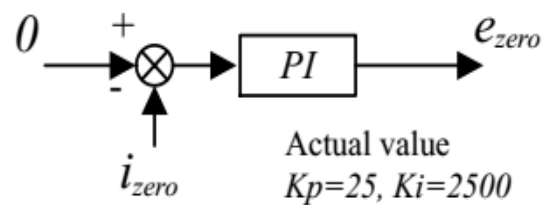


Fig. 4. Zero-sequence line current controller.

If we assume there is no power loss on MMC. Then the ac-side power of MMC should be equal to the dc-side power of MMC. So the dc component of the dc-side current can be easily set as $I_{dc,ref} = P_{out} / V_{dc}$. Where P_{out} is the ac-side output power of MMC and V_{dc} is the dc supply voltage of MMC. A PR controller is used to control the zero-sequence of the inner difference current to $I_{dc,ref}$. The output of PR controller is the zero-sequence component of the reference inner difference voltage. Beside the double-line frequency ripple, the dc current ripple controller can also cancel the resonance current caused by LC circuit resonant. A controller is added to reduce the dc current ripple as shown in Fig. 5. The output of the dc current ripple controller is added to the output of the circulating current suppression controller as shown in Fig. 3.

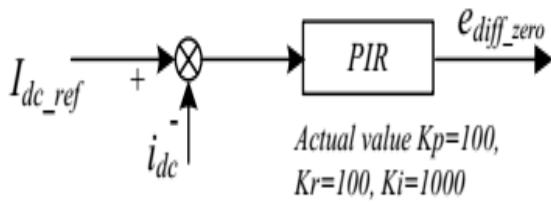


Fig.5. DC-side current ripple controller.

III. SIMULATION RESULTS

A simulation of the proposed system is conducted in MATLAB SimPowerSystem. The simulation environment and parameters are listed in table I. At $t = 0:2s$ the circulating current controller and the controller to eliminate the dc current ripple is activated. From $t = 0:6s$ to $t = 0:8s$, there is a 0.2 pu negative-sequence component voltage on the grid side. Regardless of the start-up process, the capacitor voltages of sub modules were charged at nominal value at beginning.

B. Performance of the control system

Fig.6 shows the output real power of the MMC. During the unbalanced voltage condition (t from 0:6 to 0:8), the output power has a double-line frequency component. When I^- is zero, with a non zero V^-g , The double-line frequency component of line power is not zero.

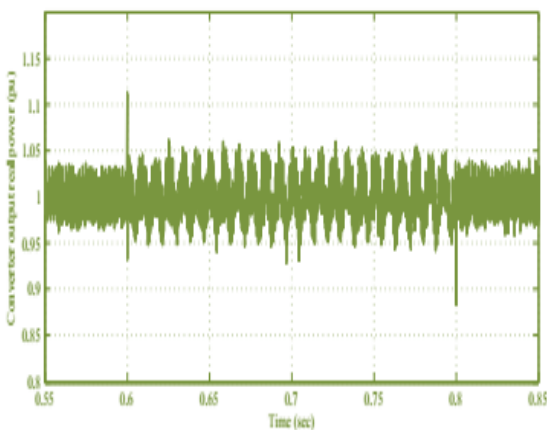


Fig. 6. Output real power of converter.

Fig.7 shows the output reactive power of the MMC. As the same with the output active power. During the unbalanced grid condition, there is a double-line

frequency component appear on the converter output reactive power.

