

Conversion Systems of Wind Energy Using DFIG

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ABSTRACT: *Doubly-fed induction generator (DFIG) are extensively used for variable velocity wind energy conversion structures(WECS). This paper offers a detailed evaluation on diverse topologies, configuration, energy converters and control schemes used with the operation of the DFIG. The main involvement of this work fabrication in the control of GSC for supplying harmonics. Similarly to its slip power transfer. The rotor-aspect converter (RSC) is used for reaching most strength extraction and to deliver required reactive electricity to DFIG. Wind energy conversion machine (WECS) works as a static compensator (STATCOM) for supplying harmonics even if the wind turbine is in shutdown situation. Of each GSC and RSC manipulate algorithms are provided in detail. DFIG-primarily based WECS is applied using MATLAB/Simulink. A prototype of the proposed DFIG based WECS is developed the usage of a digital sign processor (DSP). The wind power is the preferred for all renewable energysources.*

KEYWORDS-Variable speed DFIG, MPPT, windenergy, power quality, active filtering, GSC

I. INTRODUCTION

Now-a-days, the intake of traditional power belongings has elevated, So efforts had been made to generate power from renewable energy sources together with wind, sun and so on., Wind power has end up definitely one in every of the most crucial and promising property of renewable energy. This needs more transmission capability and better method of keeping gadget reliability. In recent times the wind power capability of the area is approximately 50gw and it's far anticipated to achieve 160GW through using 2012. In cutting-edge Wind Turbine generation system (WTGS), the wind mills are subjected to model of load and effect of sudden wind tempo versions. With expanded penetration of wind strength into electric powered grids, Doubly-Fed Induction Generator (DFIG) wind turbines are in large part deployed due to their variable pace characteristic and for that reason influencing gadget dynamics. This

has created an hobby in growing appropriate fashions for DFIG to be incorporated into power gadget research. The continuous style of having high penetration of wind power, in state-of-the-art years, has made it necessary to introduce new practices. Furthermore, so that it will model power virtual converters, in the high-quality state of affairs, it's miles assumed that the converters are exceptional and the DC-link voltage some of the converters is constant. Consequently, depending on the converter manipulate, a controllable voltage (modern) deliver may be carried out to symbolize the operation of the rotor-side of the converter within the version.

Within the literature, manasipattnaik, "have a have a look at of Doubly-Fed Induction Generator for variable pace wind energy Conversion structures", offers brief concept about the operation and working of DFIG.[1]. F. Poitiers, M. Machmoum, R. Le Doeuff and M.E. Zaim, "manage Of A Doubly-Fed Induction Generator For Wind energy conversion system", offers information about the modeling of the DFIG and the manipulate operation used.[2]. R. Pena, J.C Clare and G.M Asher (1996), "Doubly Fed Induction Generator the use of again-to-again PWM converter and its software to variable-velocity wind-strength technology", describes the rotor facet converter manipulate of dfig which offers the reference waveform for rotor facet converter and the pulses for RSC were received with this the real and reactive strength may be managed.[3].

T. Thiringer, A. Petersson, and T. Petru (2003), "grid disturbance reaction Of Wind Turbine organized With Induction Generator and Doubly-Fed induction generator", offers brief concept approximately the grid disturbance reaction to fixed velocity wind turbines and wind turbines with DFIG are provided.[4]. A. Petersson, L. Harnefors, and T. Thiringer (2005), "assessment OF contemporary

control methods For Wind mills the use of Doubly-Fed Induction device,” gives brief concept about the assessment of the stator-flux orientated modern-day manage of the DFIG.[5]. carlesbatlle, arnaud`oria-Cerezo ,Romeo Ortega (2006) , “a robustly stable PI Controller for The Doubly-Fed Induction gadget”, this paper offers the short concept about the closed loop of the device the use of the PI controller.