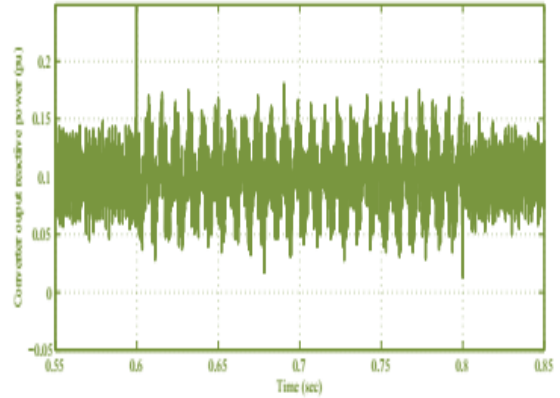


Fig. 7. Output reactive power of converter

Fig.8 is the grid current of MMC during the unbalance condition. The ripple during the unbalanced condition is due to the changing of the power and reactive power. The outloop power controller tries to regulate the converter power to reference value. So the ripple of the power leads a ripple in current reference in dq frame, and the ripple for reference current in dq frame causes a ripple of line current in abc frame.

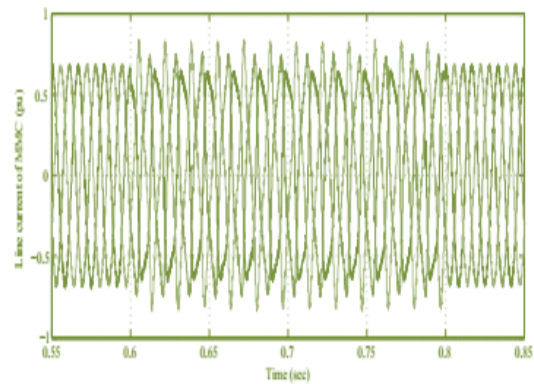


Fig. 8. Grid current of MMC

Fig. 9 is the zero-sequence component of line current. After applying the zero-sequence current controller at $t = 0:1s$, the magnitude of the zero-sequence current is reduced during both balanced and unbalanced condition.

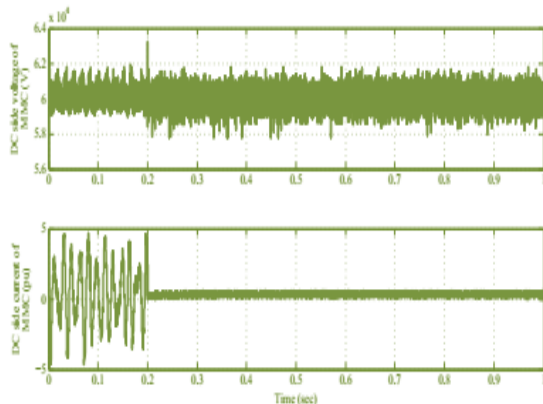


Fig. 9. Zero-sequence component of line current of MMC

IV. CONCLUSION

Investigative examine of the internal unbalances in an MMC has been authorized out. This unbalance can be a result of the asymmetries, non linearities and trade in the tolerances of the components as for instance arm inductors and submodule capacitors used in an MMC. When the poor-series component of the line current at some stage in unbalanced circumstance is managed to zero, there may be a double-line frequency factor on the output power of MMC in the course of unbalanced condition. With right nonzero terrible-sequence line present day, the double-line frequency component of the output actual strength may be removed. Their controller reduces both superb- and terrible-sequence components of the circulating modern-day at some stage in the unbalanced condition. In addition, a dc modern-day controller is applied to reduce the 0-series of the circulating contemporary and resonance modern-day on the dc-facet of MMC.

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Authors Details:



M. Mahesh completed M.tech (Electrical Power Systems) from Ellenki college of engineering in the year 2016. My areas of interest are power systems, machines.



P V Samrat completed M.E. from College of Engineering, Osmania University in the year 2013. My areas of Interests are Power Electronics, Power Quality, Grids.



G. Isaac Having 9+ Years Of Exp As Asst Professor In The Dept Of Electrical And Electronics Engg, Presently Working As Asst Professor In Global Institute Of Engg And Technology, Jntu, Hyderabad. I Did B.Tech From Royal College Of Engg (Presently Hyderabad Inst Of Engg And Technology And Management In The Year 2005 And M.Tech (Power Electronics And Industrial Drives) From Jntu College Of Engg Hyd In Year 2010.