II. A NEW APPROACH FOR UPFC

These dfigs additionally provide correct damping performance for the weak grid. Unbiased control of active and reactive strength is finished with the aid of the usage of the decoupled vector control set of policies. This vector manipulate of such systems is generally found out in synchronously rotating reference frame oriented in each voltage axis or flux axis. In this art work, the manage of rotor aspect converter (rsc) is implemented in voltage-orientated reference body. Response of dfig-based wind electricity conversions system (wecs) to grid disturbance is in comparison to the fixed pace wecs. Generated power smoothing is achieved by way of the use of enforcing first-rate magnetic energy storage structures.

The other auxiliary offerings together with reactive power requirement and short stability limit are achieved by which encompass static compensator (statcom). A distribution statcom (dstatcom) coupled with fly-wheel energy storage machine is used at the windfarm for mitigating harmonics and frequency disturbances. A terrific capacitor power storage system at the dc hyperlink of unified strength splendid conditioner (upqc). Improving electricity wonderful and reliability. The harmonics compensation and reactive energy control are carried out with the assist of present rsc. An indirect contemporary control method is straightforward and shows better ordinary performance for doing away with harmonics as compared to direct modern-day manage.

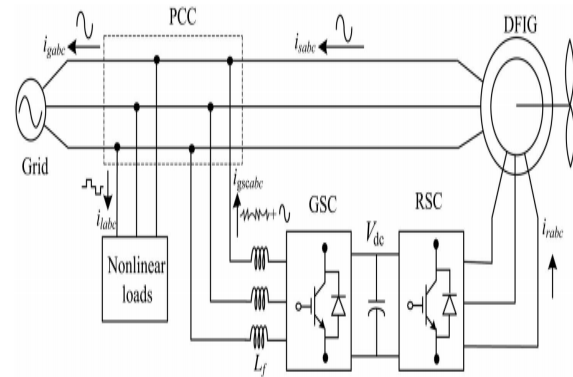


Fig. 1. Proposed system configuration

Working precept: on this painting, a new manage algorithm for gsc is proposed for compensating harmonics produced by nonlinear loads the use of an indirect modern-day control. Rsc is used for controlling the reactive power of dfig. The other principal benefit of proposed dfig is that it works as an active clear out even if the wind turbine is in shutdown condition. Therefore, it compensates load reactive strength and harmonics at wind turbine stalling case. Each simulation and experimental performances of the proposed incorporated energetic filter out-primarily based dfig are presented in this work. The dynamic overall performance of the proposed dfig is also tested for varying wind speeds and adjustments in unbalanced nonlinear loads at factor of common place coupling.

In fig.1 shows a schematic diagram of the proposed DFIG based WECS with integrated active filter capabilities. DFIG, the stator is directly connected to the grid as shown in Figure. Two back-to-back connected voltage source converters (VSCs) are placed between the rotor and the grid. Nonlinear loads are connected at PCC as shown in Fig. 1. The proposed DFIG works as an active filter in addition to the active power generation similar to normal DFIG. Harmonics generated by the nonlinear load connected at the PCC distort the PCC voltage.

RSC is controlled for achieving maximum power point tracking (MPPT) and also for making unity power factor at the stator side using voltage-

oriented reference frame. Synchronous reference frame (SRF) control method is used for extracting the fundamental component of load currents for the GSC control.

DESIGN OF DFIG-BASED WECS:

Selection of rankings of vscs and dc-hyperlink voltage is very plenty crucial for the a hit operation of wecs.

Choice of DC-link Voltage:The dc-hyperlink voltage of VSC must be greater than twice the peak of most phase voltage. While considering from the rotor aspect, the rotor voltage is slip times the stator voltage. So, the layout criteria for theselection of dc-link voltage may be done by considering handiest percent voltage. Even as thinking about from the GSC aspect, the percent line voltage (vab) is 230 V, as the system is hooked up in delta mode. consequently, the dc-link voltage is anticipated as

$$V_{dc} \geq \frac{\sqrt{2}}{\sqrt{3} * m} V_{ab}$$

where

Vab is the line voltage at the PCC.

Maximum modulation index is selected as 1 for linear range.

The value of dc-link voltage (Vdc) by (1) is estimated as 375 V.

Hence, it is selected as 375 V

Selection of VSC Rating: The DFIG draws a lagging volt-ampere reactive (VAR) for its excitation to build the rated air gap voltage. , the rating of the VSC used as RSC is rated as given as

$$S_{rated} = \sqrt{P_r^2 + Q_r^2}$$

Design of Interfacing Inductor: The design of interfacing inductors between GSC and PCC depends upon allowable GSC current limit (igscpp), dc-link voltage, and switching frequency of GSC. Maximum possible GSC line currents are used for the calculation. Maximum line current depends upon the maximum power and the line voltage at GSC. The maximum possible power in the GSC is the

slip power. Interfacing inductor between PCC and GSC is selected as 4 mH.

$$L_i = \frac{\sqrt{3} m v_{dc}}{12 a f_m \Delta i_{gsc}} = \frac{\sqrt{3} \times 1 \times 375}{12 \times 1.5 \times 10\,000 \times 0.25 \times 3.76} = 3.8\text{mH}$$

CONTROL STRATEGY:

Control algorithms for both GSC and RSC are presented in this section. The control algorithm for emulating wind turbine characteristics using dc machine and Type A chopper is also shown in Fig. 2.

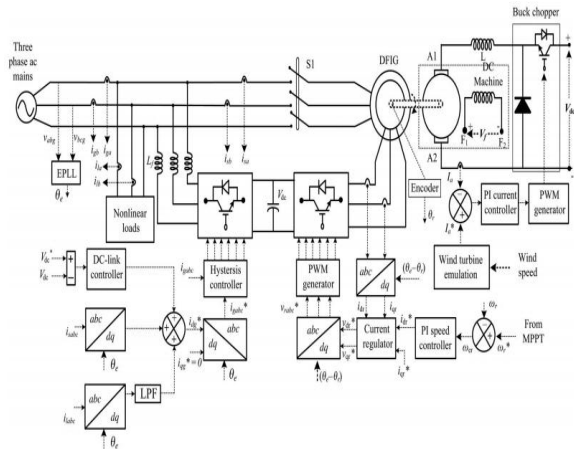


Fig. 2. Control algorithm of the proposed WECS.

Control of RSC:The main purpose of RSC is to extract maximum power with independent control of active and reactive powers. Here, the RSC is controlled in an orientation reference frame., the active and reactive powers are controlled by controlling direct and quadrature axis rotor currents (idr and iqr).

$$i_{dr}^*(k) = i_{dr}^*(k-1) + k_{pd} \{ \omega_{er}(k) - \omega_{er}(k-1) \} + k_{id} \omega_{er}(k)$$

Where:

The speed error (ω_{er}) is obtained by subtracting sensed speed (ω_r) from the reference speed (ω_r^{*}).

k_{pd} and k_{id} are the proportional and integral constants of the speed controller.

$\omega_{er}(k)$ and $\omega_{er}(k - 1)$ are the speed errors at k th and $(k-1)$ th instants.

$i^*_{dr}(k)$ and $i^*_{dr}(k - 1)$ are the direct axis rotor reference current at k th and $(k-1)$ th instants.

Reference rotor speed (ω^*_r).

In general, the quadrature axis reference rotor current (i^*_{qr}) is selected such that the stator reactive power (Q_s) is made zero. In this DFIG, quadrature axis reference rotor current (i^*_{qr}) is selected for injecting

the required reactive power. Inner current control loops are taken for control of actual direct and quadrature axis rotor currents (i_{dr} and i_{qr}) close to the direct and quadrature axis reference rotor currents (i^*_{dr} and i^*_{qr}). The rotor currents i_{dr} and i_{qr} are calculated from the sensed rotor currents (i_{ra} , i_{rb} , and i_{rc}).

Control of GSC:

The novelty of this work lies in the control of this GSC for mitigating the harmonics produced by the nonlinear loads. The control block diagram of GSC is shown in Fig. 2. Here, an indirect current control is applied on the grid currents for making them sinusoidal and balanced. Therefore, this GSC supplies the harmonics for making grid currents sinusoidal and balanced. These grid currents are calculated by subtracting the load currents from the summation of stator currents and GSC currents. Active power component of GSC current is obtained by processing the dc-link voltage error (v_{dce}) between reference and estimated dc-link voltage (V^*_{dc} and V_{dc}) through PI controller as

$$i^*_{gsc}(k) = i^*_{gsc}(k - 1) + k_{pdc} \{v_{dce}(k) - v_{dce}(k - 1)\} + k_{idc} v_{dce}(k)$$

Where k_{pdc} and k_{idc} are proportional and integral gains of dc-link voltage controller. $V_{dce}(k)$ and $V_{dce}(k - 1)$ are dc-link voltage errors at k th and $(k-1)$ th instants. $i^*_{gsc}(k)$ and $i^*_{gsc}(k - 1)$ are active

power component of GSC current at k th and $(k-1)$ th instants.

II. SIMULATION RESULTS

The DFIG machine modes of operation namely sub-synchronous generating, super-synchronous generating are simulated and the waveforms for speed and stator, rotor power and torque in each of the above modes of operation are presented. The rotor speed is controlled by using v/f control and grid-side reactive power & V_{dc} are controlled by using voltage oriented control techniques. The grid-side current is controlled by using reference current control techniques under p-q theory.

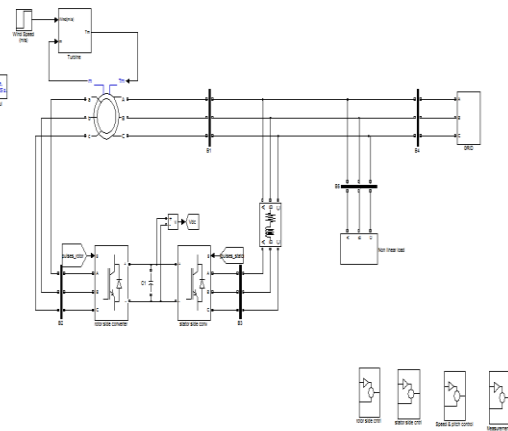
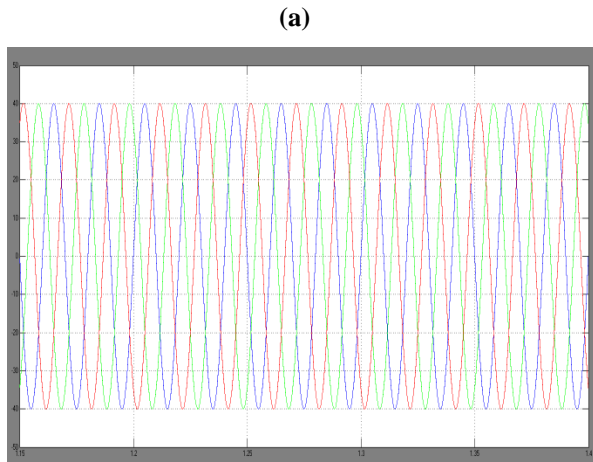


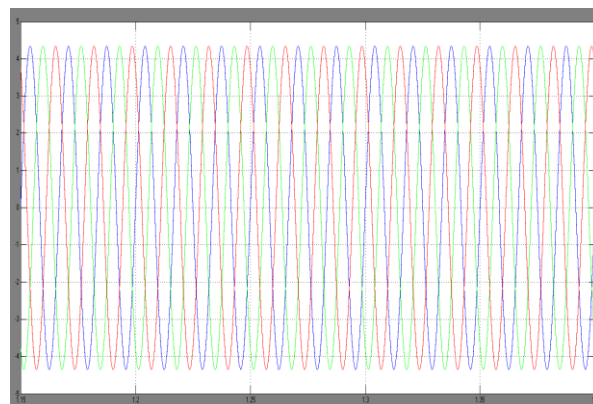
Fig 3 Matlab/simulink diagram of DFIG connected to WECS



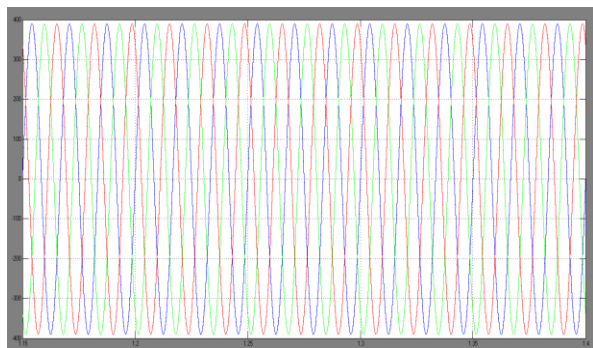


(a)

Fig 4 (a) Load current (Iabc1) (b) Load voltage (Vabc1)

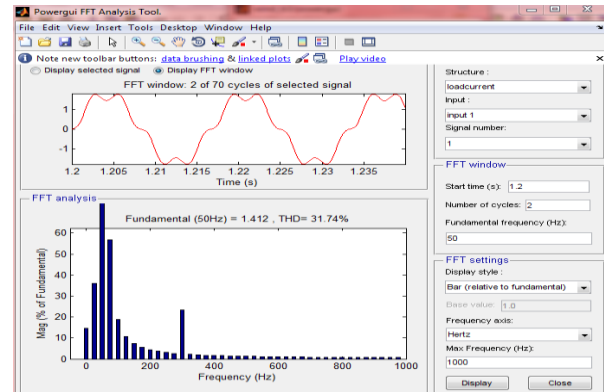
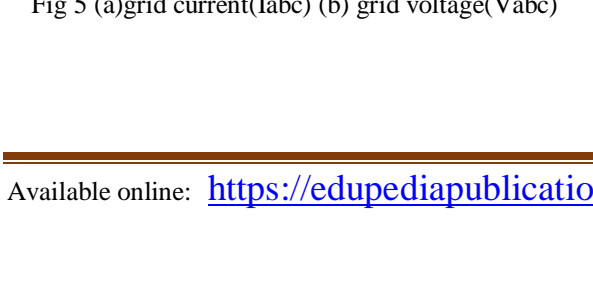


(b)

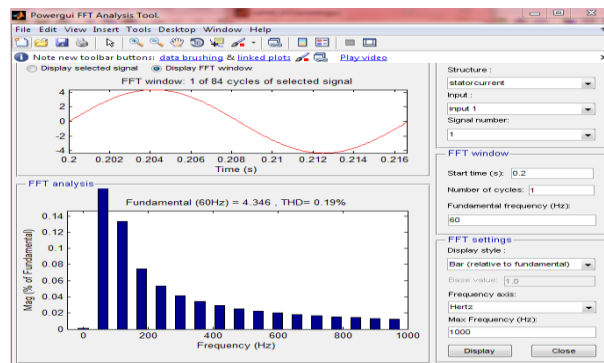


(a)

Fig 5 (a) grid current(Iabc) (b) grid voltage(Vabc)



(a)



(b)

Fig 6 FFT Analysis tool

III. CONCLUSION

Proposed dfig, thereactive electricity for the induction machine has been supplied from the rsc and therefore the load reactive energy has been stocked with from the gsc. Decoupled manage of both active and reactive powers has dispensed by rsc control. Dfig has additionally been tried at wind turbine installing condition for compensating harmonics and reactive electricity of neighborhood a whole lot. Projected dfig-based wecs with AN integrated spirited filter out has been simulated the usage of matlab/simulink surroundings, and the simulated results are verified with take a look at results of the developed epitome of this wecs.

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